# XuanTie-Openc910-UserManual

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# History

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## CHAPTER 1

Overview

This document describes open-source C910 (OpenC910), also referred to as C910, C910MP, and C910 core in this document.

## 1.1 Introduction

C910MP is a high-performance 64-bit multi-core CPU built on the RISC-V architecture. It is oriented to edge computing that requires high performance. For example, it can be applied to edge servers, edge computing cards, advanced machine vision, advanced video surveillance, self-driving, mobile smart terminals, and 5G base stations. C910MP adopts a homogeneous multi-core architecture and supports dual cores. Each C910 core runs on a microsystem architecture developed by Alibaba Cloud and is optimized for high performance. High-performance technologies are introduced, such as a superscalar architecture with a 3-to-8 line decoder and multi-channel data prefetch. In addition, the C910 core performs real-time detection and shuts down internal idle function modules to reduce dynamic power consumption of the CPU.

#### **1.2 Features**

#### 1.2.1 Architectural features of C910MP

- Homogeneous multi-core architecture and dual cores supported;
- Power-off for each core or the entire cluster supported;



- One AXI4 master interface and a 128-bit bus supported;
- Two levels of caches provided: L1 cache running on the Harvard architecture and L2 shared cache;
- L1 instruction/data cache size: 64 KB, with a cache line size of 64 bytes;
- The Modified, Exclusive, Shared, Invalid (MESI) cache coherence protocol supported for L1 cache, and the Modified, Owned, Exclusive, Shared, Invalid (MOESI) cache coherence protocol supported for L2 cache;
- L2 cache: a 16-way set-associative cache sized 1 MB and with a cache line size of 64 bytes;
- Core local interrupt (CLINT) controller and platform-level interrupt controller (PLIC) supported;
- Timers supported;
- Custom multi-core debug frameworks with RISC-V-compatible interfaces supported.

#### 1.2.2 Features of the C910 core

- RISC-V 64GC instruction set architecture;
- Little-endian mode supported;
- 9-stage to 12-stage pipelining architecture;
- Superscalar architecture with a 3-to-8 line decoder, fully transparent to software;
- In-order fetch, out-of-order issue, out-of-order completion, and in-order retirement;
- Two-level translation lookaside buffer (TLB) memory management units for virtual/physical address translation and memory management;
- I-Cache/D-Cache size: 64 KB, with a cache line size of 64 bytes;
- Instruction prefetch, and automatic detection and dynamic startup of hardware;
- Low-power access technology with I-Cache way prediction;
- Low-power execution technology with short-loop buffer;
- 64 KB two-level multi-way parallel branch predictor;
- Branch target buffer with 1024 entries;
- 12-layer hardware return address stack supported;
- Indirect branch predictor with 256 entries;
- Non-blocking issue and speculative execution;
- Renaming technology based on physical registers;
- 0-latency move instructions supported;
- Dual issue and full out-of-order execution for load/store instructions;

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- Concurrent bus access for up to 8 read requests and 8 write requests;
- Write combining supported;
- Strided 8-channel hardware prefetch supported;
- Half-precision, single-precision, and double-precision floating-point units supported.

## **1.3 Configurations**

C910MP adopts the following configurations:

- Number of cores: 2
- L1 I-Cache: 64KB
- L1 D-Cache: 64KB
- L2 Cache: 1MB
- Master Interface: AXI4
- Number of external interrupts: 144

## 1.4 XuanTie extended architecture

C910 is compatible with XuanTie C-series extended architecture 1.0, which provides extensions in the following aspects:

- Operation instructions: C910 improves operation capabilities with integer, floating-point, and load/store instructions, well supplementing the RISC-V base instruction sets.
- Cache operations: C910 enables you to easily maintain caches to improve cache efficiency.
- Memory model: C910 manages address attributes efficiently to improve memory access efficiency.
- Control registers: C910 extends the features of control registers based on the standard RISC-V architecture.
- Multi-core synchronization instructions: C910 adopts multi-core synchronization instructions to keep multi-core consistency.
- PLIC: C910 is integrated with a built-in PLIC.

## **1.5 Version compatibility**

C910 is compatible with the following RISC-V standard versions:

• The RISC-V Instruction Set Manual, Volume I: RISC-V User-Level ISA, Version 2.2.

#### Chapter 1. Overview



- The RISC-V Instruction Set Manual, Volume II: Privileged Architecture, Version 1.10.
- The mountinhibit register in the RISC-V Instruction Set Manual, Volume II: Privileged Architecture, Version 20190125-Public-Review-draftis added to the performance monitoring unit (PMU).

## 1.6 Naming conventions

#### 1.6.1 Terms

- Logic 1The level value corresponding to the Boolean logic value TRUE.
- Logic 0The level value corresponding to the Boolean logic value FALSE.
- SetThe action of setting one or more bits to the level value corresponding to logic 1.
- Clear The action of setting one or more bits to the level value corresponding to logic 0.
- **Reserved bit**A bit reserved for feature extension. The value of a reserved bit is 0 unless otherwise specified.
- SignalAn electrical value used to transfer information based on its state or state transition.
- PinAn external electrical and physical connection. Multiple signals can connect to one pin.
- **Enable**The action of switching a discrete signal to a valid state:
  - Switch a valid low-level signal from a high level to a low level.
  - Switch a valid high-level signal from a low level to a high level.
- **Disable**The action of switching the state of an enabled signal:
- Switch a valid low-level signal from a low level to a high level.
- Switch a valid high-level signal from a high level to a low level.
- ${\bf LSB}{\rm The}$  least significant bit.  ${\bf MSB}{\rm :}$  The most significant bit.
- Signal, bit field, and control bit: Expressed based on a general rule.
- Identifier followed by a value range: Indicates a group of signals from the most significant bit to the least significant bit.

For example, addr[4:0] indicates a group of address buses, where addr[4] indicates the most significant bit, and addr[0] indicates the least significant bit.

• Single identifier: Indicates a single signal.

For example, pad\_cpu\_rst\_b indicates a single signal.

In some cases, an identifier followed by a number is used to express a specific meaning. For example, addr15 indicates the 16th bit of a group of buses.

## CHAPTER 2

#### C910MP Overview

#### 2.1 Structure

The structure of C910MP is shown in Fig. 2.1 .

#### 2.2 In-core subsystems

C910 consists of the following in-core subsystems: instruction fetch unit (IFU), instruction decoding unit (IDU), integer unit (IU), floating-point unit (FPU), load/store unit (LSU), retirement unit (RTU), memory management unit (MMU), and physical memory protection (PMP) unit.

#### 2.2.1 IFU

The IFU can fetch and parallel process up to eight instructions at a time. It improves access efficiency with a variety of technologies, for example, I-Cache way prediction, instruction registers, loop acceleration buffers, and direct/indirect branch prediction. The IFU features low power consumption, high branch prediction accuracy, and high prefetch efficiency.

#### 2.2.2 IDU

The IDU can decode up to three instructions and detect data correlation at a time. The IDU detects data correlation between instructions by using the physical register renaming technology, and sends the



Fig. 2.1: C910MP structure



instructions out of order to the next-level pipeline for execution. The IDU supports out-of-order scheduling and distribution of instructions. It speculatively issues instructions to mitigate performance loss caused by data correlation.

#### 2.2.3 Execution units

Execution units include IUs and FPUs.

IUs include the arithmetic logic unit (ALU), multiplication (MULT) unit, division (DIV) unit, and branch/jump unit (BJU). The ALU performs 64-bit integer operations. The MULT unit supports  $16 \times 16$ ,  $32 \times 32$ , and  $64 \times 64$  integer multiplication. The DIV unit is designed based on the radix-16 SRT algorithm. Its execution cycle varies with operands. The BJU can correct branch prediction errors within one cycle.

FPUs include the floating-point arithmetic logic unit (FALU), floating-point fused multiply-add unit (FMAU), and floating-point divide and square root unit (FDSU). FPUs support half-precision, single-precision, and double-precision operations. The FALU performs addition, subtraction, comparison, conversion, register data transmission, sign-injection, and classification operations. The FMAU performs common multiply and fused multiply-add operations. The FDSU performs floating-point divide and square root operations.

#### 2.2.4 LSU

The LSU supports dual issue for scalar store/load instructions, single issue for vector store/load instructions, and full out-of-order execution for all store/load instructions. The LSU supports non-blocking access to caches. It supports byte, halfword, word, doubleword, and quadword store/load instructions, and supports sign/zero extension for byte and halfword load instructions. Store/load instructions can be executed in a pipeline so that only one data entry is accessed per cycle. The LSU supports 8-channel hardware prefetch. It can transfer data to the L1 D-Cache in advance. If the D-Cache is absent, the LSU supports parallel bus access.

#### 2.2.5 RTU

The RTU consists of a re-order buffer and a physical register stack. The re-order buffer controls out-of-order recycling and in-order retirement of instructions. The physical register stack controls out-of-order recycling and transfer of results. The RTU improves the instruction retirement efficiency through parallel recycling and fast retirement of instructions. The RTU supports parallel retirement of up to three instructions per clock cycle and implements precise exceptions.

#### 2.2.6 MMU

The MMU translates 39-bit virtual addresses to 40-bit physical addresses in compliance with the RISC-V SV39 standard. The MMU of C910 provides extended software writeback methods and address attributes



based on the hardware writeback criteria defined in SV39.

For more information, see Memory Model.

#### 2.2.7 PMP

The PMP unit complies with the RISC-V standard and supports 8 entries, but does not support the NA4 mode. The minimum granularity supported by the PMP unit is 4 KB.

For more information, see Memory Model.

### 2.3 Multi-core subsystems

C910 consists of the following multi-core subsystems: consistency interface unit (CIU), L2 cache, master device interface unit, platform-level interrupt controller (PLIC), timer, and custom multi-core single-port debug framework.

#### 2.3.1 CIU

The CIU ensures data coherence between L1 D-Caches based on the MESI protocol. Two listening buffers are configured to parallel handle multiple listening requests, to fully utilize the listening bandwidth. The CIU adopts an efficient data bypassing mechanism. When a listening request hits an L1 D-Cache under listening, data is directly bypassed to the request initiation core. In addition, the CIU supports broadcasting of invalid TLB/I-Cache requests. This reduces the software costs of maintaining data coherence between TLB/I-Cache and D-Cache.

#### 2.3.2 L2 cache

The L2 cache is tightly coupled to the CIU for synchronous access with L1 D-Caches. The L2 cache adopts a block-based pipelining architecture and can parallel handle two access requests within one cycle. It supports a maximum access bandwidth of 1024 bps. The operating frequency of the L2 cache is the same as that of C910. The tag and data RAM access latency can be configured by using software.

#### 2.3.3 Master device interface unit

The master device interface unit supports the AXI4 protocol and address access by keyword priority, and can work under different system clock to CPU clock ratios, for example, 1:1, 1:2, 1:3, 1:4, 1:5, 1:6, 1:7, and 1:8.



#### 2.3.4 PLIC

The PLIC controls sampling and distribution of 144 external interrupt sources. It supports level and pulse interrupts. You can set 32 interrupt priorities.

For more information, see Interrupt Controllers .

#### 2.3.5 Timer

The multi-core system provides one shared 64-bit system timer. Each core has a private timer comparison value register. Values of the system timer are collected and compared with those in the private timer comparison value register to generate timer signals.

For more information, see Interrupt Controllers .

### 2.4 Interface overview

C910 provides the following interfaces by feature: clock reset signal, bus system, interrupt system, debug system, low power system, DFT system, and CPU running monitoring signal. For more information, see Fig. 2.2.



Fig. 2.2: C910MP interfaces

## chapter 3

### Instruction Sets

This section describes the instruction sets implemented in C910: RV base instruction sets and XuanTie extended instruction sets.

## 3.1 RV base instruction sets

#### 3.1.1 Integer instruction set (RV64I)

The integer instruction set includes instructions of the following types by feature:

- Add/Subtract instructions
- Logical operation instructions
- Shift instructions
- Compare instructions
- Data transmission instructions
- Branch and jump instructions
- Memory access instructions
- Control register operation instructions
- Low power instructions
- Exception-return instructions



• Special functional instructions

Instruction	Description	Execution latency
Add/Subtract instructions		
ADD	A signed add instruction	1
ADDW	A signed add instruction that op-	1
	erates on the lower 32 bits	
ADDI	A signed add immediate instruc-	1
	tion	
ADDIW	A signed add immediate instruc-	1
	tion that operates on the lower 32	
	bits	
SUB	A signed subtract instruction	1
SUBW	A signed subtract instruction	1
	that operates on the lower 32 bits	
Logic operation instructions		
AND	A bitwise AND instruction.	1
ANDI	An immediate bitwise AND in-	1
	struction	
OR	A bitwise OR instruction	1
ORI	An immediate bitwise OR in-	1
	struction	
XOR	A bitwise XOR instruction.	1
XORI	An immediate bitwise XOR in-	1
	struction	
Shift instructions		
SLL	A logical left shift instruction	1
SLLW	A word logical left shift instruc-	1
	tion that operates on the lower 32	
	bits	
SLLI	An immediate logical left shift in-	1
	struction	
SLLIW	An immediate logical left shift	1
	instruction that operates on the	
	lower 32 bits	
SRL	A logical right shift instruction	1
SRLW	A logical right shift instruction	1
	that operates on the lower 32 bits	

Table 3.1: RV64I instructions

Continued on next page



Instruction	Description	Execution latency
SRLI	An immediate logical right shift	1
	instruction	
SRLIW	An immediate logical right shift	1
	instruction that operates on the	
	lower 32 bits	
SRA	An arithmetic right shift instruc-	1
	tion	
SRAW	An arithmetic right shift instruc-	1
	tion that operates on the lower 32	
	bits	
SRAI	An immediate arithmetic right	1
	shift instruction	
SRAIW	An immediate arithmetic right	1
	shift instruction that operates on	
	the lower 32 bits	
Compare instructions		
SLT	A signed set-if-less-than instruc-	1
	tion	
SLTU	An unsigned set-if-less-than in-	1
	struction	
SLTI	A signed set-if -less-than-	1
	immediate instruction	
SLTIU	An unsigned set-if -less-than-	1
	immediate instruction	
Data transmission instruc-		
tions		
LUI	A load upper immediate instruc-	1
	tion	
AUIPC	An add upper immediate to PC	1
	instruction	
Branch and jump instruc-		
tions		
BEQ	A branch-if-equal instruction	1
BNE	A branch-if-not-equal instruction	1
BLT	A signed branch-if-less-than in-	1
	struction	
BGE	A signed branch-if-g reater-than-	1
	or-equal instruction	

Table 3.1 – continued from previous pa	ige
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Instruction	Description	Execution latency
BLTU	An unsigned branch-if-less-than	1
	instruction	
BGEU	An unsigned branch-if-g reater-	1
	than-or-equal instruction	
JAL	An instruction for directly jump-	1
	ing to a subroutine	
JALR	An instruction for jumping to a	1
	subroutine by using an address in	
	a register	
Memory access instructions		
LB	A sign-extended byte load in-	WEAK ORDER LOAD: $>=3$
	struction	STORE: 1 STRONG ORDER
		Aperiodic
LBU	An unsign-extended byte load in-	Same as above
	struction	
LH	A sign-extended halfword load in-	Same as above
	struction	
LHU	An unsign-extended halfword	Same as above
	load instruction	
LW	A sign-extended word load in-	Same as above
	struction	
LWU	An unsign-extended word load	Same as above
	instruction	
LD	A doubleword load instruction	Same as above
SB	A byte store instruction	Same as above
SH	A halfword store instruction	Same as above
SW	A word store instruction	Same as above
SD	A doubleword store instruction	Same as above
Control register operation in-		
structions		
CSRRW	A move instruction that	Blocked
	reads/writes control registers	Aperiodic
CSRRS	A move instruction for setting	Same as above
	control registers	
CSRRC	A move instruction that clears	Same as above
	control register	

Table	3.1 -	<ul> <li>continued</li> </ul>	from	previous	page
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Continued on next page



Instruction	Description	Execution latency
CSRRWI	A move instruction that	Same as above
	reads/writes immediates in	
	control registers	
CSRRSI	A move instruction for setting	Same as above
	immediates in control registers	
CSRRCI	A move instruction that clears	Same as above
	immediates in control registers	
Low power instructions		
WFI	An instruction for entering the	Aperiodic
	low-power standby mode	
Exception-return instructions		
MRET	An instruction for returning from	Block
	exceptions in machine mode (M-	
	mode)	
SRET	An instruction for returning from	Same as above
	exceptions in supervisor mode (S-	
	mode)	
Special functional instructions		
FENCE	A memory synchronization in-	Aperiodic
	struction	
FENCE.I	An instruction stream synchro-	Blocked
	nization instruction	
SFENCE.VMA	A virtual memory synchroniza-	Same as above
	tion instruction	
EBREAK	A breakpoint instruction	1
ECALL	An environment call instruction	1

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For more information, see Appendix A-1 I instructions .

## 3.1.2 Multiply/Divide instruction set (RV64M)

For more information, see Appendix A-2 M instructions .





## 3.1.3 Atomic instruction set (RV64A)

LR.WA word load-reserved instruction.This instruction is split into multiple atomic instructions for execution. This instruction can be split into atomic instructions for blocked execution, but la- tency is not allowed.LR.DA doubleword load-reserved instruction.SC.WSC.WA word store-conditional instruction.SC.DSC.DA doubleword store-conditional instruction.SC.WA doubleword store-conditional instruction.SC.DA doubleword store-conditional instruction.SC.DAMOSWAP.WAn atomic swap instruction that operation.AMOSWAP.DAn atomic add instruction.AMOSWAP.DAn atomic add instruction that operates on the lower 32 bits.AMOADD.WAn atomic add instruction.AMOXOR.WAn atomic bitwise XOR instruction that operates on the lower 32 bits.AMOAND.WAn atomic bitwise XOR instruction.AMOAND.WAn atomic bitwise AND instruction.AMOAND.WAn atomic bitwise AND instruction that operates on the lower 32 bits.AMOOR.DAn atomic bitwise OR instruction that operates on the lower 32 bits.AMOOR.DAn atomic bitwise OR instruction that operates on the lower 32 bits.AMOOR.DAn atomic bitwise OR instruction that operates on the lower 32 bits.AMOOR.DAn atomic bitwise OR instruction that operates on the lower 32 bits.AMOOR.DAn atomic bitwise OR instruction that operates on the lower 32 bits.AMOOR.DAn atomic signed MIN instructionAMOMIN.DAn atomic signed MIN instruction that operates on the lower 32 bits.<	Instruction	Description	Execution latency
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#### Table 3.2: RV64A instructions

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#### Chapter 3. Instruction Sets



For more information, see Appendix A-3 A instructions.

### 3.1.4 Single-precision floating-point instruction set (RV64F)

A single-precision floating-point instruction set includes instructions of the following types by feature:

- Operation instructions
- Sign injection instructions
- Data transmission instructions
- Compare instructions
- Data type conversion instructions
- Memory store instructions
- Floating-point classify instructions

Instruction	Description	Latency
Operation instruction		
FADD.S	A single-precision floating-point	3
	add instruction.	
FSUB.S	A single-precision floating-point	3
	subtract instruction.	
FMUL.S	A single-precision floating-point	4
	multiply instruction	
FMADD.S	A single-precision floating-point	5
	multiply-add instruction.	
FMSUB.S	A single-precision floating-point	5
	multiply-subtract instruction.	
FNMADD.S	A single-precision floating-point	5
	n egate-(multiply-add) instruc-	
	tion.	
FNMSUB.S	A single-precision floating-point	5
	negate -(multiply-subtract) in-	
	struction.	
FDIV.S	A single-precision floating-point	4-10
	divide instruction.	
FSQRT.S	A single-precision floating-point	4-10
	square-root instruction.	
Sign injection instructions		

#### Table 3.3: RV64F instructions :name: RVF\_table



Instruction	Description	Latency
FSGNJ.S	A single-precision floating-point	3
	sign-injection instruction.	
FSGNJN.S	A single-precision floating-point	3
	negate sign-injection instruction.	
FSGNJX.S	A single-precision floating-point	3
	sign-injection XOR instruction.	
Data transmission instruc-		
tions		
FMV.X.W	A single-precision floating-point	1+1 in split execution
	read move instruction	
FMV.W.X	A single-precision floating-point	1+1 in split execution
	write move instruction.	
Compare instructions		
FMIN.S	A single-precision floating-point	3
	MIN instruction.	
FMAX.S	A single-precision floating-point	3
	MAX instruction.	
FEQ.S	A single-precision floating-point	3+1 in split execution
	compare equal instruction.	
FLT.S	A single-precision floating-point	3+1 in split execution
	compare less than instruction.	
FLE.S	A single-precision floating-point	3+1 in split execution
	compare less than or equal to in-	
	struction.	
Data type conversion in-		
structions		
FCVT.W.S	An instruction that converts	3+1 in split execution
	a single-precision floating-point	
	number into a signed integer.	
FCVT.WU.S	An instruction that converts	3+1 in split execution
	a single-precision floating-point	
	number into an unsigned integer.	
FCVT.S.W	An instruction that converts a	3+1 in split execution
	signed integer into a single-	
	precision floating-point number.	
FCVT.S.WU	An instruction that converts an	3+1 in split execution
	unsigned integer into a single-	
	precision floating-point number.	

Table 3.3 – continued from previous page	Table	3.3 – continued	from	previous page
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Instruction	Description	Latency
FCVT.L.S	An instruction that converts	3+1 in split execution
	a single-precision floating-point	
	number into a signed long inte-	
	ger.	
FCVT.LU.S	An instruction that converts	3+1 in split execution
	a single-precision floating-point	
	number into an unsigned long in-	
	teger.	
FCVT.S.L	An instruction that converts a	1+3 in split execution
	signed long integer into a single-	
	precision floating-point number.	
FCVT.S.LU	An instruction that converts	1+3 in split execution
	an unsigned long integer into	
	a single-precision floating-point	
	number.	
Memory store instruction		
FLW	A single-precision floating-point	WEAK ORDER LOAD: $>=3$
	load instruction.	STORE: 1 STRONG ORDER
		Aperiodic
FSW	A single-precision floating-point	Same as above
	store instruction.	
Floating-point classify instruc-		
tions		
FCLASS.S	A single-precision floating-point	1+1
	classify instruction.	

Table	3.3 –	continued	from	previous	page
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For more information, see Appendix A-4 F instructions .

### 3.1.5 Double-precision floating-point instruction set (RV64D)

A double-precision floating-point instruction set includes instructions of the following types by feature:

- Operation instructions
- Sign injection instructions
- Data transmission instructions
- Compare instructions
- Data type conversion instructions
- Memory store instructions



Instruction	Description	Latency
Operation instruction		
FADD.D	A double-precision floating-point	3
	add instruction	
FSUB.D	A double-precision floating-point	3
	subtract instruction.	
FMUL.D	A double-precision floating-point	4
	multiply instruction.	
FMADD.D	A double-precision floating-point	5
	multiply-add instruction.	
FMSUB.D	A double-precision floating-point	5
	multiply-subtract instruction	
FNMSUB.D	A double-precision floating-point	5
	n egate-(multiply-add) instruc-	
	tion	
FNMADD.D	A double-precision floating-point	5
	negate -(multiply-subtract) in-	
	struction.	
FDIV.D	A double-precision floating-point	4-17
	divide instruction.	
FSQRT.D	A double-precision floating-point	4-17
	square-root instruction.	
Sign injection instruction		
FSGNJ.D	A double-precision floating-point	3
	sign-injection instruction.	
FSGNJN.D	A double-precision floating-point	3
	negate sign-injection instruction.	
FSGNJX.D	A double-precision floating-point	3
	sign-injection XOR instruction.	
Data transmission instruc-		
tions		
FMV.X.D	A double-precision floating-point	1+1
	read move instruction.	
FMV.D.X	A double-precision floating-point	1+1
	write move instruction.	
Compare instructions		

Table 3.4:	RV64D	instructions
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Instruction	Description	Latency
FMIN.D	A double-precision floating-point	3
	instruction for extracting the	
	minimum value	
FMAX.D	A double-precision floating-point	3
	instruction for extracting the	
	maximum value.	
FEQ.D	A double-precision floating-point	3+1 in split execution
	compare instruction for deter-	
	mining whether register values	
	are equal.	
FLT.D	A double-precision floating-point	3+1 in split execution
	compare instruction for deter-	
	mining whether a register value	
	is less than another.	
FLE.D	A double-precision floating-point	3+1 in split execution
	compare instruction for deter-	
	mining whether a register value	
	is less than or equal to another.	
Data type conversion in-		
structions		
FCVT.S.D	An instruction that converts	3
	a double-precision floating-point	
	number into a single-precision	
	floating-point number.	
FCVT.D.S	An instruction that converts	3
	a single-precision floating-point	
	number into a double-precision	
	floating-point number.	
FCVT.W.D	An instruction that converts	3+1 in split execution
	a double-precision floating-point	
	number into a signed integer.	
FCVT.WU.D	An instruction that converts	3+1 in split execution
	a double-precision floating-point	
	number into an unsigned integer.	
FCVT.D.W	An instruction that converts a	3+1 in split execution
	signed integer into a double-	
	precision floating-point number.	

Table	3.4 –	continued	from	previous	page
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Instruction	Description	Latency
FCVT.D.WU	An instruction that converts an	3+1 in split execution
	unsigned integer into a double-	
	precision floating-point number.	
FCVT.L.D	An instruction that converts	3+1 in split execution
	a double-precision floating-point	
	number into a signed long inte-	
	ger.	
FCVT.LU.D	An instruction that converts	3+1 in split execution
	a double-precision floating-point	
	number into an unsigned long in-	
	teger.	
FCVT.D.L	An instruction that converts a	3+1 in split execution
	signed long integer into a double-	
	precision floating-point number.	
FCVT.D.LU	An instruction that converts	3+1 in split execution
	an unsigned long integer into	
	a double-precision floating-point	
	number.	
Memory store instructions		
FLD	A double-precision floating-point	Weak order
	load instruction.	LOAD: >=3
		STORE: 1
		STRONG ORDER
		Aperiodic
FSD	A double-precision floating-point	Same as above
	store instructio	
Floating-point classify in-		
structions		
FCLASS.D	A double-precision floating-point	1+1
	classify instruction	

Table 3.4 – continued from previous page

For more information, see Appendix A-5 D instructions.

### 3.1.6 Compressed instruction set (RV64C)

The compressed instruction set includes instructions of the following types by feature:

- Add/Subtract instructions
- Logical operation instructions

### Chapter 3. Instruction Sets



- Shift instructions
- Data transmission instructions
- Branch and jump instructions
- Immediate offset access instructions

Instruction	Description	Latency
Add/Subtract instructions		
C.ADD	A signed add instruction	1
C.ADDW	A signed add instruction that op-	1
	erates on the lower 32 bits.	
C.ADDI	A signed add immediate instruc-	1
	tion.	
C.ADDIW	A signed add immediate instruc-	1
	tion that operates on the lower 32	
	bits.	
C.SUB	A compressed signed subtract in-	1
	struction.	
C.SUBW	A signed subtract instruction	1
	that operates on the lower 32 bits	
C.ADDI16SP	An instruction that adds an im-	1
	mediate scaled by 16 to the stack	
	pointer.	
C.ADDI4SPN	An instruction that adds an im-	1
	mediate scaled by 4 to the stack	
	pointer	
Logic operation instructions		
C.AND	A bitwise AND instruction	1
C.ANDI	An immediate bitwise AND in-	1
	struction	
C.OR	A bitwise OR instruction	1
C.XOR	A bitwise XOR instruction	1
Shift instructions		
C.SLLI	An immediate logical left shift in-	1
	struction.	
C.SRLI	An immediate logical right shift	1
	instruction.	
C.SRAI	An immediate arithmetic right	1
	shift instruction.	

Table 3.5: RV64C instructions

#### Chapter 3. Instruction Sets



Table	3.5 - continued	from	previous page	
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Instruction	Description	Latency
C.FSD	A double-precision store instruc-	Same as above
	tion.	
C.FLDSP	A double-precision stack store in-	Same as above
	struction.	
C.FSDSP	A double-precision stack load in-	Same as above
	struction.	
Special instructions		
C.NOP	A no-operation instruction	1
C.EBREAK	A breakpoint instruction	1

Table 3.5 – continued from previous page

For more information, see Appendix A-6 C Instructions .

# 3.2 XuanTie extended instruction sets

C910 provides some extended custom instructions based on the RV64GC instruction sets. Extended halfprecision floating-point instructions of C910 can be directly used. All other extended instruction sets of C910 must be enabled before they can be used; otherwise, illegal instruction errors will occur. To enable an extended instruction set, enable the THEADISAEE bit in the MXSTATUS register.

# 3.2.1 Arithmetic operation instructions

Instruction	Description	Execution Latency
Add/Subtract in-		
structions		
ADDSL	An add register instruction that shifts registers	1
MULA	A multiply-add instruction	Additive numbers uncor-
		related: 4
MULS	A multiply-subtract instruction	Additive numbers uncor-
		related: 4
MULAW	A multiply-add instruction that operates on the	Additive numbers corre-
	lower 32 bits	lated: 1
MULSW	A multiply-subtract instruction that operates on	Additive numbers corre-
	the lower 32 bits.	lated: 1
MULAH	A multiply-add instruction that operates on the	Additive numbers corre-
	lower 16 bits	lated: 1
MULSH	A multiply-subtract instruction that operates on	Additive numbers corre-
	the lower 16 bits.	lated: 1
Shift instructions		
SRRI	A cyclic right shift instruction.	1
SRRIW	A cyclic right shift instruction that operates on the	1
	lower 32 bits.	
Move instructions		
MVEQZ	An instruction for moving values when the register	1
	value is 0	
MVNEZ	An instruction for moving values when the register	1
	value is not 0	

 Table 3.6:
 Arithmetic operation instructions

For more information, see Appendix B-3 Arithmetic operation instructions.





# 3.2.2 Bit operation instructions

Instruction	Description	Execution la-
		tency
Bit operation in-		
structions		
TST	An instruction for testing bits with the value of 0.	1
TSTNBZ	An instruction for testing bytes with the value of 0.	1
REV	An instruction for reversing the byte order.	1
REVW	An instruction for reversing the byte order in the lower 32	1
	bits.	
FF0	An instruction for fast finding the first bit with the value of	1
	0 in a register.	
FF1	An instruction for fast finding the first bit with the value of	1
	1 in a register.	
EXT	A signed extension instruction for extracting consecutive bits	1
	of a register.	
EXTU	A zero extension instruction for extracting consecutive bits of	1
	a register.	

 Table 3.7: Bit operation instructions

For more information, see Appendix B-4 Bitwise operation instructions.

### 3.2.3 Memory access instructions

Table 3.8:	Memory	access	$\operatorname{instructions}$
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Instruction	Description	Execution latency
FLRD	A doubleword load instruction	
	for shifting floating-point regis-	
	ters.	
FLRW	A word load instruction for shift-	
	ing floating-point registers.	
FLURD	A doubleword load instruction	
	for shifting the lower 32 bits in	
	floating-point registers.	
FLURW	A word load instruction for shift-	
	ing the lower 32 bits in floating-	
	point registers.	



Instruction	Description	Execution latency
LRB	A byte load instruction for	
	shifting registers and extending	
	signed bits.	
LRH	A halfword load instruction for	
	shifting registers and extending	
	signed bits	
LRW	A halfword load instruction for	
	shifting registers and extending	
	signed bits	
LRD	A doubleword load instruction	
	for shifting registers.	
LRBU	A byte load instruction for shift-	
	ing registers and extending zero	
	bits.	
LRHU	A halfword load instruction for	
	shifting registers and extending	
	zero bits.	
LRWU	A word load instruction for shift-	
	ing registers and extending zero	
	bits.	
LURB	A byte load instruction for	
	shifting registers and extending	
	signed bits.	
LURH	A halfword load instruction for	
	shifting registers and extending	
	signed bits.	
LURW	A word load instruction for shift-	
	ing the lower 32 bits in registers	
	and extending signed bits.	
LURD	A doubleword load instruction	
	for shifting the lower 32 bits in	
	floating-point registers.	
LURBU	A byte load instruction for shift-	
	ing the lower 32 bits in registers	
	and extending zero bits.	
LURHU	A halfword load instruction for	
	shifting the lower 32 bits in reg-	
	isters and extending zero bits.	

Table	3.8 -	continued	from	previous	page
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Instruction	Description	Execution latency
LURWU	A word load instruction for shift-	
	ing the lower 32 bits in registers	
	and extending zero bits.	
LBIA	A base-address auto-increment	This instruction is split into the
	instruction for loading bytes and	load and ALU instructions for ex-
	extending signed bits.	ecution.
LBIB	A byte load instruction for auto-	
	incrementing the base address	
	and extending signed bits.	
LHIA	A base-address auto-increment	
	instruction for loading halfwords	
	and extending signed bits.	
LHIB	A halfword load instruction for	
	auto-incrementing the base ad-	
	dress and extending signed bits.	
LWIA	A base-address auto-increment	
	instruction for loading words and	
	extending signed bits.	
LWIB	The word load instruction for	
	auto-incrementing the base ad-	
	dress and extending signed bits.	
LDIA	A base-address auto-increment	
	instruction for loading double-	
	words and extending signed bits.	
LDIB	A doubleword load instruction	
	for auto-incrementing the base	
	address and extending signed	
	bits.	
LBUIA	A base-address auto-increment	
	instruction for loading bytes and	
	extending zero bits.	
LBUIB	A byte load instruction for auto-	
	incrementing the base address	
	and extending zero bits.	
LHUIA	An address auto-increment in-	
	struction for loading halfwords	
	and extending zero bits.	

Table 3.8 – continued from previous page



Instruction	Description	Execution latency
LHUIB	A halfword load instruction for	
	auto-incrementing the base ad-	
	dress and extending zero bits	
LWUIA	An address auto-increment in-	
	struction for loading words and	
	extending zero bits.	
LWUIB	A word load instruction for auto-	
	incrementing the base address	
	and extending zero bits.	
LDD	A double-register load instruc-	This instruction is split into two
	tion.	load instructions for execution.
LWD	A double-register word load in-	
	struction for extending signed	
	bits.	
LWUD	A double-register word load in-	
	struction for extending zero bits.	
FSRD	A doubleword store instruction	Weak order
	for shifting floating-point regis-	LOAD: $>=3$
	ters.	STORE: 1
		STRONG ORDER
		Aperiodic
FSRW	A word store instruction for shift-	
	ing floating-point registers.	
FSURD	A doubleword store instruction	
	for shifting the lower 32 bits in	
	floating-point registers.	
FSURW	A word store instruction for shift-	
	ing the lower 32 bits in floating-	
	point registers.	
SRB	A byte store instruction for shift-	
	ing registers.	
SRW	A word store instruction for shift-	
	ing registers.	
SRD	A doubleword store instruction	
	for shifting registers.	
SURB	A byte store instruction for shift-	
	ing the lower 32 bits in registers.	

Table	3.8 -	continued	from	previous	page
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Instruction	Description	Execution latency
SURH	A halfword store instruction for	
	shifting the lower 32 bits in reg-	
	isters.	
SURW	A word store instruction for shift-	
	ing the lower 32 bits in registers.	
SURD	A doubleword store instruction	
	for shifting the lower 32 bits in	
	floating-point registers	
SBIA	A base-address auto-increment	This instruction is split into the
	instruction for storing bytes	store and ALU instructions for
		execution.
SBIB	A byte store instruction for auto-	
	incrementing the base address.	
SHIA	A base-address auto-increment	
	instruction for storing halfwords.	
SHIB	A halfword store instruction for	
	auto-incrementing the base ad-	
	dress.	
SWIA	A base-address auto-increment	
	instruction for storing words.	
SWIB	A word store instruction for auto-	
	incrementing the base address.	
SDIA	A base-address auto-increment	
	instruction for storing double-	
	words	
SDIB	A doubleword store instruction	
	for auto-incrementing the base	
	address.	
SDD	A double-register store instruc-	This instruction is split into two
	tion.	store instructions for execution.
SWD	An instruction for storing the	
	lower 32 bits in double registers	

Table 3.8 – continued from previous page

For more information, see Appendix B-5 Storage instructions.

## 3.2.4 Cache instructions

For more information, see Appendix B-1 Cache instructions.



### 3.2.5 Multi-core synchronization instructions

Table 3.9∙	Multi-core	synchronization	instructions
Table 0.5.	muni core	Synomization	monucuoms

Instruction	Description
SFENCE.VMAS	A broadcast instruction for synchronizing virtual memory.
SYNC	A synchronization instruction
SYNC.S	A synchronization broadcast instruction
SYNC.I	An instruction for synchronizing the clearing operation.
SYNC.IS	A broadcast instruction for synchronizing the clearing operation.

For more information, see Appendix B-2 Multi-core synchronization instructions.

# 3.2.6 Half-precision floating-point instructions

Instruction	Description	Execution latency
Operation instructions		
FADD.H	A half-precision floating-point	3
	add instruction.	
FSUB.H	A half-precision floating-point	3
	subtract instruction.	
FMUL.H	A half-precision floating-point	3
	multiply instruction.	
FMADD.H	A half-precision floating-point	4
	multiply-add instruction.	
FMSUB.H	A half-precision floating-point	4
	multiply-subtract instruction.	
FNMADD.H	A half-precision floating-point n	4
	egate-(multiply-add) instruction.	
FNMSUB.H	A half-precision floating-point	4
	negate -(multiply-subtract) in-	
	struction.	
FDIV.H	A half-precision floating-point di-	4-7
	vide instruction.	
FSQRT.H	A half-precision floating-point	4-7
	square-root instruction.	
Sign injection instructions		

Table 3.10: Half-precision floating-point instructions



Instruction	Description	Execution latency
FSGNJ.H	A half-precision floating-point	3
	sign-injection instruction	
FSGNJN.H	A half-precision floating-point	3
	negate sign-injection instruction	
FSGNJX.H	A half-precision floating-point	3
	XOR sign-injection instruction	
Data transmission instructions		
FMV.X.H	A half-precision floating-point	1+1
	read move instruction.	
FMV.H.X	A half-precision floating-point	1+1
	write move instruction	
Compare instructions		
FMIN.H	A half-precision floating-point	3
	MIN instruction	
FMAX.H	A half-precision floating-point	3
	MAX instruction.	
FEQ.H	A half-precision floating-point	3+1 in split execution
	compare equal instruction.	
FLT.H	A half-precision floating-point	3+1 in split execution
	compare less than instruction.	
FLE.H	A half-precision floating-point	3+1 in split execution
	compare less than or equal to in-	
	struction.	
Data type conversion in-		
structions		
FCVT.S.H	An instruction that converts	3
	a half-precision floating-point	
	number into a single-precision	
	floating-point number.	
FCVT.H.S	An instruction that converts	3
	a single-precision floating-point	
	number into a half-precision	
	floating-point number.	
FCVT.D.H	An instruction that converts	3
	a half-precision floating-point	
	number into a double-precision	
	floating-point number.	

Table 3.10 – continued from previous page



		, <b>o</b>
Instruction	Description	Execution latency
FCVT.H.D	An instruction that converts	3
	a double-precision floating-point	
	number into a half-precision	
	floating-point number.	
FCVT.W.H	An instruction that converts a	3+1 in split execution
	half-precision floating-point num-	
	ber into a signed integer.	
FCVT.WU.H	An instruction that converts a	3+1 in split execution
	half-precision floating-point num-	
	ber into an unsigned integer.	
FCVT.H.W	An instruction that converts	3+1 in split execution
	a signed integer into a half-	
	precision floating-point number	
FCVT.H.WU	The instruction that converts	3+1 in split execution
	an unsigned integer into a half-	
	precision floating-point number.	
FCVT.L.H	An instruction that converts a	3+1 in split execution
	half-precision floating-point num-	
	ber into a signed long integer.	
FCVT.LU.H	An instruction that converts a	3+1 in split execution
	half-precision floating-point num-	
	ber into an unsigned long integer.	
FCVT.H.L	An instruction that converts a	3+1 in split execution
	signed long integer into a half-	
	precision floating-point number.	
FCVT.H.LU	An instruction that converts an	3+1 in split execution
	unsigned long integer into a half-	
	precision floating-point number.	
Memory store instructions		
FLH	A half-precision floating-point	Weak order
	load instruction	LOAD: $>=3$
		STORE: 1
		STRONG ORDER
FSH	A half-precision floating-point	Same as above
	store instruction.	
Floating-point classify in-		
structions		

Table 3.10 – continued from previous page

### Chapter 3. Instruction Sets



Instruction	Description	Execution latency	
FCLASS.H	A single-precision floating-point	1+1	
	classify instruction		

Table 3.10 – continued from previous page
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For more information, see Appendix B-6 Half-precision floating-point instructions .

# CHAPTER 4

## CPU Modes and Registers

### 4.1 CPU modes

C910 supports three RISC-V \*\*privilege modes\*\*: machine mode (M-mode), supervisor mode (S-mode), and user mode (U-mode). C910 runs programs in M-mode after reset. The three modes correspond to different operation privileges and differ in the following aspects:

- 1. Register access
- 2. Use of privileged instructions
- 3. Memory access
- The U-mode provides the lowest privileges.

User programs are allowed to access only the registers specific to the U-mode. This prevents user programs from accessing privileged information. The operating system manages and serves user programs by coordinating their behaviors.

# • The S-mode provides higher privileges than the U-mode but lower privileges than the M-mode.

Programs running in S-mode are not allowed to access control registers specific to the M-mode and are limited by physical memory protection (PMP). The page-based virtual memory acts as the core of the S-mode.

• The M-mode has the highest privileges.

#### Chapter 4. CPU Modes and Registers



Programs running in M-mode have full access to memory, I/O resources, and underlying features required for starting and configuring the system. By default, the CPU switches to the M-mode to respond to exceptions and interrupts that occur in any mode unless the exceptions and interrupts are delegated.

Most instructions can run in all the three modes. However, some privileged instructions with major impact on the system are available only in S-mode or M-mode. For more information, see *Appendix A Standard Instructions* and *Appendix B T-Head Extended Instructions*.

The privilege mode in which an exception occurs is different from that in which the CPU responds to the exception. The CPU switches to a higher privilege mode to respond to the exception, and switches back to the lower privilege mode after the exception is handled.

# 4.2 Register view

The register view of C910 is shown in Fig. 4.1.



Fig. 4.1: Register view



# 4.3 General-purpose registers

C910 provides thirty-two 64-bit general-purpose registers that have the same features as those defined in RISC-V. For more information, see Table 4.1.

Register	ABI name	Description
x0	zero	A hardwired zero register.
x1	ra	A return address register.
x2	$\operatorname{sp}$	A stack pointer register.
x3	$_{\rm gp}$	A global pointer register.
x4	$\operatorname{tp}$	A thread pointer register.
x5	t0	A temporary/standby link register.
x6-7	t1-2	Temporary registers.
x8	s0/fp	A reserved register/frame pointer register.
x9	s1	A reserved register.
x10-11	a0-1	Function argument/Return value registers.
x12-17	a2-7	Function argument registers.
x18-27	s2-11	Reserved registers.
x28-31	t3-6	Temporary registers.

 Table 4.1: General-purpose registers

The general-purpose registers are used to sore instruction operands, instruction execution results, and address information.

# 4.4 Floating-point registers

In addition to standard RV64FD instructions, C910 also supports floating-point half-precision computing and provides 32 independent 64-bit floating-point registers. These registers are accessible in U-mode, S-mode, and M-mode.

Register	ABI name	Description
f0-7	ft0-7	Floating-point temporary registers.
f8-9	fs0-1	Floating-point reserved registers.
f10-11	fa0-1	Floating-point argument/return value registers.
f12-17	fa2-7	Floating-point argument registers.
f18-27	fs2-11	Floating-point reserved registers.
f28-31	ft8-11	Floating-point temporary registers.

Table 4.2: Floating-point registers

#### Chapter 4. CPU Modes and Registers

Unlike x0, f0 is not hardwired to 0, but its bit values are variable like other floating-point registers. A single-precision floating-point number occupies only the lower 32 bits of a 64-bit floating-point register, and the upper 32 bits must be set to 1; otherwise, the number will be considered nonnumeric. A half-precision floating-point number occupies only the lower 16 bits of a 64-bit floating-point register, and the upper 48 bits must be set to 1; otherwise, the number will be considered nonnumeric.

The independent floating-point registers help increase the register capacity and bandwidth, improving performance of the CPU. Along with the floating-point registers, floating-point load and store instructions and instructions for transferring data between floating-point and general-purpose registers are added.

### 4.4.1 Transmit data between floating-point and general-purpose registers

Data can be transmitted between floating-point and general-purpose registers through floating-point register move instructions. Floating-point register move instructions include:

- FMV.X.H/FMV.H.X: A half-precision data move instruction for floating-point registers.
- FMV.X.W/FMV.W.X: A single-precision data move instruction for floating-point registers.
- FMV.X.D/FMV.D.X: A double-precision data move instruction for floating-point registers.

When half-precision, single-precision, or double-precision data is transmitted from a general-purpose register to a floating-point register, the data format remains unchanged. Therefore, a program can directly use these registers without converting their types.

For more information, see Appendix A-4 F instructions.

### 4.4.2 Maintain consistency of register precision

Floating-point registers can store half-precision, single-precision, double-precision, and integer data. For example, the type of data stored in f1 depends on the last write operation, and may be any one of the four types.

Floating-point units (FPUs) do not detect data formats based on hardware. The hardware parses data formats in a floating-point register only based on the executed floating-point instruction, regardless of the data format in the last write operation in the register. In this case, the consistency of data precision in the register is ensured only by the compiler or program.

# 4.5 System control registers

### 4.5.1 Standard control registers

This section describes RISC-V standard control registers implemented in C910 by M-mode, S-mode, and U-mode.



The RISC-V standard M-mode control registers implemented in C910 are described in Table 4.3.

Register	Read/Write permission	ID	Description
M-mode infor-			
mation registers			
mvendorid	Read-only in M-mode	0xF11	A vendor ID regis-
			ter.
marchid	Read-only in M-mode	0xF12	An architecture ID
			register.
mimpid	Read-only in M-mode	0xF13	An M-mode hard-
			ware implementa-
			tion ID register.
mhartid	Read-only in M-mode	0xF14	An M-mode logical
			kernel ID register.
M-mode excep-			
tion configura-			
tion registers			
mstatus	Read/Write in M-mode	0x300	An M-mode CPU
			status register.
misa	Read/Write in M-mode	0x301	An M-mode CPU
			instruction set at-
			tribute register.
medeleg	Read/Write in M-mode	0x302	An M-mode ex-
			ception delegation
			control register.
mideleg	Read/Write in M-mode	0x303	An M-mode in-
			terrupt delegation
			control register.
mie	Read/Write in M-mode	0x304	An M-mode inter-
			rupt enable con-
			trol register.
mtvec	Read/Write in M-mode	0x305	An M-mode vector
			base address regis-
			ter.
mcounteren	Read/Write in M-mode	0x306	An M-mode
			counter enable
			control register.
mcountinhibit	Read/Write in M-mode	0x320	An M-mode count
			inhibit register.

Table 4.3: RISC-V standard M-mode control registers



Register	Read/Write permission	ID	Description
M-mode excep-			
tion handling			
registers			
mscratch	Read/Write in M-mode	0x340	An M-mode
			temporary data
			backup register
			upon exceptions.
mepc	Read/Write in M-mode	0x341	An M-mode ex-
			ception program
			counter.
mcause	Read/Write in M-mode	0x342	An M-mode excep-
			tion event cause
			register.
mtval	Read/Write in M-mode	0x343	An M-mode excep-
			tion event vector
			register.
mip	Read/Write in M-mode	0x344	An M-mode inter-
			rupt pending state
			register.
M-mode mem-			
ory protection			
registers			
pmpcfg0	Read/Write in M-mode	0x3A0	Physical memory
			protection configu-
			ration register 0.
pmpaddr0	Read/Write in M-mode	0x3B0	Physical memory
			protection base
			address register 0.
pmpaddr7	Read/Write in M-mode	0x3B7	Physical memory
			protection base
			address register 7.
M-mode c oun-			
ters/timers			
mcycle	Read/Write in M-mode	0xB00	An M-mode cycle
			counter.

Table	4.3 –	continued	from	previous	page
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Register	Read/Write permission	ID	Description
minstret	Read/Write in M-mode	0xB02	An M-mode re-
			tired instruction
			counter.
mhpmcounter3	Read/Write in M-mode	0xB03	Machine-mode
			counter 3.
mhpmcounter31	Read/Write in M-mode	0xB1F	M-mode counter
			31.
M-mode			
counter configu-			
ration registers			
mhpmevent3	Read/Write in M-mode	0x323	M-mode event se-
			lect register 3.
mhpmevent31	Read/Write in M-mode	0x33F	M-mode event se-
			lect register 31.

Table	4.3 – continued	from	previous page
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The RISC-V standard S-mode control registers implemented in C910 are described in Table 4.4.



Register	Read/Write permission	ID	Description
S-mode			
exception			
configura-			
tion registers			
sstatus	Read/Write in S-mode	0x100	An S-mode CPU sta-
			tus register.
sie	Read/Write in S-mode	0x104	An S-mode interrupt
			enable control regis-
			ter.
stvec	Read/Write in S-mode	0x105	An S-mode vector
			base address register.
scounteren	Read/Write in S-mode	0x106	An S-mode counter
			enable control regis-
			ter.
S-mode			
exception			
handling			
registers			
sscratch	Read/Write in S-mode	0x140	An S-mode tempo-
			rary data backup
			register upon excep-
			tions.
sepc	Read/Write in S-mode	0x141	An S-mode exception
			program counter.
scause	Read/Write in S-mode	0x142	An S-mode exception
			event cause register.
stval	Read/Write in S-mode	0x143	An S-mode exception
			event vector register.
sip	Read/Write in S-mode	0x144	An S-mode interrupt
			pending state regis-
			ter.
S-mode			
address			
translation			
registers			
satp	Read/Write in S-mode	0x180	An S-mode virtual
			address translation
			and protection regis-
			ter.

Table 4.4: RISC-V standard S-mode control registers



The RISC-V standard user-mode control registers implemented in C910 are described in Table 4.5.

Register	Read/Write permission	ID	Description
U-mode floating-			
point control regis-			
ters			
fflags	Read/Write in U-mode	0x001	A floating-point
			accrued exception sta-
			tus register.
frm	Read/Write in U-mode	0x002	A floating-point
			dynamic rounding mode
			control register.
fcsr	Read/Write in U-mode	0x003	A floating-point control
			and status register.
U-mode c oun-			
ters/timers			
cycle	Read/Write in U-mode	0xC00	A U-mode cycle
			counter.
time	Read/Write in U-mode	0xC01	A U-mode timer.
instret	Read/Write in U-mode	0xC02	A U-mode retired in-
			struction counter.
hpmcounter3	Read/Write in U-mode	0xC03	A U-mode counter 3.
hpmcounter31	Read/Write in U-mode	0xC1F	U-mode counter 31.

 Table 4.5: RISC-V standard U-mode control registers

## 4.5.2 Extended control registers

This section describes extended control registers implemented in C910 by M-mode, S-mode, and U-mode.

The extended M-mode control registers of C910 are described in Table 4.6.



Register	Read/Write permission	ID	Description
Extended M-mode			
CPU control and			
status registers			
mxstatus	Read/Write in M-mode	0x7C0	An extended M-mode status regis-
			ter.
mhcr	Read/Write in M-mode	0x7C1	An M-mode hardware configura-
			tion register.
mcor	Read/Write in M-mode	0x7C2	An M-mode hardware operation
			register.
mccr2	Read/Write in M-mode	0x7C3	An M-mode L2 cache control reg-
			ister.
mhint	Read/Write in M-mode	0x7C5	An M-mode implicit operation reg-
			ister.
mrvbr	Read-only in M-mode	0x7C7	An M-mode reset
			vector base address register.
mcounterwen	Read/Write in M-mode	0x7C9	An S-mode counter write enable
			register.
mcounterinten	Read/Write in M-mode	0x7CA	An M-mode event interrupt enable
			register.
mcounterof	Read/Write in M-mode	0x7CB	An M-mode overflow flag register.
Extended M-mode			
cache access regis-			
ters			
mcins	Read/Write in M-mode	0x7D2	An M-mode cache instruction reg-
			ister.
mcindex	Read/Write in M-mode	0x7D3	An M-mode cache access index reg-
			ister.
mcdata0	Read/Write in M-mode	0x7D4	An M-mode cache data register 0.
mcdata1	Read/Write in M-mode	0x7D5	An M-mode cache data register 1.
Extended M-mode			
CPU model registers			
mcpuid	Read-only in M-mode	0xFC0	An M-mode CPU model register.
mapbaddr	Read-only in M-mode	0xFC1	An on-chip bus base address regis-
			ter.
Extended multi-core			
registers			
msmpr	Read/Write in M-mode	0x7F3	A snooping enable register.

Table 4.6: Extended M-mode control registers of C910

#### Chapter 4. CPU Modes and Registers



For more information, see Appendix C-1 M-mode control registers.

The extended S-mode control registers of C910 are described in Table 4.7.

Register	Read/Write permission	ID	Description
Extended S-mode			
CPU control and			
status registers			
sxtatus	Read/Write in S-mode	0x5C0	An extended S-mode status register.
shcr	Read/Write in S-mode	0x5C1	An S-mode hardware control register.
scounterinten	Read/Write in S-mode	0x5C4	An S-mode event inter-
			rupt enable register.
scounterof	Read/Write in S-mode	0x5C5	An S-mode event over-
			flow flag register.
scycle	Read/Write in S-mode	0x5E0	An S-mode cycle
			counter.
shpmcounter31	Read/Write in S-mode	0x5FF	S-mode counter 31.
Extended S-mode			
MMU registers			
smir	Read/Write in S-mode	0x9C0	An S-mode MMU index
			register.
smel	Read/Write in S-mode	0x9C1	An S-mode MMU En-
			tryLo register.
smeh	Read/Write in S-mode	0x9C2	An S-mode MMU En-
			tryHi register.
smcir	Read/Write in S-mode	0x9C3	An S-mode MMU con-
			trol register.

Table 4.7:	Extended	S-mode	control	registers	of	C910
10010 1.1.	LAtonaca	5 moue	00110101	regipterp	or	0010

For more information, see Appendix C-2 S-mode control registers.

The extended U-mode control registers of C910 are described in Table 4.8.



Register	Read/Write permission	ID	Description
Extended U-mode			
floating-point con-			
trol registers			
fxcr	Read/Write in U-mode	0x800	An extended
			U-mode
			floating-point control
			register.

Table 4.8: Extended U-mode control registers of C910

For more information, see Appendix C-3 U-mode control registers.

# 4.6 Data formats

### 4.6.1 Integer data format

Values in a register are not distinguished by big-endian or little-endian type, but by signed or unsigned type. Values in a register are arranged from right to left with the least significant bit being the rightmost bit and the most significant bit being the leftmost bit, as shown in Fig. 4.2.



Fig. 4.2: Integer data structure in registers

### 4.6.2 Floating-point data format

FPUs of C910 comply with the RISC-V standard and the ANSI/IEEE 754-2008 standard for floating-point arithmetic, and support half-precision, single-precision, and double-precision computation. The floating-point data format is shown in Fig. 4.3. Single-precision data occupies only the lower 32 bits of a 64-bit



#### Chapter 4. CPU Modes and Registers

floating-point register, and the upper 32 bits must be set to 1; otherwise, the data will be considered nonnumeric. Half-precision data occupies only the lower 16 bits of a 64-bit floating-point register, and the upper 48 bits must be set to 1; otherwise, the data will be considered nonnumeric.



Fig. 4.3: Floating-point data structure in registers

# 4.7 Big-endian and little-endian

The concepts of big-endian and little-endian are proposed with respect to the data storage formats of memories. In the big-endian scheme, the most significant byte of an address is stored to the lower bits in physical memory. In the little-endian scheme, the most significant byte of an address is stored to the upper bits in physical memory. The data formats are shown in Fig. 4.4.

C910 supports only the little-endian scheme, and supports binary integers with standard complements. The length of each instruction operand can be explicitly encoded in programs (load/store instructions) or implicitly indicated in instruction operations (index operation and byte extraction) Usually, an instruction receives a 64-bit operand and generates a 64-bit result.

• 平头哥

A+7	A+6	A+5	A+4	A+3	A+2	A+1	А	
Byte 7	Byte6	Byte 5	Byte4	Byte 3	Byte2	Byte1	Byte0	Double word at A
Byte7	Byte 6	Byte 5	Byte4	Byte 3	Byte2	Byte1	Byte0	Word at A
Byte7	Byte 6	Byte 5	Byte4	Byte 3	Byte 2	Byte1	Byte0	Half word at A
Byte7	Byte6	Byte 5	Byte4	Byte3	Byte2	Byte1	Byte0	Byte at A

a) Small end mode

	A+3	A+2	A+1	A	A+7	A+6	A+5	A+4
Double word a	Byte4	Byte 5	Byte6	Byte7	Byte0	Byte 1	Byte 2	Byte 3
Word at A	Byte0	Byte 1	Byte2	Byte3	Byte7	Byte6	Byte 5	Byte4
Half word at A	Byte 2	Byte 3	Byte0	Byte 1	Byte5	Byte4	Byte7	Byte 6
Byte at A	Byte 3	Byte 2	Byte1	Byte0	Byte4	Byte 5	Byte 6	Byte 7

# b) Big end V1 mode

	А	A+1	A+2	A+3	A+4	A+5	A+6	A+7
Double word at A	Byte7	Byte6	Byte5	Byte4	Byte3	Byte2	Byte 1	Byte0
Word at A	Byte 3	Byte2	Byte1	Byte0	Byte7	Byte6	Byte 5	Byte4
Half word at A	Byte 1	Byte0	Byte3	Byte2	Byte 5	Byte4	Byte7	Byte 6
Byte at A	Byte0	Byte 1	Byte2	Byte3	Byte4	Byte 5	Byte 6	Byte7

c) Big end V2 mode

Fig. 4.4: Data structure in memory

# CHAPTER 5

### Exceptions and Interrupts

### 5.1 Overview

Exception handling is a core feature of a CPU. Exceptions include instruction exceptions and external interrupts. When some exception events occur, the CPU is enabled to respond to these events. The events include hardware errors, instruction execution errors, and user program request services.

The key of exception handling is to save the operating status of the CPU when an exception occurs and resume the status when the CPU exits exception handling. Exceptions can be identified in all stages of the instruction pipeline. The CPU hardware ensures that subsequent instructions do not change the CPU status. Exceptions are handled at the boundary of an instruction. To be specific, the CPU responds to the exceptions when the instruction retires, and saves the address of the to-be-executed instruction when the CPU exits exception handling. Even if exceptions are identified before an instruction retires, the CPU does not handle the exceptions until the instruction retires. To ensure proper functioning of programs, the CPU does not repeatedly run the executed instructions after exception handling is completed.

In machine mode (M-mode), the CPU responds to an instruction exception or an external interrupt in the following procedure:

Step 1: Save the exception PC to the mepc register.

Step 2: Update the meause and mtval registers based on the exception type.

**Step 3**: Save the machine interrupt-enable (MIE) bit in the mstatus register to the MPIE field, clear the MIE field, and prohibit responses to interrupts.



#### Chapter 5. Exceptions and Interrupts

**Step 4**: Save the privilege mode applied before the exception occurs to the MPP field in the mstatus register, and switch to the M-mode.

**Step 5**: Obtain the entry address of exception program based on the base address and mode in the mtvec register, and run instructions of the exception program in sequence.

C910 conforms to the exception vector table defined in RISC-V, as shown in Table 5.1.

Interrupt flag	Exception vector ID	Description
1	0	Unavailable.
1	1	A software interrupt in supervisor mode (S-mode).
1	2	Reserved.
1	3	A software interrupt in M-mode.
1	4	Unavailable.
1	5	A timer interrupt in S-mode.
1	6	Reserved.
1	7	The timer interrupt in M-mode.
1	8	Unavailable.
1	9	An external interrupt in S-mode.
1	10	Reserved.
1	11	An external interrupt in M-mode.
1	17	A performance detection overflow interrupt.
1	Others	Reserved.
0	0	Unavailable.
0	1	A fetch instruction access error exception.
0	2	An illegal instruction exception.
0	3	A debug breakpoint exception.
0	4	A load instruction unaligned access exception.
0	5	A load instruction access error exception.
0	6	A store/atomic instruction unaligned access exception.
0	7	A store/atomic instruction access error exception.
0	8	A user-mode (U-mode) environment call exception.
0	9	An S-mode environment call exception.
0	10	Reserved.
0	11	An M-mode environment call exception.
0	12	An instruction fetch page error exception.
0	13	A load instruction page error exception.
0	14	Reserved.
0	15	A store/atomic instruction page error exception.
0	>= 16	Reserved.

Table 5.1:	Exception	and	interrupt	vector	assignment
10010 0.1.	LACOPTION	ana	moorupu	VCCUOL	assistintation

#### Chapter 5. Exceptions and Interrupts

C910 supports exception and interrupt delegation. When an exception or interrupt occurs in S-mode, the CPU switches to the M-mode for handling. This causes performance loss of the CPU. Delegation enables the CPU to respond to exceptions and interrupts in S-mode. Exceptions that occur in M-mode are not delegated, but still handled in M-mode. Interrupts that occur in M-mode can be delegated to the S-mode for handling, except the external interrupts, software interrupts, and timer interrupts that occur in M-mode. In M-mode. In M-mode, the CPU does not respond to delegated interrupts.

In S-mode and U-mode, the CPU can respond to all interrupts and exceptions that meet the specified criteria. The CPU responds to undelegated exceptions and interrupts in M-mode, and updates the machine-mode exception handling registers. The CPU responds to delegated exceptions and interrupts in S-mode, and updates the S-mode exception handling registers.

# 5.2 Exceptions

### 5.2.1 Exception handling

In M-mode, the CPU responds to illegal instruction or access error exceptions in the following procedure:

Step 1: Save the exception PC to the mepc register.

**Step 2**: Set the interrupt flag in the meause register to 0, write the exception ID to the meause register, and update the mtval register based on the rules defined in Table 5.2.

**Step 3**: Save the machine interrupt-enable (MIE) bit in the mstatus register to the MPIE field, clear the MIE field, and prohibit responses to interrupts.

**Step 4**: Save the privilege mode applied before the exception occurs to the MPP field in the mstatus register, and switch to the M-mode.

**Step 5**: The PC fetches an instruction from the base address in the mtvec register and executes the instruction. The instruction is usually a jump instruction for jumping to the top-level handler. The handler analyzes the mcause register to obtain the exception ID and calls the handler corresponding to the exception ID.


Exception vec-	Exception	mtval update					
tor ID							
1	Fetch instruction access error exception	Virtual address accessed by the fetch in-					
		struction					
2	Illegal instruction exception	Instruction code					
3	Debug breakpoint exception	0					
4	Load instruction unaligned access excep-	Virtual address accessed by the load instruc-					
	tion	tion					
5	Load instruction access error exception	0					
6	Store/Atomic instruction unaligned ac-	Virtual address accessed by the					
	cess exception	store/atomic instruction					
7	Store/Atomic instruction access error ex-	0					
	ception						
8	U-mode environment call exception	0					
9	S-mode environment call exception	0					
11	M-mode environment call exception	0					
12	Fetch instruction page error exception	Virtual address accessed by the fetch in-					
		struction					
13	Load instruction page access exception	Virtual address accessed by the load instruc-					
		tion					
15	Store/Atomic instruction page error ex-	Virtual address accessed by the					
	ception	store/atomic instruction					

Table 5.2: Updates to mtval when exceptions occur

### 5.2.2 Return from exceptions

You can run the mret instruction to return from an exception. In this case, the CPU performs the following operations:

- Restore the mepc register to the PC. (The mepc register stores the PC applied when the exception occurs. You can adjust the mepc register to skip the exception instruction; otherwise, the exception instruction will be executed again.)
- Restore the value of the MPIE field in the mstatus register to the MIE field in the mstatus register.
- Restore the privilege mode applied before the exception occurs from the MPP field in the mstatus register.



### 5.2.3 Imprecise exceptions

In rare cases, the CPU may encounter imprecise exceptions. An imprecise exception means that the mepc register does not point to the instruction triggering the exception when the exception occurs. For example, the bus returns an error after the CPU executes a load instruction. An instruction can quickly retire in the pipeline, and the load instruction may have retired when the bus returns the error. Therefore, the mepc register points to a subsequent instruction instead of the load instruction.

However, imprecise exceptions rarely occur in practical systems. Once an imprecise exception occurs, the system may have encountered a fatal error.

# **5.3 Interrupts**

### 5.3.1 Interrupt priorities

When receiving multiple interrupt requests, the CPU responds to them by their priorities (in descending order):

- M-mode external interrupt
- M-mode software interrupt
- M-mode timer interrupt
- S-mode external interrupt
- S-mode software interrupt
- S-mode timer interrupt
- PMU overflow interrupt
- S-mode external interrupt (delegated)
- S-mode software interrupt (delegated)
- S-mode timer interrupt (delegated)
- PMU overflow interrupt (delegated)

#### 5.3.2 Interrupt responses

In M-mode, the CPU responds to an interrupt in the following procedure:

Step 1: Execute the current instruction and save the PC of the next instruction to the mepc register.

**Step 2**: Set the interrupt flag in the meause register to 1, write the interrupt ID to the meause register, and update the mtval register to 0.

#### Chapter 5. Exceptions and Interrupts

**Step 3**: Save the machine interrupt-enable (MIE) bit in the mstatus register to the MPIE field, clear the MIE field, and prohibit responses to interrupts.

**Step 4**: Save the privilege mode applied before the interrupt occurs to the MPP field in the mstatus register, and switch to the M-mode.

Step 5 (The Mode field in the mtvec register is 0, indicating a direct interrupt): The PC fetches an instruction from the base address in the mtvec register and executes the instruction. The instruction is usually a jump instruction for jumping to the top-level handler. The handler analyzes the mcause register to obtain the interrupt ID and calls the handler corresponding to the interrupt ID.

Step 5 (The Mode field in the mtvec register is 1, indicating a vectored interrupt): The PC fetches an instruction from the address calculated in (Base address in the mtvec register  $+ 4 \times$  Interrupt ID) and executes the instruction. The instruction is usually a jump instruction for jumping to the corresponding interrupt handler.

### 5.3.3 Return from interrupts

You can run the mret instruction to return from an interrupt. In this case, the CPU performs the following operations:

- Restore the mepc register to the PC. (The mepc register stores the PC of the next instruction and therefore does not need to be adjusted.)
- Restore the value of the MPIE field in the mstatus register to the MIE field in the mstatus register.

Restore the privilege mode applied before the interrupt occurs from the MPP field in the mstatus register.

# CHAPTER 6

### Memory Model

### 6.1 Overview

#### 6.1.1 Memory attributes

C910 supports two memory types: memory and device, which are distinguished by the SO bit. The memory supports speculative execution and out-of-order execution. It is further classified into cacheable memory and non-cacheable memory. The device supports only non-speculative in-order execution and therefore is non-cacheable. It is further classified into bufferable device and non-bufferable device. Bufferable indicates that a response to a write request can be quickly returned on an intermediate node. Non-bufferable indicates that a response to a write request is returned only after the end device completes writing.

To share data among multiple cores, C910 allows you to set the shareable (SH) page attribute. A shareable page is shared among multiple cores, and the hardware maintains data coherence. A non-shareable page is exclusively occupied by a core, and the software, instead of hardware, maintains data coherence among multiple cores.

The SH attribute of the cacheable memory is configurable. The non-cacheable memory and device are shareable by default, and you cannot modify their SH attributes.

In addition, C910 allows you to set the security (SEC) page attribute.

Table 6.1 describes the page attributes corresponding to each memory type.

Memory type	SO	C	В	SH	SEC
Cacheable memory	0	1	1	Configurable	Configurable
Non-cacheable memory	0	0	1	1	Configurable
Bufferable device	1	0	1	1	Configurable
Non-bufferable device	1	0	0	1	Configurable

Table 6.1: Memory types

The CPU can obtain the page attribute of an address from the sysmap.h file or a page table entry (PTE). The two methods are described as follows:

1. Page attributes of addresses are determined by the sysmap.h file if virtual addresses are not translated into physical addresses, that is, the machine mode (M-mode) or MMU is disabled.

2. Page attributes of addresses depend on the MAEE field in the mxstatus register if virtual addresses are translated into physical addresses, that is, the CPU is not in M-mode and the MMU is enabled. If the MAEE field is enabled, page attributes of addresses are determined by page attributes extended in the corresponding PTEs. If the MAEE field is disabled, page attributes of addresses are determined by the sysmap.h file.

sysmap.h is an extended configuration file of C910 that is open to users. You can define page attributes for different address ranges as required.

sysmap.h allows you to set page attributes for up to 8 address spaces. The largest address (non-inclusive) of address space i (i = 0 to 7) is defined by the SYSMAP\_BASE\_ADDRi (i = 0 to 7) macro. The smallest address (inclusive) is defined by the SYSMAP\_BASE\_ADDR(i - 1) macro. That is,

SYSMAP\_BASE\_ADDR(i - 1) <= Address of address space i < SYSMAP\_BASE\_ADDRi.

The smallest address of address space 0 is 0x0. Page attributes of memory addresses beyond the eight address spaces defined in the sysmap.h file are cacheable/bufferable/shareable/security by default. The upper and lower boundaries of each address space is 4 KB aligned. Therefore, the SYSMAP\_BASE\_ADDRi macro defines the upper 28 bits of an address.

Page attributes of memory addresses within address space i (i = 0 to 7) are defined by the SYSMAP\_FLAGi (i = 0 to 7) macro. The attribute layout is shown in fig\_address\_format.

### 6.1.2 Memory ordering model

C910MP adopts a weak memory ordering model, which is defined as follows:

- Ordering of access to the same address is maintained among multiple cores, including read after read (RAR), write after write (WAW), write after read (WAR), add read after write (RAW).
- Weak ordering of access to different addresses is allowed among multiple cores, including RAR, WAW, WAR, add RAW.



• Atomic other-multi-copy is ensured. When a core is able to obtain written data of another core, other cores must also be able to obtain the data. However, when a core is able to obtain its own written data, it is not required that other cores be able to obtain the data.

Weak memory ordering causes inconsistency between the actual read/write order among multiple cores and the access order defined by the program. Therefore, C910 provides extended SYNC instructions to enforce memory access ordering in software.

SYNC instructions define the execution order of all instructions, ensuring that all instructions preceding a SYNC instruction are executed before the SYNC instruction. In addition, SYNC instructions can also be used to synchronize instruction memory. After instructions preceding a SYNC instruction are executed, the SYNC instruction clears the pipeline and re-fetches instructions. For more information, see Table 6.2.

Mnemonic	Description	Scope
SYNC.IS	Synchronize data and instruction memory	Shareable
SYNC.I	Synchronize data and instruction memory	Non-shareable
SYNC.S	Synchronize data memory	Shareable
SYNC	Synchronize data memory	Non-shareable

Table 6.2: SYNC instructions

# 6.2 MMU

### 6.2.1 Overview

The memory management unit (MMU) of C910 complies with the RISC-V SV39 standard. It provides the following features:

- Address translation: Translates 39-bit virtual addresses to 40-bit physical addresses.
- Page protection: Checks the read/write/execution permissions of page visitors.
- **Page attribute management**: Extends address attribute bits and obtains page attributes based on access addresses for further processing by the system.

## 6.2.2 TLB

The MMU uses translation lookaside buffers (TLBs) to implement its features. A TLB stores virtual addresses used when the CPU accesses the memory. Before translating a virtual address, the MMU checks the page attributes in the TLB and outputs a physical address corresponding to the virtual address.

The MMU of C910 uses two levels of TLBs: the uTLB at level 1 and the jTLB at level 2. The uTLB includes the I-uTLB and the D-uTLB. After the CPU is reset, the hardware invalidates all entries in the uTLB and the jTLB, without the need of initializing software.

#### Chapter 6. Memory Model



The I-uTLB provides 32 fully associative entries for storing pages in 4 KB, 2 MB, or 1 GB size. When an instruction fetch request hits the I-uTLB, the physical address and the corresponding permission attribute can be obtained in the current cycle.

The D-uTLB provides 17 fully associative entries for storing pages in 4 KB, 2 MB, or 1 GB size. When a load/store request hits the D-uTLB, the physical address and the corresponding permission attribute can be obtained in the current cycle.

The jTLB is a 4-way set-associative cache shared by instructions and data. It provides 1024 entries for storing pages in 4 KB, 2 MB, or 1 GB size. When a request misses the uTLB but hits the jTLB, the physical address and the corresponding permission attribute will be returned within at least three cycles.

### 6.2.3 Address translation process

The MMU is used to translate virtual addresses into physical addresses and check corresponding permissions. Specific address mappings and corresponding permissions are configured by the operating system and stored in page tables. C910 implements address translation through indexing by at most three levels of page tables. The MMU accesses the L1 page table to obtain the base address of an L2 page table and the corresponding permission attributes, accesses the L2 page table to obtain the base address of an L3 page table and the corresponding permission attributes, and accesses the L3 page table to obtain the final physical address and the corresponding permission attributes. The MMU may obtain the final physical address, that is, a leaf table entry, at each level of access. The virtual page number (VPN) consists of 27 bits and is divided into three 9-bit VPN[i]. A part of the VPN is used for indexing in each access.

Content of leaf table entries is cached in the TLB to accelerate address translation. The content includes physical addresses translated from virtual addresses and corresponding permission attributes. If the uTLB is missed, the MMU accesses the jTLB. If the jTLB is missed, the MMU enables a hardware page table walk to access the memory to obtain the final address translation result.

A page table stores entry addresses of next-level page tables or physical information of the final page table. The page table structure is shown below:

63 62 61 60	59 58							e e	38	37				32
So C B Sh				-							PP	N[2]	]	
	Sec													
31 28	27		19	18		10	9 8	7	6	5	4 3	8 2	1	0
PPN[2]	]	PPN[1]			PPN[0]		RSW	D	A	G U	Х	W	R	V

Page table structure

#### Flags: page attributes in bit [9:0]

Features are described in *smel register*.

#### Flags: page attributes in bit [63:59]



The custom page attributes of C910, which are available when the MAEE field in the mxstatus register is enabled. Features are described in *smel register*.

#### **PPN:** physical page number

PPN[i] indicates the PPN corresponding to each level of page table.

The address translation process is described as follows:

If the TLB is hit when the CPU attempts to access a virtual address, the CPU directly obtains the physical address and the corresponding attributes from the TLB. If the TLB is missed, the MMU performs the following steps to translate the virtual address:

1. Obtain the access address {satp.PPN, VPN[2], 3' b0} of the L1 page table, and access the D-Cache/memory based on the address to obtain a 64-bit PTE of the L1 page table.

2. Check whether the PTE conforms to the physical memory protection (PMP) permission. If no, generate the corresponding access error exception. If yes, determine whether the X/W/R bit meets the condition of the leaf page table based on the rules shown in Table 6.4 . If yes, the final physical address has been found. Then go to step 3. If no, obtain the access address {PTE.PPN, next-level VPN, 3' b0} of the next-level page table, and access the D-Cache/memory again.

- 3. After the leaf page table is found, compare the X/W/R/L bit in the PMP register with the X/W/R bit in the PTE to obtain the minimum permissions, check the permissions, and write the content of the PTE back to jTLB.
- 4. If permission violation is found in any PMP check, generate the corresponding access error exception based on the access type.

5. Generate a page fault exception in the following three cases: the leaf page table is found but the access type does not conform to the setting of the A/D/X/W/R/U bit, no leaf page table is found after three accesses, or an access error is generated during access to the D-Cache/memory.

6. If the leaf page table is found in less than three accesses, a large page table has been obtained. In this case, check whether the PPN of the large page table is aligned based on the page size. If no, generate a page fault exception.

### 6.2.4 System control registers

In addition to the standard satp register, the MMU of C910 provides the extended smir, smcir, supervisormode (S-mode) entry low (smel), and S-mode entry high (smeh) control registers. You can use the extended registers to directly read, write, probe, and invalidate the TLB.

#### 6.2.4.1 Supervisor address translation and protection (satp) register

The satp register is an MMU control register defined in the SV39 standard.

#### Mode: MMU address translation mode



RV64		
Value	Name	Description
0	Bare	No translation or protection
1-7	-	Reserved
8	Sv39	Page-based 39-bit virtual addressing
9	Sv48	Page-based 48-bit virtual addressing
10	Sv57	Reserved for page-based 57-bit virtual addressing
11	Sv64	Reserved for page-based 64-bit virtual addressing
12-15	-	Reserved

Table 6.3: MMU	address	translation	$\operatorname{mode}$
----------------	---------	-------------	-----------------------

#### ASID: the current address space identifier (ASID)

Indicates the ASID of the current program.

#### PPN: root PPN for hardware writeback

Indicates the PPN used for L1 hardware writeback.

#### 6.2.4.2 smcir register

The smcir register enables you to probe, read, write, and invalidate the TLB.

63	}												32
										_			
3	30	29 28	8 27	26	25	24	23		10	6 15			0
Р	R	WI WJ	R		Π	-		-				ASID	
	]	[ASID				IAL	L						

Fig. 6.1: Smcir Register Description

#### TLBP: TLB probe

Indicates the operation of probing the TLB based on the smeh register.

When the TLB is hit, the value of the smir register is updated to the serial number of the TLB.

#### TLBR: TLB read

Indicates the operation of reading values of corresponding TLB entries based on indexes in the smir register, and updating the smeh and smel registers based on the values.

#### TLBWI: TLB indexed write





Indicates the operation of writing values of the smeh and smel registers to corresponding TLB entries based on indexes in the smir register.

#### TLBWR: TLB random write

Indicates the operation of writing values of the smeh and smel registers to corresponding TLB entries based on indexes in the random register.

### TLBIASID: TLB invalidation by ASID

Indicates the operation of invalidating all TLB entries that match the specified ASID.

#### TLBIALL: TLB initialization

Indicates the operation of invalidating all TLB entries and initializing the TLB.

#### TLBII: TLB invalidation by index

Indicates the operation of invalidating all TLB entries that match the specified index in the smir register.

### TLBIAW: TLB invalidation by world

Indicates the operation of invalidating all TLB entries corresponding to the trustable or non-trustable world.

This field is available only when trusted execution environment (TEE) extension is configured. It has not been implemented in C910.

#### ASID: the ASID used

Indicates the ASID used for matching in the TLBIASID operation. The smcir register enables you to probe, read, write, and invalidate the TLB.

#### TLBP: TLB probe

Indicates the operation of probing the TLB based on the smeh register. When the TLB is hit, the value of the smir register is updated to the serial number of the TLB.

#### TLBR : TLB read

Indicates the operation of reading values of corresponding TLB entries based on indexes in the smir register, and updating the smeh and smel registers based on the values.

#### TLBWI: TLB indexed write

Indicates the operation of writing values of the smeh and smel registers to corresponding TLB entries based on indexes in the smir register.

#### TLBWR: TLB random write

Indicates the operation of writing values of the smeh and smel registers to corresponding TLB entries based on indexes in the random register.

### TLBIASID: TLB invalidation by ASID



Indicates the operation of invalidating all TLB entries that match the specified ASID.

#### **TLBIALL: TLB** initialization

Indicates the operation of invalidating all TLB entries and initializing the TLB.

#### TLBII: TLB invalidation by index

Indicates the operation of invalidating all TLB entries that match the specified index in the smir register.

#### ASID: the ASID used

Indicates the ASID used for matching in the TLBIASID operation.

#### 6.2.4.3 smir register

The smir register is used to index the TLB. In TLB probing, the index of a hit entry is updated. In TLB write indexing, the index field of the smir register is written to write the mapping to the corresponding index in the jTLB.

63		32
	_	
31 30 29	11 10/9	0
P -	- Index	
Tfatal		

Fig. 6.2: Smir Register Descriptions

#### P – Probe Failure

0: indicates that TLB is hit when the TLBP instruction is executed.

1: indicates that TLB is missed when the TLBP instruction is executed.

#### Tfatal – Probe multiple

Specifies whether multiple matches occur when the TLBP instruction is executed.

- 0: indicates that no multiple matches occur.
- 1: indicates that multiple matches occur.

#### Index – TLB Index

1024-entry configuration: Index [9:8] is the way index, and index [7:0] is the set/entry index (4-way, 256 entries).

2048-entry configuration: Index [10:9] is the way index, and index [8:0] is the set/entry index (4-way, 512 entries).



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#### 6.2.4.4 smeh register

The smeh register stores virtual addresses in TLB access and VPNs when TLB exceptions occur. The ASID indicates the process ID corresponding to the current page.



#### Fig. 6.3: Smeh Register Descriptions

#### VPN: the virtual page number

This field is updated by hardware when the TLB is read or a page error exception occurs. Software writes a value to this field before writing values to TLB entries.

#### Pagesize: the page size

The page size is indicated by using a one-hot, where 100 indicates a size of 4 KB, 010 indicates a size of 2 MB, and 001 indicates a size of 1 GB.

This field is updated by hardware when the TLB is read. Software writes a value to this field before writing values to TLB entries.

#### ASID: the ASID used

This field stores the ID of the current address space identified by the operating system. It is used to distinguish between processes.

This field is updated by hardware when the TLB is read. Software writes a value to this field before writing values to TLB entries.

#### 6.2.4.5 smel register

The smel register stores physical addresses in TLB access and page attributes.

#### PPN: a 28-bit physical page number

#### SO - Strong Order

Indicates the access order required by memory.

- 1' b0: No strong order (Normal memory)
- 1' b1: Strong order(Device)
- C Cacheable



63 62 61 60 59 58	38 37 32
SO C B Sh	– PPN
Sec	
31	10 9 8 7 6 5 4 3 2 1 0
PPN	RSW D A G U X W R V

#### Fig. 6.4: SMEL Register Descriptions

- 1' b0: Uncacheable
- 1' b1: Cacheable

#### B - Buffer

- 1' b0: Unbufferable
- 1' b1: Bufferable

#### SH – Shareable

Indicates whether the page is shareable.

1' b0: Unshareable

1' b1: Shareable

#### Sec (T – Trustable)

Indicates whether the page belongs to the trustable or non-trustable world. This bit is available only when TEE pro extension is configured.

1' b0: non-trustable

1' b1: trustable

#### $\mathbf{RSW} - \mathbf{Reserved}$ for Software

A bit reserved for software to implement custom page table features. The default value is 2' b0.

#### $\mathbf{D} - \mathbf{Dirty}$

When the D bit is 1, it indicates whether data can be/has been written to the page.

1' b0: indicates that data has not been written/cannot be written to the page.

1' b1: indicates that data has been written/can be written to the page.

When the D bit is 0, a write operation to the page will trigger a page fault (store) exception. You can maintain the meanings of values of the D bit in the exception program through software.

A – Accessed



When the A bit is 1, it indicates that the page is accessible. When the A bit is 0, it indicates that the page is inaccessible. Access to the page will trigger a page fault exception for the corresponding access type.

1' b0: indicates that the page is accessible.

1' b1: indicates that the page is accessible.

#### $\mathbf{G} - \mathbf{Global}$

The global page ID, which indicates whether the page can be shared by multiple processes.

- 1' b0: indicates that the page is non-shareable and that the ASID is exclusive.
- 1' b1: indicates that the page is shareable.

#### U - User

Indicates whether the page is accessible in user mode (U-mode).

1' b0: indicates that the page is inaccessible in U-mode. Access to the page in U-mode will trigger a page fault exception. The default value is 1' b0.

1' b1: indicates that the page is accessible in U-mode.

#### X W R: executable, writable, readable

Х	W	R	Meaning
0	0	0	Pointer to next level of page table
0	0	1	Read-only page
0	1	0	Reserved for future use
0	1	1	Read-write page
1	0	0	Execute-only page
1	0	1	Read-execute page
1	1	0	Reserved for future page
1	1	1	Read-write-execute page

Table 6.4: XWR permissions

#### V - Valid

Indicates whether the physical page has been mapped to a virtual page. If the V bit of a page is 0, access to the page will cause a page fault exception.

- 1' b0: indicates that the physical page has not been mapped to a virtual page.
- 1' b1: indicates that the physical page has been mapped to a virtual page.

### 6.3 PMP



### 6.3.1 Overview

The PMP unit of C910 complies with the RISC-V standard. The PMP unit checks the access permission on a physical address to determine whether the CPU has the read/write/execution permissions on the address in current mode.

The PMP unit of C910 provides the following features:

- Supports eight PMP entries, which are identified and indexed by 0 to 7.
- Supports the minimum address split granularity of 4 KB.
- Supports the OFF, top of range (TOR), and naturally aligned power-of-2 region (NAPOT) address matching modes, but not the naturally aligned four-byte region (NA4) mode.
- Supports three permissions: readable, writable, and executable.
- Supports software locks for PMP entries.

### 6.3.2 PMP control registers

A PMP entry consists of an 8-bit configuration register and a 64-bit address register. All PMP control registers are accessible in M-mode. Access to PMP control registers in other modes will trigger illegal instruction exceptions.

#### 6.3.2.1 Physical memory protection configuration (pmpcfg) register

The pmpcfg register supports permission configuration for 8 entries.

63	56	55	48	47	40	39	32	31	24	23	16	15	8	7	0	
entry	7_cfg	entry6	cfg	entry5	cfg	entry4_	cfg	entry3	cfg	entry2_	cfg	entry1_	cfg	entry0	cfg	pmpcfg0
8		8		8		. 8		8		8		8		8		

Fig. 6.5: Layout of the pmpcfg register

7	6	5	4	3	2	1	0
L(WARL)	<b>O</b> (W)	ARL)	A (W.	ARL)	X(WARL)	W(WARL)	R(WARL)
1		2		2	1	1	1

#### Fig. 6.6: pmpcfg register

For more information about the pmpcfg register, see Table 6.5.



Bit	Name	Description		
0	R	The readable attribute of the entry.		
		<b>0</b> : indicates that the address matching the entry is non-readable.		
		1: indicates that the address matching the entry is readable.		
1	W	The writable attribute of the entry.		
		<b>0</b> : indicates that the address matching the entry is non-writable.		
		1: indicates that the address matching the entry is writable.		
2	X	The executable attribute of the entry.		
		<b>0</b> : indicates that the address matching the entry is non-executable.		
		1: indicates that the address matching the entry is executable.		
4:3	А	The address matching mode of the entry.		
		<b>00</b> : indicates the OFF mode, in which the entry is invalid.		
		01: indicates the TOR mode, in which the address of the adjacent entry is		
		used as the matching range.		
		10: indicates the NA4 mode, in which the matching range is 4 bytes. This		
		mode is not supported.		
		<b>11</b> : indicates the NAPOT mode, in which the matching range is a power of 2		
		and is at least 4 KB.		
7	L	The lock enable bit of the entry.		
		<b>0</b> : indicates that access in M-mode will succeed, and		
		access results in S-mode/U-mode depend on the R/W/X settings.		
		1: indicates that the entry is locked and cannot be modified.		
		In TOR mode, the address register of the previous entry cannot be modified		
		either.		
		Access results in all modes depend on the R/W/X settings.		

 Table 6.5: Descriptions of the pmpcfg register

In TOR mode, assuming that the access address is A, the condition for hitting entry i is as follows: pmpaddr(i-1) A < pmpaddr(i). The lower boundary of entry 0 is 0.

Addresses and corresponding protection region sizes in NAPOT mode are shown in Protection\_region\_code.



pmpaddr[37:9]	pmpcfg.A	Protection region size	Remarks
a_aaaa_aaaa_aaaa_a aaa_aaaa_aaaa	NAPOT	4KB	Supported
a_aaaa_aaaa_aaaa_a aaa_aaaa_aaa01	NAPOT	8KB	Supported
a_aaaa_aaaa_aaaa_a aaa_aaaa_aaaa_a011	NAPOT	16KB	Supported
a_aaaa_aaaa_aaaa_a aaaa_aaaa_0111	NAPOT	32KB	Supported
a_aaaa_aaaa_aaaa_a aaa_aaaa_aaa0_1111	NAPOT	64KB	Supported
a_aaaa_aaaa_aaaa_a aaa_aaaa_aa01_1111	NAPOT	128KB	Supported
a_aaaa_aaaa_aaaa_a aaa_aaaa_a011_1111	NAPOT	256KB	Supported
a_aaaa_aaaa_aaaa_a aaa_aaaa_0111_1111	NAPOT	512KB	Supported

Table 6.6: Protection region code :name: Protection\_region\_code

The PMP unit of C910 supports the minimum granularity of 4 KB in NAPOT mode, and does not support the NA4 mode.

#### 6.3.2.2 Physical memory protection address (pmpaddr) register

The PMP unit provides pmpaddr 0 to pmpaddr 7 for storing physical addresses of entries.

As defined in the RISC-V standard, pmpaddr registers store bit [39:2] of physical addresses. The PMP unit of C910 supports the minimum granularity of 4 KB. Therefore, bit [8:0] is not used for address authentication logic.

	63 38	37 9	8 0
	0	address [37:9] (WARL)	O (WARL)
Reset	0	0	0

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# 6.4 Memory access order

The following summarizes the processes of accessing an address space by C910 in different scenarios.

Scenario 1: without VA-PA translation

To access a PA:

- Obtain the address attribute from the sysmap.h file.
- Perform PMP checks to determine whether the XWR permissions conform to the PMP settings.
- Access the address.

Scenario 2: with VA-PA translation

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To access a VA:

- Translate the address by using the MMU to obtain the corresponding PTE.
- Obtain the following information from the PTE: the PA, address attribute (Note 1), and XWR permissions.
- Perform PMP checks to determine whether the XWR permissions conform to the PMP settings. (The minimum XWR permissions defined in the PMP register and PTE prevail.)
- Access the address.

(Note 1) When the MAEE field is 1, the address attribute comes from the PTE. When the MAEE field is 0, the address attribute comes from the sysmap.h file.

# CHAPTER 7

## Memory Subsystem

# 7.1 Memory Subsystem Overview

Each core of C910 has its own I-Cache and D-Cache. Two cores share one L2 cache. Data coherence among multiple cores is maintained by hardware.

# 7.2 L1 I-Cache

### 7.2.1 Overview

The L1 I-Cache provides the following features:

- Cache size: 64 KB, with a cache line size of 64 bytes, 2-way set-associative;
- Virtually indexed, physically tagged (VIPT);
- Data width for access: 128 bits;
- First-in, first-out (FIFO);
- Invalidation by I-Cache or cache line supported;
- Instruction prefetch supported;
- Way prediction supported;
- D-Cache snooping after a request misses the I-Cache (this feature can be enabled and disabled).



### 7.2.2 Way prediction

The C910 I-Cache adopts the 2-way set-associative structure. To reduce power consumption in parallel access to two caches, C910 implements I-Cache way prediction. When way prediction information is valid, access to invalid data ways is disabled, and the CPU accesses data only in the predicted way. You can configure the IWPE field in the mhint register to enable I-Cache way prediction.

Way prediction can be classified into the following two types by instruction fetch behavior:

- Sequential access: When the CPU consecutively fetches instructions in a line, the CPU predicts way information of the current access based on the way hit information of the last access.
- **Jump access**: A branch instruction obtains way prediction information of the target cache line along with the jump target address, and accesses one of the caches based on the information.

### 7.2.3 Loop acceleration buffer

C910 provides a 32-byte loop acceleration buffer to cope with a large number of short loops in programs. When detecting a short-loop instruction sequence, the CPU loads it to the loop acceleration buffer. When a subsequent instruction fetch request hits the buffer, the CPU directly obtains the instruction and jump target address from the buffer and disables access to the I-Cache, branch history table, and branch and jump target predictor, reducing dynamic power consumption of instruction fetch. You can configure the LPE field in the mhint register to enable short-loop acceleration.

### 7.2.4 Branch history table

C910 uses the branch history table to predict jump directions of conditional branch instructions. The branch history table is 64 KB in size. The bi-mode branch predictor predicts one branch result per cycle. The branch history table consists of predictors and selectors. The predictors are classified into jump and non-jump predictors and are maintained in real time based on branch history information. The branch history table indexes ways based on branch history information and the address of the current branch instruction to predict the jump direction of the branch instruction.

The branch history table predicts jump directions of the following conditional branch instructions:

BEQ, BNE, BLT, BLTU, BGE, BGEU, C.BEQZ, and C.BNEZ

### 7.2.5 Branch and jump target predictor

The C910 uses the branch and jump target predictor to predict jump target addresses of branch instructions. The branch and jump target predictor records the historical target addresses of branch instructions. If the current branch instruction hits the branch and jump target predictor, the recorded target address is used as the predicted target address of the current branch instruction.

The branch and jump target predictor provides the following features:



- Supports 1024 entries.
- Adopts the 2-way set-associative structure and supports selection and replacement based on the PC in the lower bits of a branch instruction.
- Maintains I-Cache way prediction information.
- Supports indexing by using a part of the PC of the current branch instruction.

The branch and jump target predictor predicts jump target addresses of the following branch instructions:

- BEQ, BNE, BLT, BLTU, BGE, BGEU, C.BEQZ, and C.BNEZ
- JAL and C.J

### 7.2.6 Indirect branch predictor

C910 uses the indirect branch predictor to predict target addresses of indirect branch instructions. Indirect branch instructions obtain target addresses from registers. One indirect branch instruction can contain multiple branch target addresses, which cannot be predicted by using the conventional branch and jump target predictor. Therefore, C910 uses the branch history-based indirect branch predictor to associate historical target addresses of an indirect branch instruction with its branch history information, and discretize different target addresses of one indirect branch instruction based on different branch history information. This makes it possible to predict multiple target addresses.

Indirect branch instructions include:

- JALR: except when the source register is x1 or x5
- C.JALR: except when the source register is x5
- C.JR: except when the source register is x1 or x5

### 7.2.7 Return address predictor

The return address predictor is used to quickly and accurately predict a return address when a function call ends. When the instruction fetch unit (IFU) obtains a valid function call instruction through decoding, it pushes a function return address to the return address predictor. When the IFU obtains a valid function return instruction through decoding, it pulls a function return address from the return address predictor. The return address predictor supports up to 12 nested function calls. If more than 12 function calls are nested, a target address prediction error will occur.

- Function call instructions include JAL, JALR, and C.JALR.
- Function return instructions include JALR, C.JR, and C.JALR.

For more information, see Table 7.1.



rd	rs1	rs1=rd	RAS action
!link	!link	-	none
!link	link	-	рор
link	!link	-	push
link	link	0	push and pop
link	link	1	push

 Table 7.1: Instruction features

### 7.2.8 Fast jump target predictor

To improve efficiency of the IFU in consecutive jumps, C910 provides a fast jump target predictor at level 1 of the IFU. When the IFU jumps consecutively, the fast jump target predictor records the address of the second jump instruction and the jump target address. If an instruction fetch request hits the fast jump target predictor, the IFU starts to jump at level 1, reducing performance loss of at least one cycle.

The fast jump target predictor predicts jump target addresses of the following branch instructions:

- BEQ, BNE, BLT, BLTU, BGE, BGEU, C.BEQZ, and C.BNEZ
- JAL and C.J
- Function return instructions

# 7.3 L1 D-Cache

### 7.3.1 Overview

The L1 D-Cache provides the following features:

- Cache size: 64 KB, with a cache line size of 64 bytes, 2-way set-associative;
- Physically indexed, physically tagged (PIPT);
- Maximum data width per read access: 128 bits, supporting byte, halfword, word, doubleword, and quadword access;
- Maximum data width per write access: 256 bits, supporting access to any combinations of bytes;
- Write policies: write-back with write-allocate, and write-back with write-no-allocate;
- First-in, first-out (FIFO);
- Invalidation and clearing by D-Cache or cache line supported;
- Multi-channel data prefetch for instructions.



### 7.3.2 Cache coherence

For requests with shareable and cacheable page attributes, data coherence between L1 D-Caches of different cores is maintained by hardware.

For requests with non-shareable and cacheable page attributes, the CPU does not maintain data coherence between L1 D-Caches. If non-shareable and cacheable pages need to be shared across cores, data coherence must be maintained by software.

C910MP maintains data coherence between L1 D-Caches of different cores based on the MESI protocol. MESI indicates four states of each cache line in the D-Cache:

- M: indicates that the cache line is available only in this D-Cache and has been modified (UniqueDirty).
- E: indicates that the cache line is available only in this D-Cache and has not been modified (Unique-Clean).
- S: indicates that the cache line may be available in multiple D-Caches and has not been modified (ShareClean).
- I: indicates that the cache line is not available in this D-Cache (Invalid).

### 7.3.3 Exclusive access

C910 supports exclusive memory access instructions: LR and SC. You can use the two instructions to constitute a synchronization primitive such as an atomic lock to synchronize data between different processes of a core or between different cores. The LR instruction tags the address to be exclusively accessed. The SC instruction determines whether the tagged address is preempted by other processes. C910 provides a local monitor in the L1 D-Cache and a global monitor in the L2 cache for each core. Each monitor consists of a state machine and an address buffer. The state machine has two states: IDLE and EXCLUSIVE.

Exclusive access to a cacheable page can be implemented with the local monitor. When the LR instruction is executed, it sets the state machine of the local monitor to the EXCLUSIVE state and stores the address to be accessed and the size to the buffer. When the SC instruction is executed, it reads the state of the local monitor, the address, and the size. If the state is EXCLUSIVE and the address exactly matches the size, the write operation is executed, a write success is returned, and the state machine is reset to the IDLE state. If the state or the address/size matching does not meet the requirement or the D-Cache is disabled, the write operation is not executed, a write failure is returned, and the state machine is reset to the IDLE state. When the write operation of another core performs matching against the local monitor at the same cache line address, the state machine is also reset to the IDLE state. The write operation in the current core or exclusive access to a different address does not affect the local monitor. In addition, the local monitor must be cleared when a process is switched.

Exclusive access to a non-cacheable page is implemented with both the local monitor and the global monitor. When the LR instruction is executed, it must set both the local monitor and the global monitor. After the local monitor passes the check, the SC instruction further checks the global monitor. If the global

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monitor passes the check, the write operation is executed, a write success is returned, and the state of the state machine is cleared; otherwise, the write operation is not executed, a write failure is returned, and the state of the state machine is cleared. When the write operation of another core performs matching against a global monitor at an address, the state machine of the global monitor is reset to the IDLE state.

In C910-based systems, we recommend that you use the LR and SC instructions to implement atomic locks. If the address attribute of an atomic lock is cacheable (either shareable or non-shareable), no special design is required for the SoC system. This is a typical case. If the address attribute of an atomic lock is non-cacheable, device, or strongly ordered, the system (for example, the slave client) must be integrated with an exclusive monitor. If an operation is performed in other ways, the response will be UNPREDICTABLE.

# 7.4 L2 Cache

### 7.4.1 Overview

The L2 cache provides the following features:

- Cache size: 1 MB, with a cache line size of 64 bytes, 16-way set-associative;
- Strictly inclusive of the L1 D-Cache, and non-strictly inclusive of the L1 I-Cache;
- Physically indexed, physically tagged (PIPT);
- Maximum data width per access: 64 bytes;
- Write policies: write-back with write-allocate, and write-back with write-no-allocate;
- First-in, first-out (FIFO);
- Programmable RAM latency;
- Instruction prefetch and TLB prefetch supported;
- Block-based pipelining.

#### 7.4.2 Cache coherence

The L2 cache of C910MP maintains data coherence between D-Caches of different cores based on the MOESI protocol. MOESI indicates five states of each cache line in the D-Cache:

- M: indicates that the cache line is available only in this D-Cache and has been modified (UniqueDirty).
- O: indicates that the cache line may be available in multiple D-Caches and has been modified (ShareDirty).
- E: indicates that the cache line is available only in this D-Cache and has not been modified (Unique-Clean).

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- S: indicates that the cache line may be available in multiple D-Caches and has not been modified (ShareClean).
- I: indicates that the cache line is not available in this D-Cache (Invalid)

### 7.4.3 Structure

The L2 cache of C910MP is built on a block-based pipelining architecture. Access addresses are discretized in two different blocks to allow parallel access and improve access efficiency.

The block mechanism is shown in Fig. 7.1 .

- The tag RAM is divided into two tag sub-blocks by PA[6]: tag bank 0 and tag bank 1, to handle two access requests in parallel within one clock cycle.
- Similarly, the data RAM is divided into two data sub-blocks by PA[6]: data bank 0 and data bank
  1. Each data sub-block is further divided into four 128-bit micro blocks, to obtain one cache line in parallel.



Fig. 7.1: L2 Cache structure

### 7.4.4 RAM latency

The L2 cache has a long access latency because it is large in size. It usually takes multiple clock cycles to complete access to the L2 cache. C910MP enables you to configure the access latency. You can set the setup time and latency of RAM in different processes. Detailed configurations are shown in Table 7.2.



Item	Feature	Description
L2 TAG setup	L2 Cache Tag RAM	L2 Cache Tag The RAM setup affects only tags.
	setup:	The RAM access.
	<b>1b0</b> : 0 cycles. Default	
	value	
	<b>1b1</b> : 1 cycle.	
L2 TAG latency	L2 Cache Tag RAM la-	
	tency:	
	<b>3b000</b> : 1 cycle. Default	
	value	
	<b>3b001</b> : 2 cycles.	
	<b>3b010</b> : 3 cycles.	
	<b>3b011</b> : 4 cycles.	
	<b>3b1xx</b> : 5 cycles.	
L2 DATA setup	L2 Cache Data RAM	L2 Cache Data The RAM setup affects only data.
	setup:	The RAM access.
	<b>1b0</b> : 0 cycles. Default	
	value	
	<b>1b1</b> : 1 cycle.	
L2 DATA latency	L2 Data RAM latency:	
	<b>3b000</b> : 1 cycle. Default	
	value	
	<b>3b001</b> : 2 cycles.	
	<b>3b010</b> : 3 cycles.	
	<b>3b011</b> : 4 cycles.	
	<b>3b100</b> : 5 cycles.	
	<b>3b101</b> : 6 cycles.	
	<b>3b110</b> : 7 cycles.	
	<b>3b111</b> : 8 cycles.	

Table 7.2: RAM latency configurations

You can set the latency based on the time required for accessing the RAM. The default value of setup is 0. When the RAM setup time or winding length is long, you can modify setup to 1.

The number of access cycles with the preceding configurations is shown in Table 7.3.



Tag latency	Valid access latency of the tag RAM				
/	TAG setup $= 0$	TAG setup $= 1$			
000	1	2			
001	2	3			
010	3	4			
011	4	5			
1xx	5	5			

Table 7.3: Valid access latency of the tag RAM

Table 7.4: Valid access latency of the data RAM

Tag latency	Valid access latency of the data RAM			
/	TAG setup $= 0$	TAG setup $= 1$		
000	1	2		
001	2	3		
010	3	4		
011	4	5		
100	5	6		
101	6	7		
110	7	8		
111	8	8		

- The maximum valid L2 tag latency is 5 cycles.
- When tag setup is 1, one more cycle is required for access. Before the SRAM is accessed, the SRAM input signal will be flopped.
- The maximum valid L2 data latency is 8 cycles.
- When data setup is 1, one more cycle is required for access. Before the SRAM is accessed, the SRAM input signal will be flopped.

# 7.5 Accelerated memory access

This section describes the accelerated memory access features of C910 L1 and L2 caches.

### 7.5.1 Instruction prefetch of the L1 I-Cache

The L1 I-Cache supports instruction prefetch. You can configure the IPLD field in the mhint register to enable this feature. When an instruction access request misses the current cache line, the next consecutive cache line is prefetched and stored to the prefetch buffer. When the instruction access request hits the

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prefetch buffer, the instruction is directly obtained from the prefetch buffer and written back to the I-Cache, reducing the instruction fetch latency.

This feature requires that the prefetched cache line and the current accessed cache line be on the same page, to ensure security of the instruction fetch address. In addition, you cannot allocate read-sensitive device address spaces to instruction spaces.

### 7.5.2 Multi-channel data prefetch of the L1 D-Cache

C910 supports data prefetch to reduce the access latency of large-sized memory such as DDR SDRAMs. C910 detects D-Cache misses to determine a fixed access mode through matching. Then the hardware automatically prefetches cache lines and writes them back to the L1 D-Cache.

C910 supports data prefetch through up to 8 channels and supports two prefetch methods: consecutive prefetch and strided prefetch (stride  $\leq 32$  cache lines).

C910 also implements forward prefetch and backward prefetch (the stride is negative) to support various possible access modes.

Data prefetch is disabled when the CPU invalidates or clears the D-Cache.

You can configure the DPLD field in the mhint register to enable data prefetch and the DPLD\_DIS field to determine the number of cache lines to be prefetched at a time.

The following instructions support data prefetch:

- LB, LBU, LH, LHU, LW, LWU, and LD
- FLW and FLD
- LRB, LRH, LRW, LRD, LRBU, LRHU, LRWU, LURB, LURH, LURW, LURD, LURBU, LURHU, LURWU, LBI, LHI, LWI, LDI, LBUI, LHUI, LWUI, LDD, LWD, and LWUD

#### 7.5.3 L1 adaptive write allocation mechanism

C910 implements adaptive write allocation at L1. When the CPU detects consecutive memory write operations, the write allocation attribute of pages is automatically disabled.

You can configure the AMR field in the mhint register to enable L1 adaptive write allocation.

When the CPU invalidates or clears the D-Cache, adaptive write allocation is automatically disabled. After the invalidation or clearing is completed, the CPU detects consecutive memory write operations again.

The following instructions support adaptive write allocation:

- SB, SH, SW, and SD
- FSW and FSD
- SRB, SRH, SRW, SRD, SURB, SURH, SURW, SURD, SBI, SHI, SWI, SDI, SDD, and SWD



### 7.5.4 L2 prefetch mechanism

The L2 cache supports instruction prefetch and TLB prefetch. It supports the following prefetch features:

- The number of instructions prefetched at a time is software-configurable and can be 0, 1, 2, or 3. All prefetched instructions are written back to the L2 cache.
- Only one entry is prefetched from the TLB at a time.
- The prefetch range is a 4 KB page table, and addresses beyond the range will not be prefetched.
- You can use the machine-mode (M-mode) L2-cache control register (mccr2) to configure the prefetch mechanism.

# **7.6** L1/L2 cache operation instructions and registers

After the CPU is reset, the I-Cache and D-Cache are automatically invalidated and disabled by default.

Similarly, after the CPU is reset, the L2 cache is automatically invalidated. After the invalidation is completed, the L2 cache is automatically enabled and cannot be disabled. When the L1 cache is disabled, no data is written back to the L2 cache if the L2 cache is missed.

### 7.6.1 Extended registers of the L1 cache

Extended registers of the C910 L1 cache are classified into the following types by feature:

- Cache enable and mode configuration: The M-mode hardware configuration register (mhcr) allows you to enable/disable the I-Cache/D-Cache and configure the write allocation and writeback modes. The supervisor-mode (S-mode) hardware configuration register (shcr) is a read-only register mapped to the mhcr register.
- Dirty page table entry clearing and invalidation: The M-mode cache operation register (mcor) allows you to clear and invalidate dirty page table entries in the I-Cache and the D-Cache.
- Cache read: The machine-mode cache access instruction register (mcins), M-mode cache access index register (mcindex), and M-mode cache access data register 0/1 (mcdata0/1) allow you to read data from the I-Cache and the D-Cache.

For more information, see *M*-mode CPU control and status extension registers and *M*-mode cache access extension registers.

### 7.6.2 Extended registers of the L2 cache

Extended registers of the C910 L2 cache are classified into the following types by feature:

- L2 cache enable and latency configuration: The mccr2 register allows you to set the access latency of the L2 cache.
- L2 cache read: The mcins, mcindex, and mcdata0/1 registers allow you to read data from the L2 cache.

For more information, see *M*-mode CPU control and status extension registers and *M*-mode cache access extension registers.

# 7.6.3 L1/L2 cache operation instructions

C910 provides extended L1/L2 cache operation instructions that invalidate page table entries by address, invalidate all page table entries, clear dirty page table entries by address, clear all dirty page table entries, clear and invalidate dirty page table entries by address, and clear and invalidate all dirty page table entries. For more information, see Table 7.5 .

ICACHE.IALL	Invalidates all page table entries in the I-Cache.
ICACHE.IALL	S Invalidates all page table entries in the I-Cache through broadcasting.
ICACHE.IPA	Invalidates page table entries that match the specified physical addresses in the I-Cache.
ICACHE.IVA	Invalidates page table entries that match the specified virtual addresses in the I-Cache.
DCACHE.CAL	LClears all dirty page table entries in the D-Cache.
DCACHE.CIA	LIC lears and invalidates all dirty page table entries in the D-Cache.
DCACHE.CIPA	Clears dirty page table entries that match the specified physical addresses in the D-Cache
	and invalidates the entries.
DCACHE.CISV	VClears dirty page table entries in the D-Cache based on the specified way and set and
	invalidates the entries.
DCACHE.CIVA	A Clears dirty page table entries that match the specified virtual addresses in the D-Cache
	and invalidates the entries.
DCACHE.CPA	Clears dirty page table entries that match the specified physical addresses in the D-Cache.
DCACHE.CPA	LC lears dirty page table entries that match the specified physical addresses in the L1 D-
	Cache.
DCACHE.CVA	Clears dirty page table entries that match the specified virtual addresses in the D-Cache.
DCACHE.CSW	Clears dirty page table entries in the D-Cache based on the specified way and set.
DCACHE.CVA	LClears dirty page table entries that match the specified virtual addresses in the L1 D-
	Cache.
DCACHE.IPA	Invalidates page table entries that match the specified physical addresses in the D-Cache.
DCACHE.ISW	Invalidates page table entries in the D-Cache based on the specified way and set.
DCACHE.IVA	Invalidates page table entries that match the specified virtual addresses in the D-Cache.
DCACHE.IALI	- Invalidates all page table entries in the D-Cache.
L2CACHE.CA	LIC lears all dirty page table entries in the L2 cache.
L2CACHE.CIA	LC lears all dirty page table entries in the L2 cache and invalidates the entries.
L2CACHE.IAL	LInvalidates all dirty page table entries in the L2 cache.

Table 7.5: L1/L2 cache operation instructions



For more information, see Appendix B-1 Cache instructions.

# CHAPTER 8

# Interrupt Controllers

# 8.1 Core local interrupt (CLINT) controller

C910 implements the CLINT controller. It is a memory address mapping module that handles software and timer interrupts.

### 8.1.1 CLINT register address mapping

The CLINT controller occupies a 64 KB memory space. Addresses in the upper 13 bits depend on the SoC hardware integration. Address mapping in the lower 27 bits is shown in Table 8.1. All registers support only access to word-aligned addresses.

### Chapter 8. Interrupt Controllers



Address	Name	Туре	Initial value	Description
0x4000000	MSIP0	Read/Wr	it0x00000000	The machine-mode (M-mode) software
				interrupt pending register for core 0.
				The upper bits are tied to $0$ , and bit $[0]$
				is valid.
0x4000004	MSIP1	Read/Wr	it@x00000000	The M-mode software interrupt
				pending register for core 1. The upper
				bits are tied to $0$ , and bit $[0]$ is valid.
Reserved	-	-	-	-
0x4004000	MTIMECMPL0	Read/Wr	it <b>θ</b> xFFFFFFFF	The M-mode clock timer
				compare value register (the lower $32$
				bits) for core 0.
0x4004004	MTIMECMPH0	Read/Wr	it <b>θ</b> xFFFFFFFF	The M-mode clock timer
				compare value register (the upper $32$
				bits) for core 0.
0x4004008	MTIMECMPL1	Read/Wr	it <b>θ</b> xFFFFFFFF	The M-mode clock timer
				compare value register (the lower $32$
				bits) for core 0.
0x400400C	MTIMECMPH1	Read/Wr	it <b>θ</b> xFFFFFFFF	The M-mode clock timer
				compare value register (the upper $32$
				bits) for core 0.
Reserved	-	-	-	-
0x400C000	SSIP0	Read/Wr	it0x00000000	The supervisor-mode (S-mode) software
				interrupt
				pending register for core 1. The upper
				bits are tied to 0, and bit $[0]$ is valid.
0x400C004	SSIP1	Read/Wr	it0x00000000	The S-mode software interrupt pending
				register for core 1.
				The upper bits are tied to 0, and bit $[0]$
				is valid.
Reserved	-	-	-	-
0x400D000	STIMECMPL0	Read/Wr	it <b>0</b> xFFFFFFFF	The S-mode clock timer compare value
				register (the lower 32 bits) for core $0$ .
0x400D004	STIMECMPH0	Read/Wr	it <b>0</b> xFFFFFFFF	The S-mode clock timer compare value
				register (the upper 32 bits) for core $0$ .
0x400D008	STIMECMPL1	Read/Wr	it <b>0</b> xFFFFFFFF	The S-mode clock timer compare value
				register (the lower 32 bits) for core 0.
0x400D00C	STIMECMPH1	Read/Wr	it <b>0</b> xFFFFFFFF	The S-mode clock timer compare value
				register (the upper 32 bits) for core 0.
Reserved	-	-	-	-

Table 8.1: Memory-mapped addresses in CLINT registers



### 8.1.2 Software interrupts

The CLINT controller can generate software interrupts.

Software interrupts are controlled by the software interrupt pending registers configured with address mappings. M-mode software interrupts are controlled by the machine software interrupt pending (MSIP) register. S-mode software interrupts are controlled by the supervisor software interrupt pending (SSIP) register.

You can set the xSIP bit to 1 to generate software interrupts or reset it to 0 clear software interrupts. CLINT S-mode software interrupt requests are valid only when the CLINTEE bit is enabled for the corresponding core.

In M-mode, the CPU is allowed to access and modify all software interrupt registers. In S-mode, the CPU is allowed to access and modify only the SSIP register. In user mode (U-mode), the CPU has no access to software interrupt registers.

The two groups of registers have the same structure. The bit layout and definition of the registers are shown in fig\_msip .

#### MSIP: the machine software interrupt pending bit

This bit indicates the status of M-mode software interrupts.

- When the MSIP bit is 1, valid M-mode software interrupt requests are available.
- When the MSIP bit is 0, no valid M-mode software interrupt requests are available.



SSIP register

#### SSIP: the supervisor software interrupt pending bit

This bit indicates the status of S-mode software interrupts.

- When the SSIP bit is 1, valid S-mode software interrupt requests are available.
- When the SSIP bit is 0, no valid S-mode software interrupt requests are available.

### **8.1.3 Timer interrupts**

The CLINT controller can generate timer interrupts.

A multi-core system has only one 64-bit system timer, mtime. mtime must run in the always-on voltage domain. mtime cannot be written but can be reset. The current value of mtime can be read from the time

#### Chapter 8. Interrupt Controllers



register of the performance monitoring unit (PMU). mtime is used to provide a unified time reference for multiple cores.

Each core has a group of 64-bit *M*-mode clock timer compare value registers (mtimecmpl and mtimecmph) and \*a group of 64-bit S-mode clock timer compare value registers \*(stimecmpl and stimecmph). You can modify the upper or lower 32 bits of these registers through word-aligned address access.

The CLINT controller compares the value of {CMPH[31:0], CMPL[31:0]} with the current value of mtime to determine whether to generate a timer interrupt. When the value of {CMPH[31:0], CMPL[31:0]} is greater than the current value of mtime, the CLINT controller does not generate an interrupt. When the value of {CMPH[31:0], CMPL[31:0]} is less than or equal to the current value of mtime, the CLINT controller generates a corresponding timer interrupt. You can rewrite the value of the mtimecmp/stimecmp register to clear the corresponding timer interrupt. S-mode timer interrupt requests are valid only when the CLINTEE bit is enabled for the corresponding core.

In M-mode, the CPU is allowed to access and modify all timer interrupt registers. In S-mode, the CPU is allowed to access and modify only the stimecmpl and stimecmph registers. In U-mode, the CPU has no access to timer interrupt registers.

The two groups of registers have the same structure. The bit layout and definition of the registers are shown in :numref:  $fig_CLICFIG3$ .

	63 32	31 0
	MTIMECMPH	MTIMECMPL
Reset	Oxfffffff	0xfffffff

mtimecmph/mtimecmpl registers

• mtimecmph/mtimecmpl: the M-mode clock timer compare value registers for the upper bits and the lower bits

These registers store timer compare values.

- mtimecmph: stores the upper 32 bits of timer compare values.
- mtimecmpl: stores the lower 32 bits of timer compare values.

	63 32	31 0
	STIMECMPH	STIMECMPL
Reset	Oxfffffff	0xfffffff

stimecmph/stimecmpl registers

• stimecmph/stimecmpl: the S-mode clock timer compare value registers for the upper bits and the lower bits

These registers store timer compare values.

• stimecmph: stores the upper 32 bits of timer compare values.



• stimecmpl: stores the lower 32 bits of timer compare values.

# 8.2 Platform-level interrupt controller (PLIC)

The PLIC controls sampling, priority arbitration, and distribution of external interrupt sources.

In the PLIC model, the M-mode and S-mode of each core can act as valid interrupt targets. The PLIC of C910 provides the following features:

- Interrupt distribution for two cores and four interrupt targets;
- Sampling of 144 interrupt sources, supporting level and pulse interrupts;
- 32 interrupt priorities;
- Independent enable for each interrupt target;
- Independent interrupt threshold for each interrupt target;
- Configurable access permissions on PLIC registers.

### 8.2.1 Interrupt arbitration

In the PLIC, only interrupt sources that meet the specified conditions are involved in arbitration on an interrupt target. The conditions include:

- The interrupt source is in the pending state (IP = 1).
- The interrupt priority is greater than 0.
- The enable bit for the interrupt target is enabled.

When multiple interrupts for an interrupt target are in the pending state, the PLIC selects the interrupt with the highest priority through arbitration. In the PLIC of C910, M-mode interrupts have higher priorities than S-mode interrupts. In the same privilege mode, a larger value of the priority configuration register indicates a higher priority. Interrupts with a priority of 0 are invalid. If multiple interrupts have the same priority, they will be handled in ascending order of IDs.

The PLIC stores interrupt IDs that are determined based on arbitration results to the interrupt claim/complete register of the corresponding interrupt target.

#### 8.2.2 Interrupt request and response

When the PLIC has a valid interrupt request for an interrupt target and the interrupt priority is higher than the interrupt threshold of the interrupt target, the PLIC sends the interrupt request to the interrupt target. When receiving the interrupt request, the interrupt target sends an interrupt response message to the PLIC if it is able to respond to the interrupt request.


The interrupt response mechanism functions as follows:

- The interrupt target initiates a read operation to the corresponding interrupt claim/complete register. The read operation returns the interrupt ID determined by the PLIC. The interrupt target proceeds to further processing based on the interrupt ID. If the interrupt ID is 0, no valid interrupt request is available, and the interrupt target ends the interrupt handling process.
- After receiving the read operation initiated by the interrupt target and returning the interrupt ID, the PLIC resets the IP bit of the interrupt source corresponding to the interrupt ID, and blocks subsequent sampling on the interrupt source before the current interrupt is completed.

## 8.2.3 Interrupt completion

After interrupt handling is completed, the interrupt target sends an interrupt completion message to the PLIC. The interrupt completion mechanism functions as follows:

- The interrupt target initiates a write operation to the corresponding interrupt claim/complete register, to write the ID of the completed interrupt to the register. If the interrupt is a level interrupt, the external interrupt source must be cleared before the write operation is initiated.
- After receiving the interrupt completion message, the PLIC does not update the interrupt claim/complete register, but unblocks sampling on the interrupt source corresponding to the interrupt ID to end the interrupt handling process.

# 8.2.4 PLIC register address mapping

The PLIC occupies a 64 MB memory space. Addresses in the upper 13 bits depend on the SoC hardware integration. Address mapping in the lower 27 bits is shown in Table 8.2. All registers support only access to word-aligned addresses. *PLIC registers are accessible through the load word instruction. Access results are placed in the lower 32 bits of 64-bit GPRs.* 

Note: Registers not supported by C910 are marked as reserved.

Address	Name	Туре	Initial	Described
			value	
0x0000000	-	-	-	-
0x0000004	PLIC_PRIO1	R/W	0x0	The
0x0000008	PLIC_PRIO2	R/W	0X0	priority configuration register for inter-
0x000000C	PLIC_PRIO3	R/W	0x0	rupts 1 to 1023.
0x0000FFC	PLIC_PRIO1023	R/W	0x0	

Table 8.2: PLIC	register	address	mapping
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#### Chapter 8. Interrupt Controllers



Address	Name	Туре	Initial	Described
			value	
0x0001000	PLIC_IP0	R/W	0x0	The
				interrupt pending register for interrupts
				1 to 31.
0x0001004	PLIC_IP1	R/W	0x0	The
				interrupt pending register for interrupts
				1 to 31.
0x000107C	PLIC_IP31	R/W	0x0	The
				interrupt pending register for interrupts
				1 to 31.
Reserved	-	-	-	-
0x0002000	PLIC_H0_MIE0	R/W	0x0	The
				M-mode interrupt enable register for in-
				terrupts 1 to 31 in core 0.
0x0002004	PLIC_H0_MIE1	R/W	0x0	The
				M-mode interrupt enable register for in-
				terrupts 32 to 63 in core 0.
		1		
0x000207C	PLIC_H0_MIE31	R/W	0x0	The
				M-mode interrupt enable register for in-
				terrupts 32 to 63 in core 0.
0x0002080	PLIC_H0_SIE0	R/W	0x0	The
				S-mode
				interrupt enable register for interrupts 1
				to 31 in core 0.
0x0002084	PLIC_H0_SIE1	R/W	0x0	The
				S-mode
				interrupt enable register for interrupts 1
				to 31 in core 0.
			•	
0x00020FC	PLIC_H0_SIE31	R/W	0x0	The
				S-mode interrupt enable register for in-
				terrupts $992$ to $1023$ in core $0$ .
0x0002100	PLIC_H1_MIE0	R/W	0x0	The
				M-mode interrupt enable register for in-
				terrupts 1 to 31 in core 0.

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#### Chapter 8. Interrupt Controllers



Addross	Nama	Tuno	Initial	Described
Address	Name	туре	Initial	Described
0.0000104		D/W	value	
0x0002104	PLIC_H1_MIE1	R/W	0x0	
				M-mode interrupt enable register for in-
				terrupts 1 to 31 in core 0.
	1			
0x000217C	PLIC_H1_MIE31	R/W	0x0	The
				M-mode interrupt enable register for in-
				terrupts 1 to 31 in core 0.
0x0002180	PLIC_H1_SIE0	R/W	0x0	The
				S-mode
				interrupt enable register for interrupts 1
				to 31 in core 1.
0x0002184	PLIC_H1_SIE1	R/W	0x0	The
				S-mode
				interrupt enable register for interrupts 1
				to 31 in core 1.
	•		·	
0x00021FC	PLIC_H1_SIE31	R/W	0x0	The
				S-mode interrupt enable register for in-
				terrupts $992$ to $1023$ in core 1.
Reserved	-	-	-	-
0x01FFFFC	PLIC_PER	R/W	0x0	The PLIC permission control register.
0x0200000	PLIC_H0_MTH	R/W	0x0	The M-mode interrupt
				threshold register for core 0.
0x0200004	PLIC_H0_MCLAI	MR/W	0x0	The M-mode interrupt
				claim/complete register for core 0.
Reserved	-	-	-	-
0x0201000	PLIC_H0_STH	R/W	0x0	The S-mode interrupt
				threshold register for core 0.
0x0201004	PLIC_H0_SCLAIN	I R/W	0x0	The S-mode interrupt
				claim/complete register for core 0.
Reserved	-	-	-	-
0x0202000	PLIC_H1_MTH	R/W	0x0	The M-mode interrupt
				threshold register for core 0.
0x0202004	PLIC_H1_MCLAI	MR/W	0x0	The M-mode interrupt
				claim/complete register for core 0.
Reserved	-	-	-	-

Table 8.2 - continued from previous pag
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Address	Name	Туре	Initial	Described
			value	
0x0203000	PLIC_H1_STH	R/W	0x0	The S-mode interrupt
				threshold register for core 0.
0x0203004	PLIC_H1_SCLAIM	IR/W	0x0	The S-mode interrupt
				claim/complete register for core 0.
Reserved	-	-	-	-

Table 8.2 – continued from previous page

# 8.2.5 PLIC\_PRIO register

This register is used to set the priorities of interrupt sources. Register read and write permissions For more information, see the descriptions of the PLIC\_PER register. The bit layout and definition of the register are shown in fig\_plic\_prio.

#### • PRIO: the interrupt priority

The lower 5 bits of the PLIC\_PRIO register are writable. The PLIC\_PRIO register supports 32 interrupt priorities. Interrupts with a priority of 0 are invalid.

M-mode interrupts have higher priorities than S-mode interrupts in any conditions. In the same privilege mode, the priority 1 is the lowest priority, and the priority 31 is the highest priority. When multiple interrupts have the same priority, interrupt IDs are further compared. An interrupt with a smaller ID has a higher priority.

# 8.2.6 PLIC\_IP register

The PLIC can read the PLIC\_IP register to obtain the pending state of each interrupt. If the ID of an interrupt is N, the interrupt information is stored in IP y (y = N mod 32) in the PLIC\_IP x (x = N/32) register. Bit 0 of the PLIC\_IP0 register is tied to 0. Register read and write permissions For more information, see the descriptions of the PLIC\_PER register. The bit layout and definition of the register are shown in Fig. 8.1.





#### • IP: the interrupt pending state bit



This bit indicates the interrupt pending state of the corresponding interrupt source.

- When the IP bit is 1, the interrupt source has pending interrupts. You can run a memory store instruction to set this bit to 1. When the sampling logic of the interrupt source detects valid level or pulse interrupts, this bit is also set to 1.
- When the IP bit is 0, the interrupt source has no pending interrupt. You can run a memory store instruction to reset this bit. After an interrupt is handled, PLIC clears the corresponding IP bit.

## 8.2.7 PLIC\_IE register

Each interrupt target has an interrupt enable bit for each interrupt source, to enable the corresponding interrupts. The M-mode interrupt enable register is used to enable M-mode external interrupts. The S-mode interrupt enable register is used to enable S-mode external interrupts.

If the ID of an interrupt is N, the interrupt enable information is stored in IE y ( $y = N \mod 32$ ) in the PLIC\_IE x (x = N/32) register. The IE bit corresponding to ID 0 is set to 0. For more information about the read and write permissions on the register, see the descriptions of the PLIC\_PER register.

The bit layout and definition of the register are shown in Fig. 8.2.



#### Fig. 8.2: PLIC\_IE x register

#### • IE: the interrupt enable state bit

This bit indicates the interrupt enable state of the corresponding interrupt source.

- When the IE bit is 1, the interrupt source is enabled for the interrupt target.
- When the IE bit is 0, the interrupt source is disabled for the interrupt target.

#### 8.2.8 PLIC\_PER register

The PLIC\_PER register is used to control access permissions on PLIC registers in S-mode.

PLIC\_PER register

#### • **S\_PER:** the access permission control bit

When the S\_PER bit is 0, the CPU has access to all PLIC registers only in M-mode. In S-mode, the CPU has access only to the S-mode PLIC\_TH register and S-mode PLIC\_CLAIM register, but not to the







PLIC\_PER, PLIC\_PRIO, PLIC\_IP, or PLIC\_IE register. In U-mode, the CPU has no access to any PLIC registers.

When the S\_PER bit is 1, the CPU has access to all PLIC registers in M-mode, and has access to all PLIC registers except PLIC\_PER in S-mode. In U-mode, the CPU has no access to any PLIC registers.

# 8.2.9 PLIC\_TH register

Each interrupt target has a PLIC\_TH register. The PLIC initiates an interrupt request to an interrupt target only when the interrupt request is valid and the interrupt priority is higher than the interrupt threshold of the interrupt target. For more information about the read and write permissions on the register, see the descriptions of the PLIC\_PER register.

The bit layout and definition of the register are shown in fig\_plic\_th .

#### • **PRIOTHRESHOLD**: the priority threshold

This bit indicates the interrupt threshold of the current interrupt target. When the interrupt threshold is 0, all interrupts are allowed.

# 8.2.10 PLIC\_CLAIM register

Each interrupt target has a PLIC\_CLAIM register. When the PLIC completes arbitration, this register is updated to the interrupt ID obtained in the current arbitration. For more information about the read and write permissions on the register, see the descriptions of the PLIC\_PER register.

The bit layout and definition of the register are shown in Fig. 8.3 .



#### Fig. 8.3: PLIC\_CLAIM register

#### • CLAIM\_ID: the interrupt request ID

A read operation to the register returns the ID currently stored in the register. The read operation indicates that the interrupt corresponding to the ID is in the process of handling. The PLIC starts the interrupt claim process.

#### Chapter 8. Interrupt Controllers



A write operation to the register indicates that the interrupt corresponding to the ID to be written has been handled. The write operation does not update the PLIC\_CLAIM register. The PLIC starts the interrupt complete process.

# 8.3 Multi-core interrupts

This section describes two common multi-core interrupt scenarios.

#### 8.3.1 Multiple cores respond to external interrupts in parallel

In the PLIC model, one interrupt source can be mapped to multiple cores. When the interrupt source generates an interrupt request, the interrupt request is in the pending state with respect to multiple cores. Different cores run in different states, and they respond to the interrupt successively and read the PLIC\_CLAIM register to obtain the interrupt ID. Design of the PLIC ensures that only the first core accessing the PLIC\_CLAIM register obtains the valid ID, and other cores obtain an invalid ID (ID = 0) and therefore do not handle the interrupt. In this case, the interrupt is handled only once.

Mapping an interrupt to multiple cores reduces the overall interrupt response time because any one of the cores has an opportunity to handle the interrupt. However, bandwidth of the cores that obtain the invalid ID is consumed, wasting additional CPU resources.

#### 8.3.2 Send software interrupts across cores

In the programming model of the CLINT controller, software interrupts are stored in dedicated registers:

- M-mode software interrupts are stored in the MSIP0 and MSIP1 registers.
- S-mode software interrupts are stored in the SSIP0 and SSIP1 registers.

Addresses of the preceding registers are unified and known to all cores. Each core can initiate write operations to the registers to send software interrupts to other cores or itself.

# CHAPTER 9

# **Bus Interface**

## 9.1 AXI master device interface

The master device interface of C910MP supports the AMBA 4.0 AXI protocol. For more information, see AMBA Specifications — AMBA® AXI<sup>TM</sup> and ACE<sup>TM</sup> Protocol Specification.

#### 9.1.1 Features of the AXI master device interface

The AXI master device interface controls address accesses and data transmission between C910 and the AXI bus. It provides the following features:

- Complies with the AMBA 4.0 AXI protocol.
- Supports a bus width of 128 bits.
- Supports different frequency ratios between the system clock and the CPU master clock.
- Supports flop-out of all output signals and flop of all input signals to obtain better timing.

#### 9.1.2 Outstanding capability of the AXI master device interface

This section describes the outstanding capability of the AXI master device interface provided by C910.



Parameter	Value	Description
Read Issuing Capability	8n+28	Each core can issue up to 8 non-cacheable and de-
	n = Number of	vice read requests. All cores can issue up to 28
	cores	cacheable read requests.
Write Issuing Capability	8n+32	Each core can issue up to 8 non-cacheable and de-
	n = Number of	vice write requests. All cores can issue up to 32
	cores	cacheable write requests.

Table 9.1: Outstanding capability of the AXI master device interface

#### Table 9.2: AWID encoding of the AXI master device interface

AWID[7:0]	Scenario	Outstanding requests of each ID
$\{3' b111, 5' b?????\}$	Cacheable write requests	Each ID has no outstanding requests.
		All cacheable write requests are out-
		standing. A total of 32 outstanding re-
		quests are supported.
{4' b0000, 4' b????}	Non-cacheable and weak-	Each ID has no outstanding requests.
	ordered write requests	All non-cacheable and weak-ordered
		write requests are outstanding. A to-
		tal of 16 outstanding requests are sup-
		ported.
$\{1' b0, 2' b(coreid), 5' h1d\}$	Non-cacheable and strong-	Non-cacheable and strong-ordered write
	ordered write requests	requests are outstanding. A total of 31
		outstanding requests are supported.

Note: The ARID and AWID encoding may vary with evolution of the CPU version. Therefore, SoC integration should not depend on specific IDs, but should conform to general-purpose rules of the AXI protocol.

# 9.1.3 Supported transmission types

The AXI master device interface supports the following transmission types:

- Burst types: INCR and WRAP;
- Transmission lengths: 1 and 4;
- Exclusive access;
- Transmission sizes: quadword, doubleword, word, halfword, and byte;
- Read and write.



Note: The AXI master device interface of C910 implements only a subset of all AXI transmission types. Therefore, SoC integration should not depend on specific transmission types, but should conform to general-purpose rules of the AXI protocol.

## 9.1.4 Supported response types

The AXI master device interface supports the following types of responses from slave devices:

- OKAY
- EXOKAY
- SLVERR
- DECERR

#### 9.1.5 CPU behavior in different bus responses

CPU behavior in different bus responses is shown in Table 9.3.

RRESP/BRESP	Result				
OKAY	Indicates that common transfer access succeeds or exclusive transfer ac-				
	cess fails. If exclusive read transfer access fails, it indicates that the				
	bus does not support exclusive transfer, and an access error exception is				
	generated. If exclusive write transfer access fails, it indicates that lock				
	preemption fails, and no exception is generated.				
EXOKAY	Indicates that exclusive access succeeds.				
SLVERR/DECERR	Indicates that an access error occurs. If this error occurs in read transfer,				
	an exception is generated. If this error occurs in write transfer, it is				
	ignored.				

Table 9.3: Bus exception handling

#### 9.1.6 Signals supported by the AXI master device interface

Signals supported by the AXI4 master device interface are described in Table 9.4.

Signal name	I/0	Reset	Definition		
Interface related to the address read channel					
biu_pad_arid[7:0]	0	0	The address ID of the read request.		
biu_pad_araddr[39:0]	0	0	The address of the read request.		

Table 9.4: Signals supported by AXI channels



Signal name	I/O	Reset	Definition
biu_pad_arlen[1:0]	0	0	The burst length of the read re-
			quest.
			00: 1 transfer
			11: 4 transfers
biu_pad_arsize[2:0]	0	0	The data bit width per cycle of the
			read request.
			000: 1 byte
			001: 2 bytes
			010: 4 bytes
			011: 8 bytes
			100: 16 bytes
biu_pad_arburst[1:0]	0	0	The transfer type corresponding to
			the read request:
			01: INCR
			10: WRAP
biu_pad_arlock	0	0	The access method corresponding
			to the read request:
			0: normal access
			1: exclusive access
biu_pad_arcache[3:0]	0	0	The memory access type corre-
			sponding to the read request:
			0000: device no n-bufferable
			(strong order)
			0001: device bufferable (strong or-
			der)
			0011: normal non-cacheable buffer-
			able (weak order)
			1111: cacheable
biu_pad_arprot[2:0]	0	0	The protection type of the read re-
			quest:
			0   1
			[2]: data   instruction
			[1]: secure   n on-secure. The value
			is always 1.
			[0]: user   privileged



Signal name	I/O	Reset	Definition	
biu_pad_aruser[2:0]	0	0	The user-defined signal of the read	
			request:	
			[2]: L2 Cache prefetch request	
			[1]: machine-mode (M-mode) re-	
			quest	
			[0]: MMU writeback request	
biu_pad_arvalid	Ο	0	The valid signal of the address read	
			channel.	
pad_biu_arready	I	-	The slave ready signal of the ad-	
			dress read channel.	
Interface related to the data re	ead channel			
_pad_biu_rid[7:0]	Ι	-	The data ID of the read request.	
pad_biu_rdata[127:0]	Ι	-	The data of the read request.	
pad_biu_rresp[3:0]	Ι	-	The response information of the	
			read request.	
			[1:0]: 00: OKAY	
			01: EXOKAY	
			10: SLVERR	
			11: DECERR	
			[2]: PASSDIRTY	
			[3]: ISSHARED	
pad_biu_rlast	Ι	-	Data of the last cycle of the read	
			request.	
pad_biu_rvalid	Ι	-	The valid signal of the data read	
			request.	
biu_pad_rready	0	1	The ready information of the data	
			read channel.	
Interface related to the address write channel				
biu_pad_awid[7:0]	Ο	0	The address ID of the write re-	
			quest.	
biu_pad_awaddr[39:0]	Ο	0	The address of the write request.	
biu_pad_awlen[1:0]	Ο	0	The burst length of the write re-	
			quest.	
			00: 1 cycle	
			11: 4 cycles	



Table 9.4 – continued from previous page
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Signal name	I/O	Reset	Definition
biu_pad_awsize[2:0]	0	0	The data bit width per cycle of the
			write request.
			000: 1 byte
			001: 2 bytes
			010: 4 bytes
			011: 8 bytes
			100: 16 bytes
$biu_pad_awburst[1:0]$	0	0	The transfer type corresponding to
			the read request:
			01: INCR
			10: WRAP
biu_pad_awlock	0	0	The access method corresponding
			to the read request:
			0: normal access
			1: exclusive access
biu_pad_awcache[3:0]	0	0	The memory access type corre-
			sponding to the read request:
			0000: device no n-bufferable
			(strong order)
			0001: device bufferable (strong or-
			der)
			0011: normal non-cacheable buffer-
			able (weak order)
			0111: write-back no-allocate
			1111: write-back cacheable
biu_pad_awprot[2:0]	0	0	The protection type of the write re-
			quest:
			0   1
			[2]: data   instruction
			[1]: secure   n on-secure. The value
			is always 1.
			[0]: user   privileged
biu_pad_awvalid	0	0	The valid signal of the address
			write channel.
pad_biu_arready	I	-	The slave ready signal of the ad-
			dress read channel.
Interface related to the data write channel			
biu_pad_wdata[127:0]	0	0	The data of the write request.



Signal name	I/O	Reset	Definition
biu_pad_wstrb[15:0]	0	0	The valid data fields of the data.
biu_pad_wlast	0	0	Data of the last cycle.
biu_pad_wvalid	0	0	The valid signal of the data write
			channel.
biu_pad_wready	Ι	-	The slave ready signal of the ad-
			dress read channel.
Interface related to the write r	esponse chann	el	
pad_biu_bid[7:0]	Ι	-	The ID of the write response.
pad_biu_bresp[1:0]	I	-	The write response information,
			which is
			the response information of the
			write request.
			[1:0]: 00: OKAY
			01: EXOKAY
			10: SLVERR
			11: DECERR
pad_biu_bvalid	I	-	The valid signal of the write re-
			sponse channel.
biu_pad_bready	0	1	The ready signal of the write re-
			sponse channel.

Table 9.4 – continued from previous page

# Chapter 10

# Debug

# 10.1 Features of the debug unit

The debug interface provides an interaction channel between software and the CPU. You can call the debug interface to obtain information stored in registers and memory of the CPU and information about other on-chip devices. You can also call the debug interface to download programs.

C910MP supports the JTAG communication protocol (also known as JTAG5) compatible with the IEEE-1149.1 standard. It can be integrated with existing JTAG components or independent JTAG controllers.

The debug interface provides the following features:

- Supports debug by using standard JTAG interfaces.
- Supports synchronous and asynchronous debug, enabling the CPU to enter the debug mode in extreme conditions.
- Supports software breakpoints.
- Supports multiple memory breakpoints.
- Enables you to check and set the values of CPU registers.
- Enables you to check and modify memory values.
- Enables the CPU to run an instruction in a single step or multiple steps.
- Enables you to quickly download programs.
- Enables the CPU to enter the debug mode after it is reset.



#### Chapter 10. Debug

Debug of C910 is jointly completed by the debug software, debug proxy, debugger, and debug interface. The location of the debug interface in the CPU debug environment is shown in Fig. 10.1 . The debug software is connected to the debug proxy over network. The debug proxy is connected to the debugger through a USB interface. The debugger communicates with the debug interface in JTAG mode.



Fig. 10.1: Location of the debug interface in CPU debug environment

# 10.2 Connection between the debug unit and CPU cores

C910MP adopts a multi-core single-port debug framework. It accesses the HAD unit of each core through a shared JTAG interface, and triggers the core to enter or exit the debug mode and access CPU resources. You can set the CORESEL field in the hacr register through the JTAG interface to specify a target core, and then configure HAD registers of the target core.

In the multi-core debug framework, when a core enters the debug mode, another one or more cores must also enter the debug mode; and when a core exits the debug mode, other one or more cores must also exit the debug mode. Therefore, C910MP provides a unified event transmission module (ETM) to transmit debug events, including debug entry and exit events, between multiple cores. When a core receives a debug command from the ICE, it generates a debug entry or exit event and sends the event to the ETM. The ETM forwards the event to other cores to enable multiple cores to synchronously enter or exit the debug mode. The multi-core debug framework (with two cores) of C910 is shown in Fig. 10.2.

#### • Multiple cores enter the debug mode

When a core enters the debug mode, it generates a DBG\_ENT signal. The EVENT\_OUTEN register of the core determines whether the DBG\_ENT signal can be sent to the ETM. When the EVENT\_OUTEN register is enabled, the DBG\_ENT signal is transmitted to other cores through the ETM. Then the EVENT\_INEN registers of other cores determine whether the cores





Fig. 10.2: Multi-core debug framework

can enter the debug mode.

#### • Multiple cores exit the debug mode

When a core exits the debug mode, it generates a DBG\_EXIT signal. The EVENT\_OUTEN register of the core determines whether the DBG\_EXIT signal can be sent to the ETM. When the EVENT\_OUTEN register is enabled, the DBG\_EXIT signal is transmitted to other cores through the ETM. Then the EVENT\_INEN registers of the other cores determine whether the cores can exit the debug mode.

# **10.3 Debug interface signals**

External interface signals of the debug unit include JTAG interface signals and debug interface signals. Table 10.1 describes the debug interface signals.

Signal name	Direction
corex_pad_halted	Output
pad_corex_dbgrq_b	Input
corex_pad_jdb_pm[1:0]	Output
pad_corex_dbg_mask	Input
pad_had_jtg_tclk	Input
pad_had_jtg_trst_b	Input
pad_had_jtg_tdi	Input
had_pad_jtg_tdo	Output
had_pad_jtg_tdo_en	Output
pad_had_jtg_tms	Input

Table 10.1: External interface signals of the debug unit

#### corex\_pad\_halted



A high level indicates that the corresponding core is in debug mode.

#### $pad\_corex\_dbgrq\_b$

This signal is used to request multiple cores to synchronously enter the debug mode. It is valid at a low level. This signal is an external input signal of the core. It is synchronized by the system clock in the core and then transmitted to the HAD unit. The HAD unit uses this signal to request multiple cores to synchronously enter the debug mode. Setting the signal to 0 is equivalent to setting the DR bit in the hcr register of the HAD unit.

#### corex\_pad\_jdb\_pm[1:0]

This signal indicates the current operating mode of the corresponding core. You can determine whether the CPU has entered the debug mode based on this signal. For more information, see Current\_CPU\_status\_PM.

had_pad_jdb_pm[1:0]	Description
00	Common mode
01	Low power mode
10	Debug mode
11	Reserved

Table 10.2: Current CPU status indicated by PM :name: Current\_CPU\_status\_PM

#### $pad\_corex\_dbg\_mask$

A debug request masking signal driven by the SoC. It is used to mask debug requests for core x. This signal must be set to a high level in a power-off process.

#### pad\_had\_jtg\_tclk

A JTAG clock signal. This signal is an external input signal and is usually generated by the debugger. To ensure proper functioning between the debug unit and cores, the frequency of this signal must be lower than 1/2 that of the CPU clock signal.

#### pad\_had\_jtg\_trst\_b

A JTAG reset signal. It is used to reset the TAP state machine and other related control signals.

#### JTAG5 signals

- pad\_had\_jtg\_tdi: A JTAG serial input signal of the HAD unit. The HAD unit performs sampling on this signal at the rising edge of JTAG TCLK, and the debugger sets this signal at the falling edge of JTAG TCLK.
- pad\_had\_jtg\_tms: A JTAG mode selection signal. This signal is initiated by the debugger to control operation of the TAP state machine in the HAD unit.



- had\_pad\_jtg\_tdo: A JTAG serial output signal of the HAD unit. The HAD unit sets this signal at the falling edge of JTAG TCLK, and the debugger performs sampling on this signal at the rising edge of JTAG TCLK.
- had\_pad\_jtg\_tdo\_en: A signal indicating that the had\_pad\_jtg\_tdo signal is valid. The debugger usually monitors this signal to determine whether the had\_pad\_jtg\_tdo signal is valid. Alternatively, the debugger can read the state of the TAP state machine in the debugger to determine whether to perform sampling on the had\_pad\_jtg\_tdo signal. This signal is mainly used to determine the JTAG pin that generates output when multiple TAP state machines are implemented.

# Chapter 11

# Power Management

C910 supports various power management features, including the support for multiple power domains, poweroff of a single core, power-off of the cluster, and clearing of the L2 cache from external hardware interfaces. This chapter describes the power management features of C910 in detail.

# 11.1 Power domain

C910 can be divided into a maximum of three power domains.

Each core is a power domain, including the computing unit, control logic, and cache RAM of the core.

The L2 subsystem (also called top level) is a power domain, including the CIU, L2 Cache, Debug, PLIC, CLINT, and SYSIO submodules.

# 11.2 Overview of low-power modes

C910 supports the following low-power modes:

- Normal mode: The cores and L2 are running properly.
- Core WFI mode: Some cores are in the wait for interrupt (WFI) mode.
- Individual-core power-off: Some cores are powered off.
- Cluster power-off: The entire cluster, including the cores and L2, is powered off.



# 11.3 Core WFI process

By executing the WFI low power instruction, a core enters WFI mode and outputs signal  $core(x)_pad_lpmd_b[1:0]=2$ ' b00, which indicates that the core has entered WFI mode. The L2 subsystem will disable the global ICG of this core inside the cluster.

The core will be woken up and exit WFI mode upon the occurrence of the following events:

- Reset
- Interrupt request: external interrupt, software interrupt, or timer interrupt requests sent by the PLIC or CLINT submodules.
- Debug request

When one of the following events occurs, the core is temporarily woken up to process the event. It reenters low power mode after the event is processed. The core does not exit WFI mode during the entire process.

• Snoop request: Snoop requests sent by other cores.

# 11.4 Individual-core power-off process

The system can shut down the power of a core to completely terminate the static power of the core.

The process for powering off a core:

- Notifies SoC that the individual-core power-off process is to be executed. The implementation of this step is subject to the SoC design.
- Masks all interrupt requests, including external interrupts, software interrupts, and timer interrupts, and then disables the interrupt enable bit (MIE/SIE) of the mstatus/status register and the interrupt enable bit of the mie/sie register. If the power-off process is executed in M-mode, the interrupt enable bits of the mstatus and mie registers are disabled. If the power-off process is executed in S-mode, the interrupt bits of the status and sie registers are disabled.
- Disables data prefetch
- Executes D-Cache INV&CLR ALL to write dirty lines back to the L2 cache.
- Disables D-Cache (no store instruction allowed between the clear cache and disable cache operations).
- Disables the SMPEN bit to mask snoop requests.
- Executes the fence iorw, iorw instruction.
- Executes the WFI instruction to enter WFI mode.
- The system performs the following operations:
- Detects a valid low-power output signal core(x)\_pad\_lpmd\_b sent from the core.



- Sets pad\_core(x)\_dbg\_mask to 1 to mask debug requests bound for the core to be powered off.
- Activates the output signal clamp bit of the core to be powered off.
- Sets the reset signal pad\_core(x)\_rst\_b to 0 for the core to be powered off.
- Shuts down the power to the core.
- A powered-off core can restart only by reset. The process of powering on a core again:
- The system detects a specific event and determines to wake up the core.
- The system sets the reset address of the core.
- The reset signal of the core is set to 0.
- The power is turned on and the reset signal remains unreleased.
- The output signal clamp bit of the core is released.
- The reset signal of the core is released.
- The core executes the initialization program, enables the SMPEN bit, or performs initialization operations, such as enabling the MMU or D-Cache.

# 11.5 Cluster power-off process (hardware clearing of the L2 cache)

Ensure that the power is shut down for all cores except the main core in the cluster. The main core is the last core to be powered off. It can be either of the two cores.

The main core performs the following operations:

- Notifies SoC that the cluster power-off process is to be executed. The implementation is subject to the SoC design.
- Masks all interrupt requests, including external interrupts, software interrupts, and timer interrupts, and then disables the interrupt enable bit (MIE/SIE) of the mstatus/status register and the interrupt enable bit of the mie/sie register.
- Disables data prefetch
- Executes the D-Cache INV&CLR ALL operation.
- Disables D-Cache (no store instruction allowed between the clear cache and disable cache operations).
- Disables the SMPEN bit.
- Executes the fence iorw, iorw instruction.
- Executes the WFI instruction to enter WFI mode.

The system performs the following operations:

• Detects a valid low-power output signal core(x)\_pad\_lpmd\_b sent from the main core.



- Sets pad\_core(x)\_dbg\_mask to 1 to mask debug requests bound for the main core.
- Activates the output signal clamp bit of the main core.
- Sets the reset signal pad\_core(x)\_rst\_b to 0 for the main core.
- Shuts down the power of the main core.
- Sets pad\_cpu\_l2cache\_flush\_req to 1 to start clearing the L2 cache.
- Waits for C910 to return cpu\_pad\_l2cache\_flush\_done=1.
- Sets pad\_cpu\_l2cache\_flush\_req to 0. (Then C910 will set cpu\_pad\_l2cache\_flush\_done to 0.)
- Waits for C910 to return cpu\_pad\_no\_op=1.
- Activates the output signal clamp bit of the L2 subsystem.
- Sets the reset signal pad\_cpu\_rst\_b of the L2 cache to 0.
- Shuts down the power of the L2 subsystem.

The cluster is powered on again by reset. The process of powering on the cluster again:

- The reset signal is set to 0 for all cores and the L2 subsystem in the cluster.
- The power is turned on, the reset signal remains unreleased, and the PLL is stable.
- The output signal clamp bits of the cores and the L2 subsystem are released.
- The reset signals of the cores and the L2 subsystem are released.
- The reset exception service program is executed to recover the CPU.

# 11.6 Cluster power-off process (software clearing of the L2 cache)

Ensure that the power is shut down for all cores except the main core in the cluster. In this scenario, it is recommended that SoC distinguishes the main core and secondary core. Core 0 can function as the main core.

The main core performs the following operations:

- Notifies SoC that the cluster power-off process is to be executed. The implementation is subject to the SoC design.
- Masks all interrupt requests, including external interrupts, software interrupts, and timer interrupts, and then disables the interrupt enable bit (MIE/SIE) of the mstatus/status register and the interrupt enable bit of the mie/sie register.
- Disables data prefetch
- Executes the D-Cache INV&CLR ALL operation.
- Disables D-Cache (no store instruction allowed between the clear cache and disable cache operations).



- Disables the SMPEN bit.
- Executes the fence iorw, iorw instruction.
- Executes the CLR & INV L2 Cache operation.
- Executes the fence iorw, iorw instruction.
- Executes the WFI instruction to enter WFI mode.

The system performs the following operations:

- Detects a valid low-power output signal core(x)\_pad\_lpmd\_b sent from the main core.
- Sets  $pad\_core(x)\_dbg\_mask$  to 1 to mask debug requests bound for the main core.
- Activates the output signal clamp bit of the main core.
- Sets the reset signal pad\_core(x)\_rst\_b to 0 for the main core.
- Shuts down the power of the main core.
- Waits for C910 to return cpu\_pad\_no\_op=1.
- Activates the output signal clamp bit of the L2 subsystem.
- Sets the reset signal pad\_cpu\_rst\_b of the L2 cache to 0.
- Shuts down the power of the L2 subsystem.

# 11.7 Simplified scenario: overall cluster power-off process (hardware clearing of the L2 cache)

In some systems, SoC designers may take a simple way to divide power domains. That is, take the entire C910 cluster (two cores and one L2 subsystem) as a power domain and power off the cluster as a whole, instead of powering off each core separately. The cluster can be powered off (hardware clearing of the L2 cache) through the following steps:

The system performs the following operations:

• Notifies SoC that the overall cluster power-off process is to be executed. The implementation is subject to the SoC design.

The core (no need to distinguish the main core and secondary core, as the process is the same for them) performs the following operations:

- Masks all interrupt requests including external interrupts, software interrupts, and timer interrupts, and disables the interrupt enable bit (MIE/SIE) of the mstatus/sstatus register, as well as the interrupt enable bit of the mie/sie register.
- Disables data prefetch
- Executes INV&CLR D-Cache ALL to write dirty lines back to the L2 cache.



- Disables D-Cache (no store instruction allowed between the clear cache and disable cache operations).
- Disables the SMPEN bit to mask snoop requests.
- Executes the fence iorw, iorw instruction.
- Executes the WFI instruction.

The system performs the following operations:

- Waits for core(x)\_pad\_lpmd\_b[1:0]==2' b00, which means all CPU cores enter the low power state.
- Sets pad\_core(x)\_dbg\_mask to 1 for all cores to mask debug requests.
- Sets pad\_cpu\_l2cache\_flush\_req to 1 to start hardware clearing for the L2 cache.
- Waits for C910 to return cpu\_pad\_l2cache\_flush\_done=1, which means the L2 cache is cleared.
- Sets pad\_cpu\_l2cache\_flush\_req to 0. (Then, C910 will set cpu\_pad\_l2cache\_flush\_done to 0.)
- Waits for cpu\_pad\_no\_op==1' b1, which means the L2 cache enters the idle state. (All CPU cores are still in the low power state.)
- Activates the output signal clamp of the cluster.
- Asserts all reset signals.
- Powers off the entire cluster.

# 11.8 Simplified scenario: overall cluster power-off process (software clearing of the L2 cache)

The simple power domain division also applies. That is, the entire C910 cluster (two cores and the L2 subsystem) is taken as a power domain and is powered off as a whole. The cluster can be powered off (software clearing of the L2 cache) through the following steps:

The system performs the following operations:

• Notifies SoC that the overall cluster power-off process is to be executed. The implementation is subject to the SoC design.

The secondary core (for example, CPU1) performs the following operations:

- Masks all interrupt requests including external interrupts, software interrupts, and timer interrupts, and disables the interrupt enable bit (MIE/SIE) of the mstatus/sstatus register, as well as the interrupt enable bit of the mie/sie register.
- Disables data prefetch
- Executes INV&CLR D-Cache ALL to write dirty lines back to the L2 cache.
- Disables D-Cache (no store instruction allowed between the clear cache and disable cache operations).



- Disables the SMPEN bit to mask snoop requests.
- Executes the fence iorw, iorw instruction.
- Executes the WFI instruction.

The main core (for example, CPU0) performs the following operations:

- Masks all interrupt requests including external interrupts, software interrupts, and timer interrupts, and disables the interrupt enable bit (MIE/SIE) of the mstatus/sstatus register, as well as the interrupt enable bit of the mie/sie register.
- Disables data prefetch
- Executes INV&CLR D-Cache ALL to write dirty lines back to the L2 cache.
- Disables D-Cache (no store instruction allowed between the clear cache and disable cache operations).
- Disables the SMPEN bit to mask snoop requests.
- Executes the fence iorw, iorw instruction.
- Waits for all secondary cores to enter WFI mode. (The implementation is subject to the SoC design.)
- Executes INV&CLR L2 Cache ALL to clear the L2 cache.
- Executes the fence iorw, iorw instruction.
- Executes the WFI instruction.

The system performs the following operations:

- Waits for core(x)\_pad\_lpmd\_b[1:0]==2' b00 and cpu\_pad\_no\_op==1' b1, which means all CPU cores enter the low power state and the L2 cache enters the idle state.
- Sets pad\_core(x)\_dbg\_mask to 1 for all cores to mask debug requests.
- Activates the output signal clamp of the cluster.
- Asserts all reset signals.
- Powers off the entire cluster.

# 11.9 Low power consumption related programming models and interface signals

#### **11.9.1** Programming models

#### M-mode snoop enable register (MSMPR)

This register is 64 bits wide. Only bit [0] has a definition (=SMPEN) and its default value is 0. This register controls whether cores can accept snoop requests.

- When MSMPR.SMPEN is 0, the cores cannot process snoop requests, and the L2 subsystem masks snoop requests bound for the cores.
- When MSMPR.SMPEN is 1, the cores can process snoop requests, and the L2 subsystem sends snoop requests to the cores.

The corresponding SMPEN bit must be set to 0 before a core is powered off. After the core is powered on, SMPEN must be set to 1 before the software enables the D-Cache and MMU. When a core is in normal running mode, its SMPEN bit must be set to 1.

#### M-mode reset vector base address register (mrvbr)

Each core has an mrvbr register for determining the restart address of the core. The access permission for mrvbr registers is MRO. The initial value of the mrvbr register of a core is determined by the hardware signal pad\_core(x)\_rvba[39:0]. Note:  $pad_core(x)_rvba[0]$  is always 0.

## **11.9.2** Interface signals

#### Reset signal control

C910 top level has three reset signals: pad\_core0\_rst\_b, pad\_core1\_rst\_b, and pad\_cpu\_rst\_b. SoC can use the preceding signals to control the reset of Core 0, Core 1, and L2.

C910 communicates with the power management unit of SoC by using the following signals:

- core(x)\_pad\_lpmd\_b: Indicates whether a core is in WFI mode. 2' b11 indicates normal mode, and
   2' b00 indicates WFI mode.
- cpu\_pad\_no\_op: Indicates whether the L2 cache is idle. This signal is valid (a high level) when all cores enter low power mode and the L2 cache finishes all transmissions.
- pad\_cpu\_l2cache\_flush\_req and cpu\_pad\_l2cache\_flush\_done: Clear the L2 cache under the control of SoC. These signals are used in the cluster power-off process. The req signal is driven by SoC, and the done signal is driven by C910. First, SoC sets the req signal to 1 to start the L2 cache clearing process > C910 finishes clearing the L2 cache and returns done=1 > SoC sets the req signal to 0 > C910 sets the done signal to 0.

# Chapter 12

# Performance Monitoring Unit

# 12.1 PMU overview

The performance monitoring unit (PMU) of C910 complies with the RISC-V standard and collects software and hardware information during a program operation for software developers to optimize their programs.

The software and hardware information collected by the PMU includes the following:

- Number of running clocks and the time
- Instruction statistics
- Statistics of key components of the CPU

# 12.2 PMU programming model

#### 12.2.1 PMU functions

Basic functions of the PMU are:

- Prohibits the counting of all events by using the mcountinhibit register.
- Resets the PMU counters, including mcycle, minstret, and mhpmcounter3 to mhpmcounter31.
- Configures the corresponding events for each PMU counter. In C910, the mappings between events and counters are fixed. Therefore, events must be configured for the PMU counters based on a fixed pattern. For example, 0x1 must be written to mhpmevent3, which means that mhpmcounter3 counts

the number of 0x1 events (L1 ICache access count), and 0x2 must be written to mhpmevent4, which means that mhpmevent4 counts the number of 0x2 events (L1 ICache miss count), and so forth.

- Grants access permissions. The mounteren register determines whether PMU counters can be accessed in S-mode, and scounteren determines whether PMU counters can be accessed in U-mode.
- Discharges the prohibition by using the mcountinhibit register and starts counting.

For more information, see *PMU setting example*.

# 12.2.2 PMU event overflow interrupt

C910 implements the M-mode event overflow mark register (mcounteren) and M-mode event interrupt enable register (mcounteren). For more information about register functions and read/write permissions, see appendix C-1 M-mode control register. In the mcounteren register, the bits and event counters are in oneto-one correspondence, indicating whether the event counters overflow. In the mcounteren register, the bits and event counters are in one-to-one correspondence, indicating whether to initiate an interrupt request when an event counter overflows.

The unified interrupt vector number of overflow interrupts initiated by the PMU is 17. The interrupt enabling and processing process is the same as that of common interrupts. For more information, see *Exceptions and Interrupts*.

# 12.3 PMU related control registers

#### 12.3.1 M-mode counter access enable register (mcounteren)

The mounteren register determines whether U-mode counters can be accessed in S-mode.



M-mode counter access enable register (mcounteren)



Table 12.1: Description of the M-mode counter access enable register

Bit	Read/Write Name	Description
31:3	Read/Write HPMn	The access bit of the hpmcounter $n$ register in S-mode.
		0: An illegal instruction exception will occur for accesses to the
		hpmcounter <i>n</i> register in S-mode.
		1: The hpmcounter $n$ register can be normally accessed in S-mode.
2	Read/Write IR	The access bit of the minstret register in S-mode.
		0: An instruction exception will occur for accesses to the minstret
		register in S-mode.
		1: The minstret register can be normally accessed in S-mode.
1	Read/Write TM	The access bit of the time register in S-mode.
		0: An illegal instruction exception will occur for accesses to the
		time register in S-mode.
		1: When the corresponding bit of the mounteren register is 1, the
		time register can be normally accessed in S-mode. Otherwise, an
		illegal instruction exception will occur.
0	Read/Write CY	The ccess bit of the mcycle register in S-mode.
		0: An illegal instruction exception will occur for accesses to the
		cycle register in S-mode.
		1: The cycle register can be normally accessed in S-mode.

# 12.3.2 S-mode counter access enable register (scounteren)

The scounteren register determines whether U-mode counters can be accessed in U-mode.



S-mode counter access enable register (scounteren)



Bit	Read/Write Name	Description
31:3	Read/Write $HPMn$	The access bit of the hpmcounter $n$ register in U-mode.
		0: An illegal instruction exception will occur for accesses to the
		hpmcounter n register in U-mode.
		1: When the corresponding bit of the mounteren register is 1, the
		hpmcounter register can be normally accessed in U-mode. Other-
		wise, an illegal instruction exception will occur.
2	Read/Write IR	The access bit of the instret register in U-mode.
		0: An illegal instruction exception will occur for accesses to the
		instret register in U-mode.
		1: When the corresponding bit of the mounteren register is 1, the
		instret register can be normally accessed in U-mode. Otherwise,
		an illegal instruction exception will occur.
1	Read/Write TM	The access bit of the time register in U-mode.
		0: An illegal instruction exception will occur for accesses to the
		time register in U-mode.
		1: When the corresponding bit of the mounteren register is 1, the
		time register can be normally accessed in U-mode. Otherwise, an
		illegal instruction exception will occur.
0	Read/Write CY	The access bit of the cycle register in U-mode.
		0: An illegal instruction exception will occur for accesses to the
		cycle register in U-mode.
		1: When the corresponding bit of the mounteren register is 1, the
		cycle register can be normally accessed in U-mode. Otherwise, an
		illegal instruction exception will occur.

Table 12.2: Description of the scounteren register

# 12.3.3 M-mode count inhibit register (mcountinhibit)

The mountinhibit register inhibits counting of M-mode counters. When performance analysis is not required, counters can be disabled to reduce the power consumption of the CPU.



M-mode count inhibit register (mcountinhibit)



Bit	Read/Write	e Name	Description
31:3	Read/Write	MHPM <i>n</i>	n Count inhibit bit of the mhpmcounter register
			0: normal counting
			1: counting inhibited
2	Read/Write	MIR	Count inhibit bit of the minstret register
			0: normal counting
			1: counting inhibited
1	-	-	-
0	Read/Write	MCY	Count inhibit bit of the mcycle register
			0: normal counting
			1: counting inhibited

Table 12.3: Description of the M-mode count inhibit register

# 12.3.4 S-mode write enable register (mcounterwen)

The mounterwen register determines whether S-mode event counters can be written in S-mode. This register is an M-mode extension register. For the register description, see *Appendix C-1 M-mode control registers*.

# 12.3.5 Performance monitoring event select register (mhpmevent3-31)

The mhpmevent3-31 register selects the counting event corresponding to a counter. In C910, a counter corresponds to an event, which cannot be modified. Therefore, only the corresponding event ID can be written to each event selector. An event counter performs counting normally only after the index value of the corresponding event is written to the event selector, and the event counter is initialized by using the csrw instruction.



M-mode performance monitoring event select register (mhpmevent)

Table 12.4 describes the M-mode performance monitoring event select register.



Table 12.4: Description of the M-mode performance monitoringevent select register

Bit	Read/Writ	e Name	Description
63:0	Read/Write	Event in-	Performance monitoring event index
		dex	0: no event
			0x1 to 0x1A: performance monitoring events implemented by hard-
			ware. For more information, see: numref: Counter_event_list.
			>0x1A: performance monitoring events that are not defined by
			hardware. These events are customized for use by the software.

Table 12.5 describes the correspondence between event selectors, events, and counters.





Event selector	Index	Event	Counter
mhpmevent3	0x1	L1 ICache Access Counter	mhpmcounter3
mhpmevent4	0x2	L1 ICache Miss Counter	mhpmcounter4
mhpmevent5	0x3	I-UTLB Miss Counter	mhpmcounter5
mhpmevent6	0x4	D-UTLB Miss Counter	mhpmcounter6
mhpmevent7	0x5	JTLB Miss Counter	mhpmcounter7
mhpmevent8	0x6	Conditional Branch Mispredict Counter	mhpmcounter8
mhpmevent9	0x7	Reserved	mhpmcounter9
mhpmevent10	0x8	Indirect Branch Mispredict Counter	mhpmcounter10
mhpmevent11	0x9	Indirect Branch Instruction Counter	mhpmcounter11
mhpmevent12	0xA	LSU Spec Fail Counter	mhpmcounter12
mhpmevent13	0xB	Store Instruction Counter	mhpmcounter13
mhpmevent14	0xC	L1 DCache Read Access Counter	mhpmcounter14
mhpmevent15	0xD	L1 DCache Read Miss Counter	mhpmcounter15
mhpmevent16	0xE	L1 DCache Write Access Counter	mhpmcounter16
mhpmevent17	0xF	L1 DCache Write Miss Counter	mhpmcounter17
mhpmevent18	0x10	L2 Cache Read Access Counter	mhpmcounter18
mhpmevent19	0x11	L2 Cache Read Miss Counter	mhpmcounter19
mhpmevent20	0x12	L2 Cache Write Access Counter	mhpmcounter20
mhpmevent21	0x13	L2 Cache Write Miss Counter	mhpmcounter21
mhpmevent22	0x14	RF Launch Fail Counter	mhpmcounter22
mhpmevent23	0x15	RF Reg Launch Fail Counter	mhpmcounter23
mhpmevent24	0x16	RF Instruction Counter	mhpmcounter24
mhpmevent25	0x17	LSU Cross 4K Stall Counter	mhpmcounter25
mhpmevent26	0x18	LSU Other Stall Counter	mhpmcounter26
mhpmevent27	0x19	LSU SQ Discard Counter	mhpmcounter27
mhpmevent28	0x1A	LSU SQ Data Discard Counter	mhpmcounter28
mhpmevent29 31	>=	Not Defined	mhpmcounter29~31
	0x1B		

Table 12.5: List of correspondence between counters and events

# 12.3.6 Event counters

Event counters are divided into three groups: M-mode event counters, U-mode event counters, and S-mode event counters (extended in C910). For more information, see: numref:mac\_counter\_list.



Name	Index	Read/Write	Initial value	Description
MCYCLE	0xB00	MRW	0x0	The cycle counter.
MINSTRET	0xB02	MRW	0x0	The instructions-retired counter.
MHPMCOUNTER3	0xB03	MRW	0x0	A performance-monitoring counter.
MHPMCOUNTER4	0xB04	MRW	0x0	A performance-monitoring counter.
MHPMCOUNTER31	0xB1F	MRW	0x0	A performance-monitoring counter.

Table 12.6: M-mode event counter list

Table 12.7 lists the U-mode event counters.

Name	Index	Read/Write	Initial value	Description
CYCLE	0xC00	URO	0x0	The cycle counter.
TIME	0xC01	URO	0x0	The timer.
INSTRET	0xC02	URO	0x0	The instructions-retired counter.
HPMCOUNTER3	0xC03	URO	0x0	A performance-monitoring counter.
HPMCOUNTER4	0xC04	URO	0x0	A performance-monitoring counter.
HPMCOUNTER31	0xC1F	URO	0x0	A performance-monitoring counter.

Table 12.7: U-mode event counter list

Table 12.8: S-mode event counter list

Name	Index	Read/Write	Initial value	Description
SCYCLE	0x5E0	SRO	0x0	The cycle counter.
SINSTRET	0x5E2	SRO	0x0	The instructions-retired counter.
SHPMCOUNTER3	0x5E3	SRO	0x0	A performance-monitoring counter.
SHPMCOUNTER4	0x5E4	SRO	0x0	A performance-monitoring counter.
SHPMCOUNTER31	0x5FF	SRO	0x0	A performance-monitoring counter.

The U-mode CYCLE, INSTRET, and HPMCOUNTERn counters are read-only mappings of the corresponding M-mode event counters. The timer is the read-only mapping of the MTIME register. The S-mode SCYCLE, SINSTRET, and SHPMCOUNTERn counters are mappings of corresponding M-mode event counters.

# CHAPTER 13

# **Program Examples**

This chapter describes various program examples, including the MMU setting example, PMP setting example, cache setting example, multi-core startup example, synchronization primitive example, PLIC setting example, and PMU setting example.

# 13.1 Optimal CPU performance configuration

The optimal performance of C910 can be achieved by using the following configurations:

- MHCR = 0x11ff
- MHINT = 0x6e30c
- MCCR2 = 0xe0000009 (Note: MCCR2 contains RAM delay settings. In this example, all delays are 0. Customers need to set a proper RAM delay based on the actual situation.)
- MXSTATUS = 0x638000
- MSMPR = 0x1

```
# mhcr
li x3, 0x11ff
csrs mhcr,x3
#mhint
li x3, 0x6e30c
```

(continues on next page)


```
csrs mhint,x3
# mxstatus
li x3, 0x638000
csrs mxstatus,x3
# msmpr
csrsi msmpr,0x1
# mccr2
li x3, 0xe0000009
csrs mccr2,x3
```

## 13.2 MMU setting example

```
* Function: An example of setting C910MP MMU.
* Memory space: Virtual address <-> physical address.
*
* Pagesize 4K: vpn: {vpn2,vpn1,vpn0} <-> ppn: {ppn2,ppn1,ppn0}
* Pagesize 2M: vpn: {vpn2,vpn1} <-> ppn:{ppn2,ppn1}
* Pagesize 1G: vpn: {vnp2} <-> ppn: {ppn2}
/*C910 will invalidate all MMU TLB entries automatically when reset*/
 /*You can use sfence.vma to invalid all MMU TLB entries if necessary*/
 sfence.vma x0, x0
 /* Pagesize 4K: vpn: {vpn2, vpn1, vpn0} <-> ppn: {ppn2, ppn1, ppn0}*/
 /* First-level page addr base: PPN (defined in satp)*/
 /* Second-level page addr base: BASE2 (self define)*/
 /* Third-level page addr base: BASE3 (self define)*/
 /* 1. Get first-level page addr base: PPN and vpn*/
 /* Get PPN*/
 csrr x3, satp
 li x4, Oxffffffffff
```



```
and x3, x3, x4
  /*2. Config first-level page*/
 /*First-level page addr: {PPN, vpn2, 3' b0}, first-level page pte:{ 44' b BASE2, 10' b1}
→ */
  /*Get first-level page addr*/
  slli x3, x3, 12
 /*Get vpn2*/
 li x4, VPN
 li x5, 0x7fc0000
 and x4, x4, x5
 srli x4, x4, 15
 and x5, x3, x4
 /*Store pte at first-level page addr*/
 li x6, {44' b BASE2, 10' b1}
  sd x6, 0(x5)
 /*3. Config second-level page*/
  /*Second-level page addr: {BASE2, vpn1, 3' b0}, second-level page pte:{ 44' b BASE3, 10'
b1} */
  /*Get second-level page addr*/
  /* VPN1*/
 li x4, VPN
 li x5, 0x3fe00
 and x4, x4, x5
  srli x4, x4, 9
  /*BASE2*/
 li x5, BASE2
 srli x5, x5, 12
 and x5, x5, x4
  /*Store pte at second-level page addr*
  li x6, {44' b BASE3, 10' b1}
  sd x6, 0(x5)
  /*4. Config third-level page*/
  /*Third-level page addr: {BASE3, vpn0, 3' b0}, third-level page pte:{
 theadflag, ppn2, ppn1, ppn0, 9' b flags,1' b1} */
  /*Get second-level page addr*/
  /* VPNO*/
 li x4, VPN
  li x5, 0x1ff
```



```
and x4, x4, x5
srli x4, x4, 3
/*BASE3*/
li x5, BASE3
srli x5, x5, 12
and x5, x5, x4
/*Store pte at second-level page addr*/
li x6, { theadflag, ppn2, ppn1, ppn0, 9' b flags, 1' b1}
sd x6, 0(x5)
/* Pagesize 2M: vpn: {vpn2, vpn1} <-> ppn: {ppn2, ppn1}*/
/*First-level page addr base: PPN (defined in satp)*/
/*Second-level page addr base: BASE2 (self define)*/
/*1. Get first-level page addr base: PPN and vpn*/
/* Get PPN*/
csrr x3, satp
li x4, 0xffffffffff
and x3, x3, x4
/*2. Config first-level page*/
/*First-level page addr: {PPN, vpn2, 3' b0}, first-level page pte:{ 44' b
BASE2, 10' b1}*/
/*Get first-level page addr*/
slli x3, x3, 12
/*Get vpn2*/
li x4, VPN
li x5, 0x7fc0000
and x4, x4, x5
srli x4, x4, 15
and x5, x3, x4
/*Store pte at first-level page addr*/
li x6, {44' b BASE2, 10' b1}
sd x6, 0(x5)
/*3. Config second-level page*/
/*Second-level page addr: {BASE2, vpn1, 3' b0}, second-level page pte:{
theadflag, ppn2, ppn1, 9' b0, 9' b flags,1' b1} */
/*Get second-level page addr*/
```



```
/*VPN1*/
li x4, VPN
li x5, 0x3fe00
and x4, x4, x5
srli x4, x4, 9
/*BASE2*/
li x5, BASE2
srli x5, x5, 12
and x5, x5, x4
/*Store pte at second-level page addr*/
li x6, { theadflag, ppn2, ppn1, 9' b0, 9' b flags,1' b1}
sd x6, 0(x5)
/* Pagesize 1G: vpn: {vpn2} <-> ppn: {ppn2}*/
/*First-level page addr base: PPN (defined in satp)*/
/*1. Get first-level page addr base: PPN and vpn*/
/* Get PPN*/
csrr x3, satp
li x4, Oxffffffffff
and x3, x3, x4
/*2. Config first-level page*/
/*First-level page addr: {PPN, vpn2, 3' b0}, first-level page pte:{
theadflag, ppn2, 9' b0, 9' b0, 9' b flags,1' b1}*/
/*Get first-level page addr*/
slli x3, x3, 12
/*Get vpn2*/
li x4, VPN
li x5, 0x7fc0000
and x4, x4, x5
srli x4, x4, 15
and x5, x3, x4
/*Store pte at first-level page addr*/
li x6, { theadflag, ppn2, 9' b0, 9' b0, 9' b flags,1' b1}
sd x6, 0(x5)
```



## 13.3 PMP setting example

```
* Function: An example of setting C910MP PMP.
* 0x0 ~ 0xf000000, TOR mode, RWX
* 0xf0000000 ~ 0xf8000000, NAPOT mode, RW
* Oxfff73000 ~ Oxfff74000, NAPOT mode, RW
* Oxfffc0000 ~ Oxfffc2000, NAPOT mode, RW
*Different execution permissions are configured for the preceding four regions. PMP must
\rightarrow be configured to prevent the CPU from executing instructions to unsupported address
→regions in different modes, especially in M-mode where the CPU has full execution
→permissions by default. Specifically, after you configure address regions that require
\rightarrow execution permissions, no permission should be configured for the rest address regions.
\hookrightarrow For more information, see the following example.
# pmpaddr0,0x0 0xf0000000, TOR mode, read and write permissions
 li x3, (0xf0000000 >> 2)
 csrw pmpaddr0, x3
 # pmpaddr1,0xf0000000 0xf8000000, NAPOT mode, read and write permissions
 li x3, ( 0xf0000000 >> 2 | (0x8000000-1) >> 3))
 csrw pmpaddr1, x3
 # pmpaddr2,0xfff73000 0xfff74000, NAPOT mode, read and write permissions
 li x3, ( 0xfff73000 >> 2 | (0x1000-1) >> 3))
 csrw pmpaddr2, x3
 # pmpaddr3,0xfffc0000 0xfffc2000, NAPOT mode, read and write permissions
 li x3, ( 0xfffc0000 >> 2 | (0x2000-1) >> 3))
 csrw pmpaddr3, x3
 # pmpaddr4,0xf0000000 0x100000000, NAPOT mode, no permissions
 li x3, ( 0xf0000000 >> 2 | (0x1000000-1) >> 3))
 csrw pmpaddr4, x3
 # pmpaddr5,0x10000000 0xfffffffff, TOR mode, no permissions
 li x3, (0xfffffffff >> 2)
 csrw pmpaddr5, x3
 # PMPCFG0 configures the execution permission, mode, and lock bit of entries.
 When lock is 1, it is valid only in M-mode.
 li x3,0x88989b9b9b8f
 csrw pmpcfg0, x3
 # pmpaddr5,0x1000000000xfffffffff: In TOR mode, when 0x100000000 <= addr <</pre>
 Oxfffffffff, pmpaddr5 will be hit. However, pmpaddr5 cannot be hit in the address
 range Oxffffff000
                                                                    (continues on next page)
```



Oxfffffffff (the minimum PMP granularity is 4 KB in C910). An NAPOT entry must be  $\rightarrow$  configured to mask the last 4 KB space of a 1 TB space.

## **13.4 Cache examples**

## 13.4.1 Cache enabling example

```
/*C910 will invalidate all I-cache automatically when reset*/
/*You can invalidate I-cache by yourself if necessary*/
/*Invalidate I-cache*/
li x3, 0x33
csrc mcor, x3
li x3, 0x11
csrs mcor, x3
// You can also use icache instrucitons to replace the invalidate sequence
// if theadisaee is enabled.
//icache.iall
//sync.is
/*Enable I-cache*/
li x3, 0x1
csrs mhcr, x3
/*C910 will invalidate all D-cache automatically when reset*/
/*You can invalidate D-cache by yourself if necessary*/
/*Invalidate D-cache*/
li x3, 0x33
csrc mcor, x3
li x3, 0x12
csrs mcor, x3
// You can also use dcache instrucitons to replace the invalidate sequence
// if theadisaee is enabled.
// dcache.iall
// sync.is
/*Enable D-cache*/
li x3, 0x2
```



csrs mhcr, x3

```
/*C910 will invalidate all L2 cache automatically when reset*/
/*You can invalidate L2 by yourself if necessary*/
/*Invalidate L2-cache if theadisaee is enabled*/
l2cache.iall
sync.is
/*Enable L2-cache*/
li x3, 8
csrs mccr2, x3
```

## 13.4.2 Example of synchronization between the instruction and data caches

CPU0

sd x3,0(x4) // a new instruction defined in x3
// is stored to program memory address defined in x4.
dcache.cval1 r0 // clean the new instrcution to the shared L2 cache.
sync.s // ensure completion of clean operation.
<pre>// the dcache clean is not necessarily if INSDE is not enabled.</pre>
icache.iva r0 // invalid icache according to shareable configuraiton.
<pre>sync.s/fence.i // ensure completion in all CPUs.</pre>
sd x5,0(x6) // set flag to signal operation completion.
sync.is
jr x4 // jmp to new code

#### CPU1 CPU3

## 13.4.3 Example of synchronization between the TLB and the data cache

CPU0

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## 13.5 Synchronization primitive examples

CPU0

```
li x1, 0x1
li x6, 0x0
ACQUIRE_LOCK: // (x3) is the lock address. 0: Free; 1: Busy.
lr x4, 0(x3) // Read lock
bnez x4, ACQUIRE_LOCK // Try again if the lock is in use
sc x5, x1, 0(x3) // Attempt to store new value
bne x6, x5, ACQUIRE_LOCK // Try again if fail
sync.s
... // Critical section code
```

CPU1

sync.s/fence.i // Ensure all operations are observed before clearing the lock. sd x0, 0(x3) // Clear the lock.

## **13.6 PLIC** setting example

```
//Init id 1 machine mode int for hart 0
/*1. Set hart threshold if needed*/
li x3, (plic_base_addr + 0x200000) // h0 mthreshold addr
li x4, 0xa //threshold value
sw x4,0x0(x3) // set hart0 threshold as 0xa
/*2. Set priority for int id 1*/
li x3, (plic_base_addr + 0x0) // int id 1 prio addr
li x4, 0x1f // prio value
```



```
sw x4,0x4(x3) // init id1 priority as 0x1f
/*3. Enable m-mode int id1 to hart*/
li x3, (plic_base_addr + 0x2000) // h0 mie0 addr
li x4, 0x2
sw x4,0x0(x3) // enable int id1 to hart0
/*4. Set ip or wait external int*/
/*following code set ip*/
li x3, (plic_base_addr + 0x1000) // h0 mthreshold addr
li x4, 0x2 // id 1 pending
sw x4, 0x0(x3) // set int id1 pending
/*5. Core enters interrupt handler, read PLIC_CLAIM and get ID*/
/*6. Core takes interrupt*/
/*7. Core needs to clear external interrupt source if LEVEL(not PULSE)
configured, then core writes ID to PLIC_CLAIM and exits interrupt*/
```

## 13.7 PMU setting example

```
/*1. Inhibit counters counting*/
li x3, 0xfffffff
csrw mcountinhibit, x3
/*2. C910 will initial all pmu counters when reset*/
/*you can initial pmu counters manually if necessarily*/
csrw mcycle, x0
csrw minstret, x0
csrw mhpmcounter3, x0
.....
csrw mhpmcounter31, x0
/*3. Configure mhpmevent*/
li x3, 0x1
csrw mhpmevent3, x3 // mhpmcounter3 count event: L1 ICache Access Counter
li x3, 0x2
```



```
csrw mhpmevent4, x3 // mhpmcounter4 count event: L1 ICache Miss Counter
.....
li x3, 0x13
csrw mhpmevent21, x3 // mhpmcounter21 count event: L2 Cache write miss Counter
/*4. Configure mcounteren and scounteren*/
li x3, 0xfffffff
csrw mcounteren, x3 // enable super mode to read hpmcounter
li x3, 0xffffffff
csrw scounteren, x3 // enable user mode to read hpmcounter
/*5. Enable counters to count when you want*/
csrw mcountinhibit, x0
```

## CHAPTER 14

## Appendix A Standard Instructions

C910MP implements the RV64IMAFDC instruction set architecture. The instructions are described in the following sections by instruction set.

## 14.1 Appendix A-1 I instructions

The following describes the RISC-V I instructions implemented by C910. The instructions are sorted in alphabetic order.

The instructions are 32 bits wide by default. However, in specific cases, the system assembles some instructions into 16-bit compressed instructions. For more information about compressed instructions, see *Appendix A-6 C Instructions*.

#### 14.1.1 ADD: a signed add instruction

#### Syntax:

add rd, rs1, rs2

#### **Operation:**

 $rd \gets rs1 + rs2$ 

#### Permission:

Machine mode (M-mode)/Supervisor mode (S-mode)/User mode (U-mode)



Exception:

None

#### Instruction format:

31	25	24 20	19 15	14 12	11 7	6 0
	000000	rs2	rs1	000	rd	0110011

## 14.1.2 ADDI: a signed add immediate instruction

#### Syntax:

addi rd, rs1, imm12

## **Operation:**

 $rd \leftarrow rs1 + sign\_extend(imm12)$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

None

#### Instruction format:

31 20	19 15	14 12	11 7	6 0
imm12[11:0]	rs1	000	rd	0010011

## 14.1.3 ADDIW: a signed add immediate instruction that operates on the lower 32 bits

Syntax:

addiw rd, rs1, imm12

#### **Operation:**

 $tmp[31:0] \leftarrow rs1[31:0] + sign\_extend(imm12)[31:0]$ 

 $rd \leftarrow sign\_extend(tmp[31:0])$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

None

31 20	19 15	14 12	11 7	6 0
imm12[11:0]	rs1	000	rd	0011011

## 14.1.4 ADDW: a signed add instruction that operates on the lower 32 bits

## Syntax:

addw rd, rs1, rs2

#### **Operation:**

 $tmp[31:0] \leftarrow rs1[31:0] + rs2[31:0]$ 

 $rd \leftarrow sign\_extend(tmp[31:0])$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

None

#### Instruction format:

31	25	24 20	19 15	14 12	11 7	6 0
0000000	)	rs2	rs1	000	rd	0111011

## 14.1.5 AND: a bitwise AND instruction

#### Syntax:

and rd, rs1, rs2

#### **Operation:**

 $\rm rd \gets rs1 \ \& \ rs2$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

None

31	25	24	20 19	15	14 12	11 7	6 0
0000000		rs2		rs1	111	rd	0110011



## 14.1.6 ANDI: an immediate bitwise AND instruction

#### Syntax:

andi rd, rs1, imm12

#### **Operation:**

 $rd \leftarrow rs1 \& sign\_extend(imm12)$ 

#### **Permission:**

M mode/S mode/U mode

#### Exception:

None

#### Instruction format:

31 20	19 15	14 12	11 7	6 0
imm12[11:0]	rs1	111	rd	0010011

## 14.1.7 AUIPC: an instruction that adds the immediate in the upper bits to the PC

#### Syntax:

auipc rd, imm20

#### **Operation:**

 $rd \leftarrow current pc + sign\_extend(imm20 << 12)$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

None

#### Instruction format:

31 12	11 7	6 0
imm20[19:0]	rd	0010111

## 14.1.8 BEQ: a branch-if-equal instruction

#### Syntax:

beq rs1, rs2, label

#### **Operation:**



if (rs1 == rs2)

next  $pc = current pc + sign\_extend(imm12 << 1)$ 

else

next pc = current pc + 4

#### **Permission:**

M mode/S mode/U mode

#### Exception:

None

#### Notes:

The compiler calculates immediate 12 based on the label.

The jump range of the instruction is  $\pm 4$  KB address space.

#### Instruction format:



## 14.1.9 BGE: a signed branch-if-greater-than-or-equal instruction

#### Syntax:

bge rs1, rs2, label

#### **Operation:**

if  $(rs1 \ge rs2)$ 

next  $pc = current pc + sign\_extend(imm12 <<1)$ 

else

next pc = current pc + 4

#### Permission:

M mode/S mode/U mode



#### Exception:

None

#### Notes:

The compiler calculates immediate 12 based on the label.

The jump range of the instruction is  $\pm 4$  KB address space.

#### Instruction format:

31	30	25	24	20	19	15	14 1	2 11	1 8	7	6	0
		imm12[9:4]	rs2		rs1		101	ii	mm12[3:0]		1100011	
		-imm12[11]									imm12[10]	

## 14.1.10 BGEU: an unsigned branch-if-greater-than-or-equal instruction

#### Syntax:

bgeu rs1, rs2, label

#### **Operation:**

if  $(rs1 \ge rs2)$ 

next  $pc = current pc + sign\_extend(imm12 << 1)$ 

#### else

next pc = current pc + 4

#### Permission:

M mode/S mode/U mode

#### Exception:

None

#### Notes:

The compiler calculates immediate 12 based on the label.

The jump range of the instruction is  $\pm 4$  KB address space.





## 14.1.11 BLT: a signed branch-if-less-than instruction

#### Syntax:

blt rs1, rs2, label

#### **Operation:**

if (rs1 < rs2)

next  $pc = current pc + sign\_extend(imm12 << 1)$ 

else

next pc = current pc + 4

#### Permission:

M mode/S mode/U mode

#### Exception:

None

#### Notes:

The compiler calculates immediate 12 based on the label.

The jump range of the instruction is  $\pm 4$  KB address space.

#### Instruction format:



## 14.1.12 BLTU: an unsigned branch-if-less-than instruction

#### Syntax:

bltu rs1, rs2, label

#### **Operation:**

if (rs1 < rs2)

next  $pc = current pc + sign\_extend(imm12 << 1)$ 

else

next pc = current pc + 4

#### Permission:

M mode/S mode/U mode



#### Exception:

None

## Notes:

The compiler calculates immediate 12 based on the label.

The jump range of the instruction is  $\pm 4$  KB address space.

#### Instruction format:

31	30	25	24	20	19	15	14 12	11 8	7	6	0
	imm	12[9:4]	rs2		rs1		110	imm12[3:0]		1100011	
	— imm	12[11]							L	-imm12[10]	

## 14.1.13 BNE: a branch-if-not-equal instruction

#### Syntax:

bne rs1, rs2, label

#### **Operation:**

if (rs1 != rs2)

next  $pc = current pc + sign\_extend(imm12 << 1)$ 

#### else

next pc = current pc + 4

#### Permission:

M mode/S mode/U mode

#### Exception:

None

#### Notes:

The compiler calculates immediate 12 based on the label.

The jump range of the instruction is  $\pm 4$  KB address space.





## 14.1.14 CSRRC: a move instruction that clears control registers

#### Syntax:

csrrc rd, csr, rs1

#### **Operation:**

 $\mathrm{rd} \gets \mathrm{csr}$ 

 $csr \leftarrow csr \& (\sim rs1)$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Notes:

Accessible control registers vary under different privileges. For more information, see the descriptions of control registers.

When rs1 = x0, this instruction does not initiate write operations and therefore does not cause writerelated exceptions.

Instruction format:

31 20	19 15	14 12	11 7	6 0
csr	rs1	011	rd	1110011

## 14.1.15 CSRRCI: a move instruction that clears immediates in control registers

#### Syntax:

csrrci rd, csr, imm5

#### **Operation:**

 $\mathrm{rd} \gets \mathrm{csr}$ 

 $csr \leftarrow csr \& \sim zero\_extend(imm5)$ 

#### **Permission:**

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Notes:



Accessible control registers vary under different privileges. For more information, see the descriptions of control registers.

When rs1 = x0, this instruction does not initiate write operations and therefore does not cause writerelated exceptions.

In	struction format:									
	31	20	19	1	51	4 12	1	11 7	6	0
	csr			imm5		111		rd	1110011	

## 14.1.16 CSRRS: a move instruction for setting control registers

#### Syntax:

csrrs rd, csr, rs1

#### **Operation:**

 $\mathrm{rd} \leftarrow \mathrm{csr}$ 

 $\mathrm{csr} \gets \mathrm{csr} \mid \mathrm{rs1}$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Notes:

Accessible control registers vary under different privileges. For more information, see the descriptions of control registers.

When rs1 = x0, this instruction does not initiate write operations and therefore does not cause writerelated exceptions.

#### Instruction format:



## 14.1.17 CSRRSI: a move instruction for setting immediates in control registers

#### Syntax:

csrrsi rd, csr, imm5

#### **Operation:**



 $\mathrm{rd} \gets \mathrm{csr}$ 

 $csr \leftarrow csr \mid zero\_extend(imm5)$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Notes:

Accessible control registers vary under different privileges. For more information, see the descriptions of control registers.

When rs1 = x0, this instruction does not initiate write operations and therefore does not cause writerelated exceptions.

#### Instruction format:

31 2	0 19 15	14 12	11 7	6 0
csr	imm5	110	rd	1110011

## 14.1.18 CSRRW: a move instruction that reads/writes control registers

#### Syntax:

csrrw rd, csr, rs1

#### **Operation:**

 $\mathrm{rd} \gets \mathrm{csr}$ 

 $\mathrm{csr} \gets \mathrm{rs1}$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Notes:

Accessible control registers vary under different privileges. For more information, see the descriptions of control registers.

When rs1 = x0, this instruction does not initiate write operations and therefore does not cause writerelated exceptions.

#### Instruction format:

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## 14.1.19 CSRRWI: a move instruction that reads/writes immediates in control registers

#### Syntax:

csrrwi rd, csr, imm5

#### **Operation:**

 $\mathrm{rd} \gets \mathrm{csr}$ 

 $csr[4:0] \leftarrow imm5$ 

 $\operatorname{csr}[63:5] \leftarrow \operatorname{csr}[63:5]$ 

#### **Permission:**

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Notes:

Accessible control registers vary under different privileges. For more information, see the descriptions of control registers.

When rs1 = x0, this instruction does not initiate write operations and therefore does not cause writerelated exceptions.

#### Instruction format:



## 14.1.20 EBREAK: a breakpoint instruction

#### Syntax:

ebreak

#### **Operation:**

Generates breakpoint exceptions or enables the core to enter the debug mode.

#### Permission:

M mode/S mode/U mode



#### Exception:

Breakpoint exceptions

#### Instruction format:

31	20 19	15 14 12	11 7	6 0
00000000001	00000	000	00000	1110011

## 14.1.21 ECALL: an environment call instruction

#### Syntax:

ecall

#### **Operation:**

Generates environment call exceptions.

#### Permission:

M mode/S mode/U mode

#### Exception:

U-mode, S-mode, and M-mode environment call exceptions

#### Instruction format:

31 2	0 19	15 14 1	2 11 7	6 0
00000000000	00000	000	00000	1110011

## 14.1.22 FENCE: a memory synchronization instruction

#### Syntax:

fence iorw, iorw

#### **Operation:**

Ensures that all memory or device read/write instructions before this instruction are observed earlier than those after this instruction.

#### Permission:

M mode/S mode/U mode

#### Exception:

None

#### Notes:

When the PI and SO bits are both 1, the instruction syntax is fence i,o, and so on.



#### Instruction format:

31	28	27	26	25	24	23	22	21	20	19	15	14	12	11		7	6	0
0000		рі	ро	pr	pw	si	so	sr	sw	00000			000		00000		0001111	

## 14.1.23 FENCE.I: an instruction stream synchronization instruction

#### Syntax:

fence.i

#### **Operation:**

Clears the I-Cache to ensure that the data access results before this instruction can be accessed by fetch operations after the instruction.

#### **Permission:**

M mode/S mode/U mode

#### Exception:

None

#### Instruction format:

31	28	27	24 23	20	19	15	14	12	11		7	6	0
	0000	0000		0000	000	00	(	001		00000		0001111	L

## 14.1.24 JAL: an instruction for directly jumping to a subroutine

#### Syntax:

jal rd, label

#### **Operation:**

next pc  $\leftarrow$  current pc + sign\_extend(imm20<<1)

 $rd \gets current \; pc \, + \, 4$ 

#### **Permission:**

M mode/S mode/U mode

#### Exception:

None

#### Notes:

The compiler calculates immediate 20 based on the label.

The jump range of the instruction is  $\pm 1$  MB address space.





# 14.1.25 JALR: an instruction for jumping to a subroutine by using an address in a register

#### Syntax:

jalr rd, rs1, imm12

**Instruction format:** 

#### **Operation:**

next pc  $\leftarrow$  (rs1 + sign\_extend(imm12)) & 64' hffffffffffff

 $rd \leftarrow current pc + 4$ 

#### **Permission:**

M mode/S mode/U mode

#### **Exception:**

None

#### Notes:

When the CPU runs in M-mode or the MMU is disabled, the jump range of the instruction is the entire 1 TB address space.

When the CPU does not run in M-mode and the MMU is enabled, the jump range of the instruction is the entire 512 GB address space.

#### Instruction format:

31 20	19 15	14 12	11 7	6 0
imm12[11:0]	rs1	000	rd	1100111

## 14.1.26 LB: a sign-extended byte load instruction

#### Syntax:

lb rd, imm12(rs1)

#### **Operation:**

 $address \leftarrow rs1 + sign\_extend(imm12)$ 

```
rd \leftarrow sign\_extend(mem[address])
```



#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on load instructions

#### Instruction format:

31 20	19 15	14 12	11 7	6 0
imm12[11:0]	rs1	000	rd	0000011

## 14.1.27 LBU: an unsign-extended byte load instruction

#### Syntax:

lbu rd, imm12(rs1)

#### **Operation:**

 $address \leftarrow rs1 + sign\_extend(imm12)$ 

 $rd \leftarrow zero\_extend(mem[address])$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on load instructions

#### Instruction format:



## 14.1.28 LD: a doubleword load instruction

#### Syntax:

ld rd, imm12(rs1)

#### **Operation:**

 $address \leftarrow rs1 + sign\_extend(imm12)$ 

 $rd \leftarrow mem[(address+7):address]$ 

#### Permission:

M mode/S mode/U mode



#### Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on load instructions

#### Instruction format:

31	20 19	15 14	12 11	7 6	0
imm12[11:0]	rs1	011	rd		0000011

## 14.1.29 LH: a sign-extended halfword load instruction

#### Syntax:

lh rd, imm12(rs1)

#### **Operation:**

 $address \leftarrow rs1 + sign\_extend(imm12)$ 

 $rd \leftarrow sign\_extend(mem[(address+1):address])$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on load instructions

#### Instruction format:

31	0 19 15	14 12	11 7	6 0
imm12[11:0]	rs1	001	rd	0000011

## 14.1.30 LHU: an unsign-extended halfword load instruction

#### Syntax:

lhu rd, imm12(rs1)

#### **Operation:**

 $address \leftarrow rs1 + sign\_extend(imm12)$ 

 $rd \leftarrow zero\_extend(mem[(address+1):address])$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on load instructions





## 14.1.31 LUI: an instruction for loading the immediate in the upper bits

#### Syntax:

lui rd, imm20

#### **Operation:**

 $rd \leftarrow sign\_extend(imm20 << 12)$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

None

#### Instruction format:

31 12	11 7	6 0
imm20[19:0]	rd	0110111

## 14.1.32 LW: a sign-extended word load instruction

#### Syntax:

lw rd, imm12(rs1)

#### **Operation:**

 $address \leftarrow rs1 + sign\_extend(imm12)$ 

 $rd \leftarrow sign\_extend(mem[(address+3):address])$ 

#### Permission:

 $M \mod/S \mod/U \mod$ 

#### Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on load instructions

31	20 19 15	14 12	11 7	6 0
imm12[11:0]	rs1	010	rd	0000011



## 14.1.33 LWU: an unsign-extended word load instruction

#### Syntax:

lwu rd, imm12(rs1)

#### **Operation:**

 $address \leftarrow rs1 + sign\_extend(imm12)$ 

 $rd \leftarrow zero\_extend(mem[(address+3):address])$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on load instructions

#### Instruction format:

31 20	19 15	14 12	11 7	6 0
imm12[11:0]	rs1	110	rd	0000011

## 14.1.34 MRET: an instruction for returning from exceptions in M-mode

#### Syntax:

mret

#### **Operation:**

 $next \ pc {\leftarrow} \ mepc$ 

mstatus.mie  $\leftarrow$ mstatus.mpie

mstatus.mpie  $\leftarrow 1$ 

#### Permission:

M mode

#### Exception:

Illegal instruction.

31	25	24 20	19 15	14 12	11 7	6 0
	0011000	00010	00000	000	00000	1110011



## 14.1.35 OR: a bitwise OR instruction

#### Syntax:

or rd, rs1, rs2

#### **Operation:**

 $rd \gets rs1 \mid rs2$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

None

#### Instruction format:

31	25 24	1 20	19 15	14 12	11 7	6 0
00000	00	rs2	rs1	110	rd	0110011

## 14.1.36 ORI: an immediate bitwise OR instruction

#### Syntax:

ori rd, rs1, imm12

#### **Operation:**

 $rd \leftarrow rs1 \mid sign\_extend(imm12)$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

None

#### Instruction format:

31	0 19 15	14 12	11 7	6 0
imm12[11:0]	rs1	110	rd	0010011

## 14.1.37 SB: a byte store instruction

#### Syntax:

sb rs2, imm12(rs1)

#### **Operation:**



 $address \leftarrow rs1 + sign\_extend(imm12)$ 

mem[:address]  $\leftarrow$  rs2[7:0]

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on store instructions

#### Instruction format:

31	25	24 20	19 15	14 12	11 7	6 0
	imm12[11:5]	rs2	rs1	000	imm12[4:0]	0100011

## 14.1.38 SD: a doubleword store instruction

#### Syntax:

sd rs2, imm12(rs1)

#### **Operation:**

 $address \leftarrow rs1 + sign\_extend(imm12)$ 

 $mem[(address+7):address] \leftarrow rs2$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on store instructions

#### Instruction format:

31	25	24 20	19 15	14 12	11 7	6 0
	imm12[11:5]	rs2	rs1	011	imm12[4:0]	0100011

## 14.1.39 SFENCE.VMA: a virtual memory synchronization instruction

#### Syntax:

sfence.vma rs1,rs2

#### **Operation:**

Invalidates and synchronizes virtual memory.

#### Permission:

M mode/S mode



## Exception:

Illegal instruction.

### Notes:

When the TVM bit in the mstatus is 1, running this instruction in S-mode will trigger an illegal instruction exception.

rs1 is the virtual address, and rs2 is the address space identifier (ASID).

- When rs1 and rs2 are both x0, all TLB entries are invalidated.
- When rs1! and rs2 are both x0, all TLB entries that hit the virtual address specified by rs1 are invalidated.
- When rs1 and rs2! are both x0, all TLB entries that hit the process ID specified by rs2 are invalidated.
- When rs1! and rs2! are both x0, all TLB entries that hit the virtual address specified by rs1 and the process ID specified by rs2 are invalidated.

## Instruction format:

31	25 24	20 19	15 14	12 11	7	6 0
0001001	rs2	rs1	00	0	00000	1110011

## 14.1.40 SH: a halfword store instruction

#### Syntax:

sh rs2, imm12(rs1)

#### **Operation:**

 $address \leftarrow rs1 + sign\_extend(imm12)$ 

 $mem[(address+1):address] \leftarrow rs2[15:0]$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on store instructions



31	25	24 20	19 15	14 12	11 7	6 0
	imm12[11:5]	rs2	rs1	001	imm12[4:0]	0100011

## 14.1.41 SLL: a logical left shift instruction

#### Syntax:

sll rd, rs1, rs2

#### **Operation:**

 $rd \leftarrow rs1 \ll rs2[5:0]$ 

## Permission:

M mode/S mode/U mode

#### Exception:

None

#### Instruction format:

31	25	24 20	19 15	14 12	11 7	6 0
0000000		rs2	rs1	001	rd	0110011

## 14.1.42 SLLI: an immediate logical left shift instruction

#### Syntax:

slli rd, rs1, shamt6

#### **Operation:**

 $rd{\leftarrow}\ rs1 << shamt6$ 

#### Permission:

M mode/S mode/U mode

#### Exception:



None

#### Instruction format:

31	26 2	25 20	19	15	14 12	11 7	6	l	0
000000		shamt6	rs1		001	rd		0010011	

# 14.1.43 SLLIW: an immediate logical left shift instruction that operates on the lower 32 bits

#### Syntax:

slliw rd, rs1, shamt5

#### **Operation:**

 $tmp[31:0] \leftarrow (rs1[31:0] << shamt5)[31:0]$ 

 $rd \leftarrow sign\_extend(tmp[31:0])$ 

## Permission:

M mode/S mode/U mode

#### Exception:

None

Instruction format:

31	25 24	20	19 1	5 14	12 11	76	5	0
0000000		shamt5	rs1	001	rc	4	0011011	

## 14.1.44 SLLW: a logical left shift instruction that operates on the lower 32 bits

#### Syntax:

sllw rd, rs1, rs2

#### **Operation:**

 $tmp[31:0] \leftarrow (rs1[31:0] << rs2[4:0])[31:0]$ 

 $rd \leftarrow sign\_extend(tmp[31:0])$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

None



## 14.1.45 SLT: a signed set-if-less-than instruction

#### Syntax:

slt rd, rs1, rs2

#### **Operation:**

if (rs1 < rs2)

 $rd \leftarrow 1$ 

else

 $\mathrm{rd}{\leftarrow}0$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

None

#### Instruction format:

31	25	24 20	19 15	14 12	11 7	6 0
0000	000	rs2	rs1	010	rd	0110011

## 14.1.46 SLTI: a signed set-if-less-than-immediate instruction

#### Syntax:

slti rd, rs1, imm12

#### **Operation:**

if  $(rs1 < sign\_extend(imm12))$ 

 $\mathrm{rd}{\leftarrow}1$ 

#### else

 $\mathrm{rd}{\leftarrow}0$ 

#### Permission:

M mode/S mode/U mode



Exception:

None

#### Instruction format:

31 2	0 19 1	5 14 12	11 7	6 0
imm12[11:0]	rs1	010	rd	0010011

## 14.1.47 SLTIU: an unsigned set-if-less-than-immediate instruction

#### Syntax:

sltiu rd, rs1, imm12

#### **Operation:**

if  $(rs1 < zero\_extend(imm12))$ 

 $\mathrm{rd}{\leftarrow}1$ 

else

 $\mathrm{rd}{\leftarrow}0$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

None

#### Instruction format:

31 20	19 15	14 12	11 7	6 0
imm12[11:0]	rs1	011	rd	0010011

## 14.1.48 SLTU: an unsigned set-if-less-than instruction

#### Syntax:

sltu rd, rs1, rs2

#### **Operation:**

if (rs1 < rs2)

 $rd \leftarrow 1$ 

else

 $\mathrm{rd}{\leftarrow}0$ 

Permission:


 $M \mod/S \mod/U \mod$ 

#### Exception:

None

# Instruction format:

31	25	24 20	19 15	14 12	11 7	6 0
0000000	)	rs2	rs1	011	rd	0110011

# 14.1.49 SRA: an arithmetic right shift instruction

# Syntax:

sra rd, rs1, rs2

# **Operation:**

 $rd \leftarrow rs1 >>> rs2[5:0]$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

None

## Instruction format:

31 25	24 20	19 15	14 12	11 7	6 0
0100000	rs2	rs1	101	rd	0110011

# 14.1.50 SRAI: an immediate arithmetic right shift instruction

# Syntax:

srai rd, rs1, shamt6

## **Operation:**

 $rd{\leftarrow}\ rs1>>>shamt6$ 

# Permission:

M mode/S mode/U mode

# Exception:

None

31	26	25 20	19 15	14 12	11 7	6 0
	010000	shamt6	rs1	101	rd	0010011

# 14.1.51 SLLIW: an immediate arithmetic right shift instruction that operates on the lower 32 bits

## Syntax:

sraiw rd, rs1, shamt5

## **Operation:**

 $tmp[31:0] \leftarrow (rs1[31:0] >> shamt5)[31:0]$ 

 $rd \leftarrow sign\_extend(tmp[31:0])$ 

# **Permission:**

M mode/S mode/U mode

# Exception:

None

# Instruction format:

31 25	24 20	19 15	14 12	11 7	6 0
0100000	shamt5	rs1	101	rd	0011011

# 14.1.52 SRAW: an arithmetic right shift instruction that operates on the lower 32 bits

# Syntax:

sraw rd, rs1, rs2

# Operation:

 $tmp \leftarrow (rs1[31:0] >>> rs2[4:0])[31:0]$ 

 $rd{\leftarrow}sign\_extend(tmp)$ 

# Permission:

M mode/S mode/U mode

# Exception:

None

31	25	24 20	19 15	14 12	11 7	6 0
	0100000	rs2	rs1	101	rd	0111011



0

# 14.1.53 SRET: an instruction for returning from exceptions in S-mode

yntax:						
sret						
Opera	ation:					
next	$pc \leftarrow sepc$					
sstati	us.sie $\leftarrow$ sstatus.s	spie				
sstati	us.spie $\leftarrow 1$					
Perm	ission:					
S mo	de					
Excep	otion:					
Illegal	instruction.					
Instru	uction format:					
31	25	24 20	19 15	14 12	11 7	6
	0001000	00010	00000	000	00000	1110011

# 14.1.54 SRL: a logical right shift instruction

# Syntax:

srl rd, rs1, rs2

## **Operation:**

 $rd \leftarrow rs1 >> rs2[5:0]$ 

# Permission:

M mode/S mode/U mode

# Exception:

None

# Instruction format:

31	25	24 20	19	15	14	12	11	7	6	0
000000		rs2	rs1		1	.01	rd		0110011	

# 14.1.55 SRLI: an immediate logical right shift instruction

## Syntax:

srli rd, rs1, shamt6



# **Operation:**

 $\mathrm{rd}{\leftarrow}\;\mathrm{rs1}>>\mathrm{shamt6}$ 

# Permission:

M mode/S mode/U mode

# Exception:

None

## Instruction format:

31	26	25 20	19 15	14 12	11 7	6 0
	000000	shamt6	rs1	101	rd	0010011

# 14.1.56 SRLIW: an immediate logical right shift instruction that operates on the lower 32 bits

#### Syntax:

srliw rd, rs1, shamt5

## **Operation:**

 $tmp[31:0] \leftarrow (rs1[31:0] >> shamt5)[31:0]$ 

 $rd \leftarrow sign\_extend(tmp[31:0])$ 

## Permission:

M mode/S mode/U mode

#### Exception:

None

#### Instruction format:

31	25 24 20	19 15	14 12	11 7	6 0
0000000	shamt5	rs1	101	rd	0011011

# 14.1.57 SRLW: a logical right shift instruction that operates on the lower 32 bits

# Syntax:

srlw rd, rs1, rs2

# **Operation:**

```
tmp \leftarrow (rs1[31:0] >> rs2[4:0])[31:0]
```

```
rd \leftarrow sign\_extend(tmp)
```



# Permission:

M mode/S mode/U mode

# Exception:

None

# Instruction format:



# 14.1.58 SUB: a signed subtract instruction

# Syntax:

sub rd, rs1, rs2

# **Operation:**

 $rd \leftarrow rs1 - rs2$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

None

Instruction format:

31	25	24 20	19 15	14 12	11 7	6 0
0100000		rs2	rs1	000	rd	0110011

# 14.1.59 SUBW: a signed subtract instruction that operates on the lower 32 bits

## Syntax:

subw rd, rs1, rs2

## **Operation:**

 $tmp[31:0] \leftarrow rs1[31:0] - rs2[31:0]$ 

 $rd \leftarrow sign\_extend(tmp[31:0])$ 

# Permission:

M mode/S mode/U mode

# Exception:

None



Instruction format:

31	25 24	20	19 15	14 12	11 7	6 0
0100	000	rs2	rs1	000	rd	0111011

# 14.1.60 SW: a word store instruction

## Syntax:

sw rs2, imm12(rs1)

#### **Operation:**

 $address \leftarrow rs1 + sign\_extend(imm12)$ 

 $mem[(address+3):address] \leftarrow rs2[31:0]$ 

# Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on store instructions

#### Instruction format:

31	25	24 20	19 15	14 12	11 7	6 0
	imm12[11:5]	rs2	rs1	010	imm12[4:0]	0100011

# 14.1.61 WFI: an instruction for entering the low power mode

# Syntax:

wfi

## **Operation:**

Triggers the CPU to enter the low power mode. In this mode, the CPU clock and most device clocks are disabled.

# Permission:

M mode/S mode/U mode

#### Exception:

None

31	25	24 20	19 15	14 12	11 7	6 0
	0001000	00101	00000	000	00000	1110011



# 14.1.62 XOR: a bitwise XOR instruction

# Syntax:

xor rd, rs1, rs2

# **Operation:**

 $rd \gets rs1 \ \widehat{} \ rs2$ 

# Permission:

M mode/S mode/U mode

## Exception:

None

## Instruction format:

31	25 24	20 19	9 15	14 12	11 7	6 0
0000000	rs	2	rs1	100	rd	0110011

# 14.1.63 XORI: an immediate bitwise XOR instruction

# Syntax:

xori rd, rs1, imm12

## **Operation:**

 $rd \leftarrow rs1 \& sign\_extend(imm12)$ 

## Permission:

M mode/S mode/U mode

## Exception:

None

```
Instruction format:
```

31 2	0 19 1	5 14 12	11 7	6 0
imm12[11:0]	rs1	100	rd	0010011

# 14.2 Appendix A-2 M instructions

The following describes the RISC-V M instructions implemented by C910. The instructions are 32 bits wide and sorted in alphabetic order.



# 14.2.1 DIV: a signed divide instruction

# Syntax:

div rd, rs1, rs2

# **Operation:**

 $rd \leftarrow rs1 \ / \ rs2$ 

# Permission:

Machine mode (M-mode)/Supervisor mode (S-mode)/User mode (U-mode)

## Exception:

None

# Notes:

# Instruction format:

31	25	24 20	19 15	14 12	11 7	6 0
0000001		rs2	rs1	100	rd	0110011

# 14.2.2 DIVU: an unsigned divide instruction

# Syntax:

divu rd, rs1, rs2

# **Operation:**

 $rd \leftarrow rs1 \ / \ rs2$ 

## Permission:

 $M \mod/S \mod/U \mod$ 

# Exception:

None

## Notes:

31	25	24 20	19 15	14 12	11 7	6 0
0000	001	rs2	rs1	101	rd	0110011



# 14.2.3 DIVUW: an unsigned divide instruction that operates on the lower 32 bits

## Syntax:

divuw rd, rs1, rs2

# **O**peration:

 $tmp[31:0] \leftarrow (rs1[31:0] / rs2[31:0])[31:0]$ 

 $rd \leftarrow sign\_extend(tmp[31:0])$ 

#### Permission:

 $M \mod/S \mod/U \mod$ 

#### Exception:

None

#### Notes:

#### Instruction format:

31	25 2	4 20	19 15	14 12	11 7	6 0
0000001		rs2	rs1	101	rd	0111011

# 14.2.4 DIVW: a signed divide instruction that operates on the lower 32 bits

# Syntax:

divw rd, rs1, rs2

# **Operation:**

 $tmp[31:0] \leftarrow (rs1[31:0] / rs2[31:0])[31:0]$ 

 $rd \leftarrow sign\_extend(tmp[31:0])$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

None

#### Notes:

When overflow occurs, the division result is 0xfffffff80000000.





# 14.2.5 MUL: a signed multiply instruction

# Syntax:

mul rd, rs1, rs2

#### **Operation:**

 $rd \leftarrow (rs1 * rs2)[63:0]$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

None

#### Instruction format:

31	25	24 20	19 15	14 12	11 7	6 0
000000	1	rs2	rs1	000	rd	0110011

# 14.2.6 MULH: a signed multiply instruction that extracts the upper bits

#### Syntax:

mulh rd, rs1, rs2

## **Operation:**

 $rd \leftarrow (rs1 * rs2)[127:64]$ 

#### Permission:

M mode/S mode/U mode

# Exception:

None

# Instruction format:

31	25 24 20	19 15	14 12	11 7	6 0
0000001	rs2	rs1	001	rd	0110011

# 14.2.7 MULHSU: a signed-unsigned multiply instruction that extracts the upper bits

Syntax:



mulusu rd, rs1, rs2

# **Operation:**

 $rd \leftarrow (rs1 * rs2)[127:64]$ 

# Permission:

M mode/S mode/U mode

# Exception:

None

## Notes:

rs1 indicates a signed number, and rs2 indicates an unsigned number.

# Instruction format:

31	25 2	24 20	19 15	14 12	11 7	6 0
0000001		rs2	rs1	010	rd	0110011

# 14.2.8 MULHU: an unsigned multiply instruction that extracts the upper bits

## Syntax:

mulhu rd, rs1, rs2

# **Operation:**

 $rd \leftarrow (rs1 * rs2)[127:64]$ 

## Permission:

 $M \mod/S \mod/U \mod$ 

# Exception:

None

# Instruction format:

31	25	24 20	19 15	14 12	11 7	6 0
	0000001	rs2	rs1	011	rd	0110011

# 14.2.9 MULW: a signed multiply instruction that operates on the lower 32 bits

# Syntax:

mulw rd, rs1, rs2

# **Operation:**



 $tmp \leftarrow (rs1[31:0] * rs2[31:0])[31:0]$ 

 $rd \leftarrow sign\_extend(tmp[31:0])$ 

# Permission:

M mode/S mode/U mode

# Exception:

None

# Instruction format:

31	25	24 20	19 15	14 12	11 7	6 0
000000	1	rs2	rs1	000	rd	0111011

# 14.2.10 REM: a signed remainder instruction

# Syntax:

rem rd, rs1, rs2

## **Operation:**

 $rd \gets rs1 ~\% ~rs2$ 

#### Permission:

M mode/S mode/U mode

## Exception:

None

# Notes:

When the divisor is 0, the remainder operation result is the dividend.

When overflow occurs, the remainder operation result is 0x0.

## Instruction format:

31	25 24	4 20	19 15	14 12	11 7	6 0
0000001		rs2	rs1	110	rd	0110011

# 14.2.11 REMU: an unsigned remainder instruction

# Syntax:

remu r<br/>d, rs1, rs2

# **Operation:**

 $rd \leftarrow rs1 \% rs2$ 



# Permission:

M mode/S mode/U mode

# Exception:

None

# Notes:

When the divisor is 0, the remainder operation result is the dividend.

# Instruction format:

31	25 24	20	19 15	14 12	11 7	6 0
0000001		rs2	rs1	111	rd	0110011

# 14.2.12 REMUW: an unsigned remainder instruction that operates on the lower 32 bits

## Syntax:

 $\mathrm{remw}\ \mathrm{rd},\ \mathrm{rs1},\ \mathrm{rs2}$ 

# **Operation:**

tmp  $\leftarrow$  (rs1[31:0] % rs2[31:0])[31:0]

 $rd \leftarrow sign\_extend(tmp)$ 

## Permission:

M mode/S mode/U mode

# Exception:

None

## Notes:

When the divisor is 0, the remainder operation result is obtained by extending the signed bit [31] of the dividend.

# Instruction format:

31 2	5 24 20	19 15	14 12	11 7	6 0
0000001	rs2	rs1	111	rd	0111011

# 14.2.13 REMW: a signed remainder instruction that operates on the lower 32 bits

## Syntax:

 $\mathrm{remw}\ \mathrm{rd},\ \mathrm{rs1},\ \mathrm{rs2}$ 



# **Operation:**

 $tmp[31:0] \leftarrow (rs1[31:0] \% rs2[31:0])[31:0]$ 

 $rd \leftarrow sign\_extend(tmp[31:0])$ 

# Permission:

M mode/S mode/U mode

# Exception:

None

## Notes:

When the divisor is 0, the remainder operation result is obtained by extending the signed bit [31] of the dividend.

When overflow occurs, the remainder operation result is 0x0.

## Instruction format:



# 14.3 Appendix A-3 A instructions

The following describes the RISC-V A instructions implemented by C910. The instructions are 32 bits wide and sorted in alphabetic order.

# 14.3.1 AMOADD.D: an atomic add instruction

## Syntax:

```
amoadd.d.aqrl rd, rs2, (rs1)
```

## **Operation:**

```
rd \leftarrow mem[rs1+7: rs1]
```

 $mem[rs1+7:rs1] \leftarrow mem[rs1+7:rs1] + rs2$ 

## Permission:

M mode/S mode/U mode

# Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on atomic instructions

## Affected flag bits:

None



#### Notes:

The aq and rl bits determine the sequences of executing the memory access instructions before and after this instruction.

- When aq and rl are both 0, the corresponding assembler instruction is amoadd.d rd, rs2, (rs1).
- When aq is 0 and rl is 1, the corresponding assembler instruction is amoadd.d.rl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed.
- When aq is 1 and rl is 0, the corresponding assembler instruction is amoadd.d.aq rd, rs2, (rs1). All memory access instructions after this instruction can be executed only after execution of this instruction is completed.
- When aq and rl are both 1, the corresponding assembler instruction is amoadd.d.aqrl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed, and all memory access instructions after this instruction can be executed only after execution of this instruction is completed.

## Instruction format:

31	-	27 26 25	24 20	19 15	14 12	11 7	6 0
	00000	aq rl	rs2	rs1	011	rd	0101111

# 14.3.2 AMOADD.W: an atomic add instruction that operates on the lower 32 bits

## Syntax:

amoadd.w.aqrl rd, rs2, (rs1)

## **Operation:**

 $rd \leftarrow sign\_extend(mem[rs1+3: rs1])$ 

 $mem[rs1+3:rs1] \leftarrow mem[rs1+3:rs1] + rs2[31:0]$ 

# Permission:

M mode/S mode/U mode

## Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on atomic instructions

## Affected flag bits:

None

## Notes:

```
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```



- When aq and rl are both 0, the corresponding assembler instruction is amoadd.w rd, rs2, (rs1).
- When aq is 0 and rl is 1, the corresponding assembler instruction is amoadd.w.rl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed.
- When aq is 1 and rl is 0, the corresponding assembler instruction is amoadd.w.aq rd, rs2, (rs1). All memory access instructions after this instruction can be executed only after execution of this instruction is completed.
- When aq and rl are both 1, the corresponding assembler instruction is amoadd.w.aqrl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed, and all memory access instructions after this instruction can be executed only after execution of this instruction is completed.

# Instruction format:

31	27	26	25	24 20	19 15	14 12	11 7	6 0
	00000	aq	rl	rs2	rs1	010	rd	0101111

# 14.3.3 AMOAND.D: an atomic bitwise AND instruction

# Syntax:

amoand.d.aqrl rd, rs2, (rs1)

## **Operation:**

```
rd \leftarrow mem[rs1+7: rs1]
```

 $\mathrm{mem}[\mathrm{rs1}{+}7\mathrm{:rs1}] \gets \mathrm{mem}[\mathrm{rs1}{+}7\mathrm{:rs1}] \ \& \ \mathrm{rs2}$ 

**Permission:** M mode/S mode/U mode

# Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on atomic instructions

## Affected flag bits:

None

## Notes:

- When aq and rl are both 0, the corresponding assembler instruction is amoand.d rd, rs2, (rs1).
- When aq is 0 and rl is 1, the corresponding assembler instruction is amoand.d.rl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed.



- When aq is 1 and rl is 0, the corresponding assembler instruction is amoand.d.aq rd, rs2, (rs1). All memory access instructions after this instruction can be executed only after execution of this instruction is completed.
- When aq and rl are both 1, the corresponding assembler instruction is amoand.d.aqrl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed, and all memory access instructions after this instruction can be executed only after execution of this instruction is completed.

# Instruction format:

31	27	26	25	24 20	19 1	5 14	12	11 7	6	0
	01100	aq	rl	rs2	rs1		011	rd	0101111	

# 14.3.4 AMOAND.W: an atomic bitwise AND instruction that operates on the lower 32 bits

# Syntax:

amoand.w.aqrl rd, rs2, (rs1)

# **Operation:**

 $rd \leftarrow sign\_extend(mem[rs1+3: rs1])$ 

 $mem[rs1+3:rs1] \leftarrow mem[rs1+3:rs1] \& rs2[31:0]$ 

## Permission:

M mode/S mode/U mode

# Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on atomic instructions

## Affected flag bits:

None

## Notes:

- When aq and rl are both 0, the corresponding assembler instruction is amoand.w rd, rs2, (rs1).
- When aq is 0 and rl is 1, the corresponding assembler instruction is amoand.w.rl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed.



- When aq is 1 and rl is 0, the corresponding assembler instruction is amoand.w.aq rd, rs2, (rs1). All memory access instructions after this instruction can be executed only after execution of this instruction is completed.
- When aq and rl are both 1, the corresponding assembler instruction is amoand.w.aqrl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed, and all memory access instructions after this instruction can be executed only after execution of this instruction is completed.

# Instruction format:

31		27	26	25	24 20	19 15	14 1	2 11	6 0
	01100	i	aq	rl	rs2	rs1	010	rd	0101111

# 14.3.5 AMOMAX.D: an atomic signed MAX instruction

# Syntax:

amomax.d.aqrl rd, rs2, (rs1)

# **Operation:**

 $rd \leftarrow mem[rs1+7: rs1]$ 

 $mem[rs1+7:rs1] \leftarrow max(mem[rs1+7:rs1], rs2)$ 

## Permission:

M mode/S mode/U mode

## Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on atomic instructions

## Affected flag bits:

None

## Notes:

- When aq and rl are both 0, the corresponding assembler instruction is amomax.d rd, rs2, (rs1).
- When aq is 0 and rl is 1, the corresponding assembler instruction is amomax.d.rl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed.
- When aq is 1 and rl is 0, the corresponding assembler instruction is amomax.d.aq rd, rs2, (rs1). All memory access instructions after this instruction can be executed only after execution of this instruction is completed.

• When aq and rl are both 1, the corresponding assembler instruction is amomax.d.aqrl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed, and all memory access instructions after this instruction can be executed only after execution of this instruction is completed.

#### Instruction format:

31	27	<mark>26</mark>	25	24 20	19 1	14	12	11 7	6	0
	10100	aq	rl	rs2	rs1		011	rd	0101111	

# 14.3.6 AMOMAX.W: an atomic signed MAX instruction that operates on the lower 32 bits

#### Syntax:

amomax.w.aqrl rd, rs2, (rs1)

## **Operation:**

 $rd \leftarrow sign\_extend(mem[rs1+3: rs1])$ 

 $mem[rs1+3:rs1] \leftarrow max(mem[rs1+3:rs1], rs2[31:0])$ 

#### Permission:

 $M \mod/S \mod/U \mod$ 

#### Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on atomic instructions

## Affected flag bits:

None

## Notes:

- When aq and rl are both 0, the corresponding assembler instruction is amomax.w rd, rs2, (rs1).
- When aq is 0 and rl is 1, the corresponding assembler instruction is amomax.w.rl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed.
- When aq is 1 and rl is 0, the corresponding assembler instruction is amomax.w.aq rd, rs2, (rs1). All memory access instructions after this instruction can be executed only after execution of this instruction is completed.
- When aq and rl are both 1, the corresponding assembler instruction is amomax.w.aqrl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruc-



tion is executed, and all memory access instructions after this instruction can be executed only after execution of this instruction is completed.

# Instruction format:

31	27	26	25	24 20	19	15 1	14 12	11 7	6	0
	10100	aq	rl	rs2	rs1		010	rd	0101111	

# 14.3.7 MOMAXU.DA: an atomic unsigned MAX instruction

# Syntax:

amomaxu.d.aqrl rd, rs2, (rs1)

## **Operation:**

 $rd \leftarrow mem[rs1+7: rs1]$ 

 $mem[rs1+7:rs1] \leftarrow max(mem[rs1+7:rs1], rs2)$ 

## Permission:

M mode/S mode/U mode

## Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on atomic instructions

# Affected flag bits:

None

## Notes:

The aq and rl bits determine the sequences of executing the memory access instructions before and after this instruction.

- When aq and rl are both 0, the corresponding assembler instruction is amomaxu.d rd, rs2, (rs1).
- When aq is 0 and rl is 1, the corresponding assembler instruction is amomaxu.d.rl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed.
- When aq is 1 and rl is 0, the corresponding assembler instruction is amomaxu.d.aq rd, rs2, (rs1). All memory access instructions after this instruction can be executed only after execution of this instruction is completed.
- When aq and rl are both 1, the corresponding assembler instruction is amomaxu.d.aqrl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed, and all memory access instructions after this instruction can be executed only after execution of this instruction is completed.

31	27	26	25	24 20	19 15	14 12	11 7	6 0
	11100	aq	rl	rs2	rs1	011	rd	0101111

# 14.3.8 AMOMAXU.W: an atomic unsigned MAX instruction that operates on the lower 32 bits.

# Syntax:

amomaxu.w.aqrl rd, rs2, (rs1)

# **Operation:**

 $rd \leftarrow zero\_extend(mem[rs1+3: rs1])$ 

 $mem[rs1+3:rs1] \leftarrow max(mem[rs1+3:rs1], rs2[31:0])$ 

## Permission:

M mode/S mode/U mode

# Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on atomic instructions

# Affected flag bits:

None

## Notes:

The aq and rl bits determine the sequences of executing the memory access instructions before and after this instruction.

- When aq and rl are both 0, the corresponding assembler instruction is amomaxu.w rd, rs2, (rs1).
- When aq is 0 and rl is 1, the corresponding assembler instruction is amomaxu.w.rl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed.
- When aq is 1 and rl is 0, the corresponding assembler instruction is amomaxu.w.aq rd, rs2, (rs1). All memory access instructions after this instruction can be executed only after execution of this instruction is completed.
- When aq and rl are both 1, the corresponding assembler instruction is amomaxu.w.aqrl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed, and all memory access instructions after this instruction can be executed only after execution of this instruction is completed.

31	27	26	25	24 2	0 19	15	14	12	11	7	6		0
	11100	aq	rl	rs2		rs1	010		rd			0101111	



# 14.3.9 AMOMIN.D: an atomic signed MIN instruction

## Syntax:

amomin.d.aqrl rd, rs2, (rs1)

# **Operation:**

 $rd \leftarrow mem[rs1+7: rs1]$ 

 $mem[rs1+7:rs1] \leftarrow min(mem[rs1+7:rs1],rs2)$ 

# Permission:

M mode/S mode/U mode

# Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on atomic instructions

# Affected flag bits:

None

# Notes:

The aq and rl bits determine the sequences of executing the memory access instructions before and after this instruction.

- When aq and rl are both 0, the corresponding assembler instruction is amomin.d rd, rs2, (rs1).
- When aq is 0 and rl is 1, the corresponding assembler instruction is amomin.d.rl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed.
- When aq is 1 and rl is 0, the corresponding assembler instruction is amomin.d.aq rd, rs2, (rs1). All memory access instructions after this instruction can be executed only after execution of this instruction is completed.
- When aq and rl are both 1, the corresponding assembler instruction is amomin.d.aqrl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed, and all memory access instructions after this instruction can be executed only after execution of this instruction is completed.

31	27	26	25	24 20	19 15	14 12	11 7	6 0
	10000	aq	rl	rs2	rs1	011	rd	0101111



# 14.3.10 AMOMIN.W: an atomic signed MIN instruction that operates on the lower 32 bits

#### Syntax:

amomin.w.aqrl rd, rs2, (rs1)

## **Operation:**

 $rd \leftarrow sign\_extend(mem[rs1+3: rs1])$ 

 $\operatorname{mem}[\operatorname{rs1+3:rs1}] \leftarrow \operatorname{min}(\operatorname{mem}[\operatorname{rs1+3:rs1}], \operatorname{rs2}[31:0])$ 

# Permission:

 $M \mod/S \mod/U \mod$ 

## Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on atomic instructions

## Affected flag bits:

None

#### Notes:

The aq and rl bits determine the sequences of executing the memory access instructions before and after this instruction.

- When aq and rl are both 0, the corresponding assembler instruction is amomin.w rd, rs2, (rs1).
- When aq is 0 and rl is 1, the corresponding assembler instruction is amomin.w.rl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed.
- When aq is 1 and rl is 0, the corresponding assembler instruction is amomin.w.aq rd, rs2, (rs1). All memory access instructions after this instruction can be executed only after execution of this instruction is completed.
- When aq and rl are both 1, the corresponding assembler instruction is amomin.w.aqrl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed, and all memory access instructions after this instruction can be executed only after execution of this instruction is completed.

3	1	27	26	25	24 20	19	15	14	12	11	7	6	0
	10000		aq	rl	rs2	rs1		0	10	rd		0101111	



# 14.3.11 AMOMINU.D: an atomic unsigned MIN instruction

## Syntax:

amominu.d.aqrl rd, rs2, (rs1)

# **Operation:**

 $rd \leftarrow mem[rs1{+}7: rs1]$ 

 $mem[rs1+7:rs1] \leftarrow min(mem[rs1+7:rs1], rs2)$ 

# Permission:

M mode/S mode/U mode

# Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on atomic instructions

# Affected flag bits:

None

# Notes:

The aq and rl bits determine the sequences of executing the memory access instructions before and after this instruction.

- When aq and rl are both 0, the corresponding assembler instruction is amominu.d rd, rs2, (rs1).
- When aq is 0 and rl is 1, the corresponding assembler instruction is amominu.d.rl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed.
- When aq is 1 and rl is 0, the corresponding assembler instruction is amominu.d.aq rd, rs2, (rs1). All memory access instructions after this instruction can be executed only after execution of this instruction is completed.
- When aq and rl are both 1, the corresponding assembler instruction is amominu.d.aqrl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed, and all memory access instructions after this instruction can be executed only after execution of this instruction is completed.

31	27	26	25	24 20	19 15	14 12	11 7	6 0
	11000	aq	rl	rs2	rs1	011	rd	0101111



# 14.3.12 AMOMINU.W: an atomic unsigned MIN instruction that operates on the lower 32 bits

#### Syntax:

amominu.w.aqrl rd, rs2, (rs1)

## **Operation:**

 $rd \leftarrow sign\_extend(mem[rs1+3: rs1])$ 

 $\operatorname{mem}[\operatorname{rs1+3:rs1}] \leftarrow \operatorname{min}(\operatorname{mem}[\operatorname{rs1+3:rs1}], \operatorname{rs2}[31:0])$ 

## Permission:

M mode/S mode/U mode

## Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on atomic instructions

## Affected flag bits:

None

#### Notes:

The aq and rl bits determine the sequences of executing the memory access instructions before and after this instruction.

- When aq and rl are both 0, the corresponding assembler instruction is amominu.w rd, rs2, (rs1).
- When aq is 0 and rl is 1, the corresponding assembler instruction is amominu.w.rl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed.
- When aq is 1 and rl is 0, the corresponding assembler instruction is amominu.w.aq rd, rs2, (rs1). All memory access instructions after this instruction can be executed only after execution of this instruction is completed.
- When aq and rl are both 1, the corresponding assembler instruction is amominu.w.aqrl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed, and all memory access instructions after this instruction can be executed only after execution of this instruction is completed.

31	27	26	25	24	20	19	1	5	14	12	11	7	6	0
11	000	aq	rl		rs2		rs1		010	)		rd	0101111	



# 14.3.13 AMOOR.D: an atomic bitwise OR instruction.

## Syntax:

amoor.d.aqrl rd, rs2, (rs1)

## **Operation:**

 $rd \leftarrow mem[rs1+7: rs1]$ 

 $mem[rs1+7:rs1] \leftarrow mem[rs1+7:rs1] \mid rs2$ 

## Permission:

 $M \mod/S \mod/U \mod$ 

# Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on atomic instructions

# Affected flag bits:

None

# Notes:

The aq and rl bits determine the sequences of executing the memory access instructions before and after this instruction.

- When aq and rl are both 0, the corresponding assembler instruction is amoor.d rd, rs2, (rs1).
- When aq is 0 and rl is 1, the corresponding assembler instruction is amoor.d.rl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed.
- When aq is 1 and rl is 0, the corresponding assembler instruction is amoor.d.aq rd, rs2, (rs1). All memory access instructions after this instruction can be executed only after execution of this instruction is completed.
- When aq and rl are both 1, the corresponding assembler instruction is amoor.d.aqrl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed, and all memory access instructions after this instruction can be executed only after execution of this instruction is completed.

# Instruction format:

31	27	26 25	24	20 19	15	14 1	2 11	7 6	0
0	01000	aq rl	rs2		rs1	011	rd	01011	11

# 14.3.14 AMOOR.W: an atomic bitwise OR instruction that operates on the lower 32 bits

## Syntax:



amoor.w.aqrl rd, rs2, (rs1)

# **Operation:**

 $rd \leftarrow sign\_extend(mem[rs1+3: rs1])$ 

 $mem[rs1+3:rs1] \leftarrow mem[rs1+3:rs1] \mid rs2[31:0]$ 

# Permission:

M mode/S mode/U mode

# Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on atomic instructions

# Affected flag bits:

None

## Notes:

The aq and rl bits determine the sequences of executing the memory access instructions before and after this instruction.

- When aq and rl are both 0, the corresponding assembler instruction is amoor.w rd, rs2, (rs1).
- When aq is 0 and rl is 1, the corresponding assembler instruction is amoor.w.rl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed.
- When aq is 1 and rl is 0, the corresponding assembler instruction is amoor.w.aq rd, rs2, (rs1). All memory access instructions after this instruction can be executed only after execution of this instruction is completed.
- When aq and rl are both 1, the corresponding assembler instruction is amoor.w.aqrl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed, and all memory access instructions after this instruction can be executed only after execution of this instruction is completed.

## Instruction format:

31	27 26	5 25	24	20 19	-	15 1	4 12	11	6	· · · ·	0
01000	ac	l l	rs2		rs1		010	rd		0101111	

# 14.3.15 AMOSWAP.D: an atomic swap instruction

## Syntax:

amoswap.d.aqrl rd, rs2, (rs1)

# **Operation:**



 $rd \leftarrow mem[rs1+7: rs1]$ 

 $mem[rs1+7:rs1] \leftarrow rs2$ 

# Permission:

M mode/S mode/U mode

# Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on atomic instructions

# Affected flag bits: None

# Notes:

The aq and rl bits determine the sequences of executing the memory access instructions before and after this instruction.

- When aq and rl are both 0, the corresponding assembler instruction is amoswap.d rd, rs2, (rs1).
- When aq is 0 and rl is 1, the corresponding assembler instruction is amoswap.d.rl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed.
- When aq is 1 and rl is 0, the corresponding assembler instruction is amoswap.d.aq rd, rs2, (rs1). All memory access instructions after this instruction can be executed only after execution of this instruction is completed.
- When aq and rl are both 1, the corresponding assembler instruction is amoswap.d.aqrl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed, and all memory access instructions after this instruction can be executed only after execution of this instruction is completed.

# Instruction format:



# 14.3.16 AMOSWAP.W: an atomic swap instruction that operates on the lower 32 bits

# Syntax:

amoswap.w.aqrl rd, rs2, (rs1)

# **Operation:**

 $rd \leftarrow sign\_extend(\ mem[rs1+3:\ rs1]\ )$ 

 $\mathrm{mem}[\mathrm{rs1}{+}3\mathrm{:rs1}] \leftarrow \mathrm{rs2}[31{:}0]$ 

# Permission:

M mode/S mode/U mode



# Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on atomic instructions

## Affected flag bits: None

# Notes:

The aq and rl bits determine the sequences of executing the memory access instructions before and after this instruction.

- When aq and rl are both 0, the corresponding assembler instruction is amoswap.w rd, rs2, (rs1).
- When aq is 0 and rl is 1, the corresponding assembler instruction is amoswap.w.rl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed.
- When aq is 1 and rl is 0, the corresponding assembler instruction is amoswap.w.aq rd, rs2, (rs1). All memory access instructions after this instruction can be executed only after execution of this instruction is completed.
- When aq and rl are both 1, the corresponding assembler instruction is amoswap.w.aqrl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed, and all memory access instructions after this instruction can be executed only after execution of this instruction is completed.

## Instruction format:



# 14.3.17 AMOXOR.D: an atomic bitwise XOR instruction

## Syntax:

amoxor.d.aqrl rd, rs2, (rs1)

## **Operation:**

```
rd \leftarrow mem[rs1+7: rs1]
```

 $mem[rs1+7:rs1] \leftarrow mem[rs1+7:rs1] \uparrow rs2$ 

## Permission:

M mode/S mode/U mode

## Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on atomic instructions

## Affected flag bits:

## None



#### Notes:

The aq and rl bits determine the sequences of executing the memory access instructions before and after this instruction.

- When aq and rl are both 0, the corresponding assembler instruction is amoxor.d rd, rs2, (rs1).
- When aq is 0 and rl is 1, the corresponding assembler instruction is amoxor.d.rl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed.
- When aq is 1 and rl is 0, the corresponding assembler instruction is amoxor.d.aq rd, rs2, (rs1). All memory access instructions after this instruction can be executed only after execution of this instruction is completed.
- When aq and rl are both 1, the corresponding assembler instruction is amoxor.d.aqrl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed, and all memory access instructions after this instruction can be executed only after execution of this instruction is completed.

#### Instruction format:

31	27 26 25	24 20	19 15	14 12	11 7	6 0
00100	aq rl	rs2	rs1	011	rd	0101111

# 14.3.18 AMOXOR.W: an atomic bitwise XOR instruction that operates on the lower 32 bits

## Syntax:

amoxor.w.aqrl rd, rs2, (rs1)

## **Operation:**

 $rd \leftarrow sign\_extend(mem[rs1+3: rs1])$ 

 $mem[rs1+3:rs1] \leftarrow mem[rs1+3:rs1] \cap rs2[31:0]$ 

#### Permission:

M mode/S mode/U mode

#### **Exception:**

Unaligned access exceptions, access error exceptions, and page error exceptions on atomic instructions

#### Affected flag bits:

None

Notes:

The aq and rl bits determine the sequences of executing the memory access instructions before and after this instruction.

- When aq and rl are both 0, the corresponding assembler instruction is amoxor.w rd, rs2, (rs1).
- When aq is 0 and rl is 1, the corresponding assembler instruction is amoxor.w.rl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed.
- When aq is 1 and rl is 0, the corresponding assembler instruction is amoxor.w.aq rd, rs2, (rs1). All memory access instructions after this instruction can be executed only after execution of this instruction is completed.
- When aq and rl are both 1, the corresponding assembler instruction is amoxor.w.aqrl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed, and all memory access instructions after this instruction can be executed only after execution of this instruction is completed.

# Instruction format:

31	27	26	25	24 20	19	15	14	12	11	7	6	· · · ·	0
	00100	aq	rl	rs2	rs1			010		rd		0101111	

# 14.3.19 LR.D: a doubleword load-reserved instruction

## Syntax:

lr.d.aqrl rd, (rs1)

## **Operation:**

 $rd \leftarrow mem[rs1+7: rs1]$ 

mem[rs1+7:rs1] is reserved

## Permission:

M mode/S mode/U mode

## Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on atomic instructions

# Affected flag bits:

None

#### Notes:

The aq and rl bits determine the sequences of executing the memory access instructions before and after this instruction.

• When aq and rl are both 0, the corresponding assembler instruction is lr.d rd, (rs1).

- When aq is 0 and rl is 1, the corresponding assembler instruction is lr.d.rl rd, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed.
- When aq is 1 and rl is 0, the corresponding assembler instruction is lr.d.aq rd, (rs1). All memory access instructions after this instruction can be executed only after execution of this instruction is completed.
- When aq and rl are both 1, the corresponding assembler instruction is lr.d.aqrl rd, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed, and all memory access instructions after this instruction can be executed only after execution of this instruction is completed.

# Instruction format:

31	27	26	25	24	20 1	.9	15	14	12	11		7	6	0
00010		aq	rl	00000		rs1			011		rd		0101111	

# 14.3.20 LR.W: a word load-reserved instruction

# Syntax:

lr.w.aqrl rd, (rs1)

# **Operation:**

 $rd \leftarrow sign\_extend(mem[rs1+3: rs1])$ 

mem[rs1+3:rs1] is reserved

## Permission:

M mode/S mode/U mode

**Exception:** Unaligned access exceptions, access error exceptions, and page error exceptions on atomic instructions

# Affected flag bits: None

- When aq and rl are both 0, the corresponding assembler instruction is lr.w rd, (rs1).
- When aq is 0 and rl is 1, the corresponding assembler instruction is lr.w.rl rd, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed.
- When aq is 1 and rl is 0, the corresponding assembler instruction is lr.w.aq rd, (rs1). All memory access instructions after this instruction can be executed only after execution of this instruction is completed.
- When aq and rl are both 1, the corresponding assembler instruction is lr.w.aqrl rd, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed, and all memory access instructions after this instruction can be executed only after execution of this instruction is completed.



Instruction format:

3	L 27	26	25	24 20	19	15	14	12	11	7	6		0
	00010	aq	rl	00000	rs1			010		rd		0101111	

# 14.3.21 SC.D: a doubleword store-conditional instruction

# Syntax:

sc.d.aqrl rd, rs2, (rs1)

# **Operation:**

If (mem[rs1+7:rs1] is reserved)

 $mem[rs1+7: rs1] \leftarrow rs2$ 

 $\mathrm{rd} \gets 0$ 

else

 $\mathrm{rd} \gets 1$ 

# Permission:

M mode/S mode/U mode

# Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on atomic instructions

## Affected flag bits:

None

## Notes:

- When aq and rl are both 0, the corresponding assembler instruction is sc.d rd, rs2, (rs1).
- When aq is 0 and rl is 1, the corresponding assembler instruction is sc.d.rl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed.
- When aq is 1 and rl is 0, the corresponding assembler instruction is sc.d.aq rd, rs2, (rs1). All memory access instructions after this instruction can be executed only after execution of this instruction is completed.
- When aq and rl are both 1, the corresponding assembler instruction is sc.d.aqrl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed, and all memory access instructions after this instruction can be executed only after execution of this instruction is completed.



# Instruction format:

31	27	26	25	24 20	19 15	14	12	11 7	6	; O
	00011	aq	rl	rs2	rs1	(	011	rd		0101111

# 14.3.22 SC.W: a word store-conditional instruction

# Syntax:

sc.w.aqrl rd, rs2, (rs1)

# **Operation:**

```
if(mem[rs1+3:rs1] is reserved)
```

 $mem[rs1+3:rs1] \leftarrow rs2[31:0]$ 

 $\mathrm{rd} \gets 0$ 

else

 $\mathrm{rd} \gets 1$ 

# Permission:

M mode/S mode/U mode

# Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on atomic instructions

## Affected flag bits:

None

## Notes:

- When aq and rl are both 0, the corresponding assembler instruction is sc.w rd, rs2, (rs1).
- When aq is 0 and rl is 1, the corresponding assembler instruction is sc.w.rl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed.
- When aq is 1 and rl is 0, the corresponding assembler instruction is sc.w.aq rd, rs2, (rs1). All memory access instructions after this instruction can be executed only after execution of this instruction is completed.
- When aq and rl are both 1, the corresponding assembler instruction is sc.w.aqrl rd, rs2, (rs1). Results of all memory access instructions before this instruction must be observed before this instruction is executed, and all memory access instructions after this instruction can be executed only after execution of this instruction is completed.



Instruction format:

31	27	26	25	24 2	0 19	15	14	12	11	7	6		0
	00011	aq	rl	rs2	rs1			010	r	rd		0101111	

# 14.4 Appendix A-4 F instructions

The following describes the RISC-V F instructions implemented by C910. The instructions are 32 bits wide and sorted in alphabetic order.

For single-precision floating-point instructions, if the upper 32 bits in the source register are not all 1, the single-precision data is treated as qNaN.

When the fs bit in the mstatus register is 2' b00, running any instruction listed in this appendix will trigger an illegal instruction exception. When the fs bit in the mstatus register is not 2' b00, it is set to 2' b11 after any instruction listed in this appendix is executed.

# 14.4.1 FADD.S: a single-precision floating-point add instruction

#### Syntax:

fadd.s fd, fs1, fs2, rm

## **Operation:**

 $\mathrm{frd} \leftarrow \mathrm{fs1} + \mathrm{fs2}$ 

## Permission:

 $M \mod/S \mod/U \mod$ 

#### Exception:

Illegal instruction.

## Affected flag bits:

Floating-point status bits NV, OF, and NX

## Notes:

RM determines the round-off mode:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fadd.s fd, fs1, fs2, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fadd.s fd, fs1, fs2, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fadd.s fd, fs1, fs2, rdn.



- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fadd.s fd, fs1, fs2, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fadd.s fd, fs1, fs2, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the floating-point control and status register (FCSR), fcsr. The corresponding assembler instruction is fadd.s fd, fs1, fs2.

#### Instruction format:

31	25	24 20	19 15	14 12	11 7	6 0
	0000000	fs2	fs1	rm	fd	1010011

# 14.4.2 FCLASS.S: a single-precision floating-point classify instruction

## Syntax:

fclass.s rd, fs1

## **Operation:**

- if ( fs1 = -inf)
  - $rd \leftarrow 64'$  h1
- if ( fs1 = -norm)

$$rd \leftarrow 64' h2$$

if ( fs1 = -subnorm)

 $rd \leftarrow 64' h4$ 

if (fs1 = -zero)

$$rd \leftarrow 64' h8$$

if (  $\mathrm{fs1}=+\mathrm{zero})$ 

$$\mathrm{rd} \leftarrow 64' \ \mathrm{h10}$$

if 
$$(fs1 = +subnorm)$$

$$\mathrm{rd} \leftarrow 64' \ \mathrm{h20}$$

if 
$$(fs1 = +norm)$$

rd 
$$\leftarrow 64'$$
 h40

if ( 
$$fs1 = +Inf$$
)


 $\mathrm{rd} \leftarrow 64' \ \mathrm{h80}$ 

if 
$$(fs1 = sNaN)$$

 $\mathrm{rd} \leftarrow 64' \ \mathrm{h100}$ 

if (  $\mathrm{fs1}=\mathrm{qNaN})$ 

 $\mathrm{rd} \leftarrow 64' \ \mathrm{h200}$ 

# Permission:

M mode/S mode/U mode

# Exception:

Illegal instruction.

# Affected flag bits:

None

# Instruction format:

31	25	24 20	19 15	14 12	11 7	6 0
1110000		00000	fs1	001	rd	1010011

# 14.4.3 FCVT.L.S: an instruction that converts a single-precision floating-point number into a signed long integer

# Syntax:

fcvt.l.s rd, fs1, rm

## **Operation:**

 $rd \leftarrow single\_convert\_to\_signed\_long(fs1)$ 

## Permission:

M mode/S mode/U mode

## Exception:

Illegal instruction.

## Affected flag bits:

Floating-point status bits NV and NX

## Notes:

RM determines the round-off mode:

• 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fcvt.l.s rd, fs1, rne.



- 3' b001: Rounds off to zero. The corresponding assembler instruction is fcvt.l.s rd, fs1, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fcvt.l.s rd, fs1, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fcvt.l.s rd, fs1, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fcvt.l.s rd, fs1, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fcvt.l.s rd, fs1.

## Instruction format:

31	25 24	20 19	15	14 12	11 7	6	0
1100000	00	010	fs1	rm	rd	1010011	

# 14.4.4 FCVT.LU.S: an instruction that converts a single-precision floating-point number into an unsigned long integer

## Syntax:

fcvt.lu.s rd, fs1, rm

## **Operation:**

 $rd \leftarrow single\_convert\_to\_unsigned\_long(fs1)$ 

## Permission:

M mode/S mode/U mode

## Exception:

Illegal instruction.

# Affected flag bits:

Floating-point status bits NV and NX

#### Notes:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fcvt.lu.s rd, fs1, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fcvt.lu.s rd, fs1, rtz.



- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fcvt.lu.s rd, fs1, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fcvt.lu.s rd, fs1, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fcvt.lu.s rd, fs1, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fcvt.lu.s rd, fs1.

31	25 24	20 19	15	14 12	11 7	6 0
1100000	000	011	fs1	rm	rd	1010011

# 14.4.5 FCVT.S.L: an instruction that converts a signed long integer into a singleprecision floating-point number

### Syntax:

fcvt.s.l fd, rs1, rm

## **Operation:**

 $fd \leftarrow signed\_long\_convert\_to\_single(fs1)$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

# Affected flag bits:

Floating-point status bit NX

#### Notes:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fcvt.s.l fd, rs1, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fcvt.s.l fd, rs1, rtz.



- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fcvt.s.l fd, fs1, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fcvt.s.l fd, fs1, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fcvt.s.l fd, fs1, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fcvt.s.l fd, fs1.

31 25	24 20	19 15	14 12	11 7	6 0
1101000	00010	rs1	rm	fd	1010011

# 14.4.6 FCVT.S.LU: an instruction that converts an unsigned long integer into a singleprecision floating-point number

# Syntax:

fcvt.s.l fd, fs1, rm

# **Operation:**

 $fd \leftarrow unsigned\_long\_convert\_to\_single\_fp(fs1)$ 

## Permission:

M mode/S mode/U mode

## Exception:

Illegal instruction.

## Affected flag bits:

Floating-point status bit NX

## Notes:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fcvt.s.lu fd, fs1, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fcvt.s.lu fd, fs1, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fcvt.s.lu fd, fs1, rdn.



- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fcvt.s.lu fd, fs1, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fcvt.s.lu fd, fs1, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fcvt.s.lu fd, fs1.

31	25	24 20	19 15	14 12	11 7	6 0
1101000		00011	rs1	rm	fd	1010011

# 14.4.7 FCVT.S.W: an instruction that converts a signed integer into a single-precision floating-point number

## Syntax:

fcvt.s.w fd, rs1, rm

# **Operation:**

 $fd \leftarrow signed\_int\_convert\_to\_single(fs1)$ 

## Permission:

M mode/S mode/U mode

## Exception:

Illegal instruction.

## Affected flag bits:

Floating-point status bit NX

## Notes:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fcvt.s.w fd, rs1, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fcvt.s.w fd, rs1, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fcvt.s.w fd, rs1, rdn.



- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fcvt.s.w fd, rs1, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fcvt.s.w fd, rs1, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fcvt.s.w fd, rs1.

# Instruction format:

31	25	24 20	) 19	15 1	14 12	11 7	6 0
110	000	00000	rs1		rm	fd	1010011

# 14.4.8 FCVT.S.WU: an instruction that converts an unsigned integer into a singleprecision floating-point number

## Syntax:

fcvt.s.wu fd, rs1, rm

# **Operation:**

 $fd \leftarrow unsigned\_int\_convert\_to\_single\_fp(fs1)$ 

# Permission:

M mode/S mode/U mode

## Exception:

Illegal instruction.

## Affected flag bits:

Floating-point status bit NX

## Notes:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fcvt.s.wu fd, rs1, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fcvt.s.wu fd, rs1, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fcvt.s.wu fd, rs1, rdn.



- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fcvt.s.wu fd, rs1, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fcvt.s.wu fd, rs1, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fcvt.s.wu fd, rs1.

31	25	24 20	19 15	14 12	11 7	6 0
	1101000	00001	rs1	rm	fd	1010011

# 14.4.9 FCVT.W.S: an instruction that converts a single-precision floating-point number into a signed integer

## Syntax:

fcvt.w.s rd, fs1, rm

# **Operation:**

 $tmp \leftarrow single\_convert\_to\_signed\_int(fs1)$ 

 $rd \leftarrow sign\_extend(tmp)$ 

## Permission:

M mode/S mode/U mode

## Exception:

Illegal instruction.

## Affected flag bits:

Floating-point status bits NV and NX

## Notes:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fcvt.w.s rd, fs1, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fcvt.w.s rd, fs1, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fcvt.w.s rd, fs1, rdn.



- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fcvt.w.s rd, fs1, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fcvt.w.s rd, fs1, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fcvt.w.s rd, fs1.

3	25	24 20	19 15	14 12	11 7	6 0
	1100000	00000	fs1	rm	rd	1010011

# 14.4.10 FCVT.WU.S: an instruction that converts a single-precision floating-point number into an unsigned integer

## Syntax:

fcvt.wu.s rd, fs1, rm

# **Operation:**

 $tmp \leftarrow single\_convert\_to\_unsigned\_int(fs1)$ 

 $rd \leftarrow sign\_extend(tmp)$ 

## Permission:

M mode/S mode/U mode

## Exception:

Illegal instruction.

## Affected flag bits:

Floating-point status bits NV and NX

## Notes:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fcvt.wu.s rd, fs1, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fcvt.wu.s rd, fs1, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fcvt.wu.s rd, fs1, rdn.



- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fcvt.wu.s rd, fs1, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fcvt.wu.s rd, fs1, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fcvt.wu.s rd, fs1.

31 25	24 20	19 15	14 12	11 7	6 0
1100000	00001	fs1	rm	rd	1010011

# 14.4.11 FDIV.S: a single-precision floating-point divide instruction

# Syntax:

fdiv.s fd, fs1, fs2, rm  $\,$ 

# **Operation:**

 $\mathrm{fd} \leftarrow \mathrm{fs1} \ / \ \mathrm{fs2}$ 

## Permission:

 $M \mod/S \mod/U \mod$ 

## Exception:

Illegal instruction.

## Affected flag bits:

Floating-point status bits NV, DZ, OF, UF, and NX

## Notes:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fdiv.s fs1, fs2, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fdiv.s fd fs1, fs2, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fdiv.s fd, fs1, fs2, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fdiv.s fd, fs1, fs2, rup.



- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fdiv.s fd, fs1, fs2, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fdiv.s fd, fs1, fs2.

31	25	24 20	19 15	14 12	11 7	6 0
0001100		fs1	fs2	rm	fd	1010011

# 14.4.12 FEQ.S: a single-precision floating-point compare equal instruction

# Syntax:

feq.s rd, fs1, fs2

# **Operation:**

if(fs1 == fs2)

 $\mathrm{rd} \gets 1$ 

else

 $\mathrm{rd} \gets 0$ 

# Permission:

M mode/S mode/U mode

## Exception:

Illegal instruction.

# Affected flag bits:

Floating-point status bit NV

# Instruction format:

31	25 24	20 19	15 14 12	11 7	6 0
1010000	fs2	fs1	010	rd	1010011

# 14.4.13 FLE.S: a single-precision floating-point compare less than or equal to instruction

## Syntax:

fle.s rd, fs1, fs2



# **Operation:**

 $\mathrm{if}(\mathrm{fs1}\,<=\,\mathrm{fs2})$ 

 $\mathrm{rd} \gets 1$ 

else

 $\mathrm{rd} \gets 0$ 

# Permission:

M mode/S mode/U mode

# Exception:

Illegal instruction.

# Affected flag bits:

Floating-point status bit NV

# Instruction format:

31	25 24	20	19 15	14 12	11 7	6 0
1010000		fs2	fs1	000	rd	1010011

# 14.4.14 FLT.S: a single-precision floating-point compare less than instruction

# Syntax:

flt.s rd, fs1, fs2

# **Operation:**

if(fs1 < fs2)

 $\mathrm{rd} \gets 1$ 

else

 $\mathrm{rd} \gets 0$ 

# Permission:

M mode/S mode/U mode

## Exception:

Illegal instruction.

# Affected flag bits:

Floating-point status bit NV

# Instruction format:



31	25	24 20	19 15	14 12	11 7	6 0
	1010000	fs2	fs1	001	rd	1010011

# 14.4.15 FLW: a single-precision floating-point load instruction

# Syntax:

flw fd, imm12(rs1)

## **Operation:**

 $address \leftarrow rs1 + sign\_extend(imm12)$ 

 $fd[31:0] \leftarrow mem[(address+3):address]$ 

 $fd[63:32] \leftarrow 32'$  hfffffff

## Permission:

M mode/S mode/U mode

### Exception:

Unaligned access, access error, page error, or Illegal instruction.

### Affected flag bits:

None

#### Instruction format:

31	20	19 15	14 12	11 7	6 0
imm12[11:0]		rs1	010	fd	0000111

# 14.4.16 FMADD.S: a single-precision floating-point multiply-add instruction

## Syntax:

fmadd.s fd, fs1, fs2, fs3, rm

# **Operation:**

 $rd \leftarrow fs1*fs2 + fs3$ 

#### **Permission:**

M mode/S mode/U mode

## Exception:

Illegal instruction.

## Affected flag bits:

Floating-point status bits NV, OF, UF, and IX



## Notes:

RM determines the round-off mode:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fmadd.s fd, fs1, fs2, fs3, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fmadd.s fd, fs1, fs2, fs3, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fmadd.s fd, fs1, fs2, fs3, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fmadd.s fd, fs1, fs2, fs3, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fmadd.s fd, fs1, fs2, fs3, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fmadd.s fd, fs1, fs2, fs3.

### Instruction format:

31	27	26 25	24	20	19 15	14 12	11 7	6	0
fs3		00	fs2		fs1	rm	fd	1000011	

# 14.4.17 FMAX.S: a single-precision floating-point MAX instruction

## Syntax:

fmax.s fd, fs1, fs2

## Operation:

 $if(fs1 \ge fs2)$ 

 $\mathrm{fd} \gets \mathrm{fs1}$ 

else

 $\mathrm{fd} \leftarrow \mathrm{fs2}$ 

## Permission:

M mode/S mode/U mode

## Exception:

Illegal instruction.

# Affected flag bits:



Floating-point status bit NV

### Instruction format:

31	25	24 2	0 19	15	14 12	11 7	6	0
00101	00	fs2	fs1		001	fd	1010011	

# 14.4.18 FMIN.S: a single-precision floating-point MIN instruction

# Syntax:

fmin.s fd, fs1, fs2

# **Operation:**

 $if(fs1 \ge fs2)$ 

 $\mathrm{fd} \leftarrow \mathrm{fs2}$ 

else

 $\mathrm{fd} \leftarrow \mathrm{fs1}$ 

### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

# Affected flag bits:

Floating-point status bit NV

### Instruction format:

31	25	24 20	19 15	14 12	11 7	6 0
0010100		fs2	fs1	000	fd	1010011

# 14.4.19 FMSUB.S: a single-precision floating-point multiply-subtract instruction

## Syntax:

fmsub.s fd, fs1, fs2, fs3, rm

# **Operation:**

 $\mathrm{fd} \leftarrow \mathrm{fs1*fs2}$ - fs3

# Permission:

M mode/S mode/U mode



# Exception:

Illegal instruction.

# Affected flag bits:

Floating-point status bits NV, OF, UF, and IX

# Notes:

RM determines the round-off mode:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fmsub.s fd, fs1, fs2, fs3, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fmsub.s fd, fs1, fs2, fs3, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fmsub.s fd, fs1, fs2, fs3, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fmsub.s fd, fs1, fs2, fs3, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fmsub.s fd, fs1, fs2, fs3, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fmsub.s fd, fs1, fs2, fs3.

# Instruction format:



# 14.4.20 FMUL.S: a single-precision floating-point multiply instruction

# Syntax:

fmul.s fd, fs1, fs2, rm

# **Operation:**

 $\mathrm{fd} \gets \mathrm{fs1} \, * \, \mathrm{fs2}$ 

# Permission:

M mode/S mode/U mode

# Exception:

Illegal instruction.



# Affected flag bits:

Floating-point status bits NV, OF, UF, and NX

# Notes:

RM determines the round-off mode:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fmul.s fd, fs1, fs2, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fmul.s fd, fs1, fs2, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fmul.s fd, fs1, fs2, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fmul.s fd, fs1, fs2, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fmul.s fd, fs1, fs2, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fmul.s fs1, fs2.

# Instruction format:



# 14.4.21 FMV.W.X: a single-precision floating-point write move instruction

# Syntax:

fmv.w.x fd, rs1

# **Operation:**

 $fd[31:0] \leftarrow rs[31:0]$ 

 $fd[63:32] \leftarrow 32'$  hfffffff

# Permission:

M mode/S mode/U mode

# Exception:

Illegal instruction.

# Affected flag bits:



None

# Instruction format:

31	25 24	4 20	19 15	14 12	11 7	6 0
1111000		00000	rs1	000	fd	1010011

# 14.4.22 FMV.X.H: a single-precision floating-point read move instruction

# Syntax:

fmv.x.w rd, fs1

# **Operation:**

 $tmp[31:0] \leftarrow fs1[31:0]$ 

 $rd \leftarrow sign\_extend(tmp[31:0])$ 

# **Permission:**

M mode/S mode/U mode

## Exception:

Illegal instruction.

## Affected flag bits:

None

# Instruction format:

31	25	24 20	19 15	14 12	11 7	6 0
	1110000	00000	fs1	000	rd	1010011

# 14.4.23 FNMADD.S: a single-precision floating-point negate-(multiply-add) instruction

## Syntax:

fnmadd.s fd, fs1, fs2, fs3, rm

## **Operation:**

 $fd \leftarrow -(fs1*fs2 + fs3)$ 

# Permission:

M mode/S mode/U mode

## Exception:

Illegal instruction.



# Affected flag bits:

Floating-point status bits NV, OF, UF, and IX

# Notes:

RM determines the round-off mode:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fnmadd.s fd, fs1, fs2, fs3, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fnmadd.s fd, fs1, fs2, fs3, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fnmadd.s fd, fs1, fs2, fs3, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fnmadd.s fd, fs1, fs2, fs3, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fnmadd.s fd, fs1, fs2, fs3, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fnmadd.s fd, fs1, fs2, fs3.

# Instruction format:

31 2	7 26 25	24 20	19 15	14 12	11 7	6 0
fs3	00	fs2	fs1	rm	fd	1001111

# 14.4.24 FNMSUB.S: a single-precision floating-point negate-(multiply-subtract) instruction

# Syntax:

fnmsub.s fd, fs1, fs2, fs3, rm

# **Operation:**

 $fd \leftarrow -(fs1*fs2 - fs3)$ 

## Permission:

M mode/S mode/U mode

# Exception:

Illegal instruction.

# Affected flag bits:



Floating-point status bits NV, OF, UF, and IX

## Notes:

RM determines the round-off mode:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fnmsub.s fd, fs1, fs2, fs3, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fnmsub.s fd, fs1, fs2, fs3, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fnmsub.s fd, fs1, fs2, fs3, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fnmsub.s fd, fs1, fs2, fs3, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fnmsub.s fd, fs1, fs2, fs3, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fnmsub.s fd, fs1, fs2, fs3.

## Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
fs3		00	fs2	fs1	rm	fd	1001011

# 14.4.25 FSGNJ.S: a single-precision floating-point sign-injection instruction

## Syntax:

fsgnj.<br/>s $\mathrm{fd},\,\mathrm{fs1},\,\mathrm{fs2}$ 

## **Operation:**

 $fd[30:0] \leftarrow fs1[30:0]$ 

 $\mathrm{fd}[31] \leftarrow \mathrm{fs2}[31]$ 

 $fd[63:32] \leftarrow 32'$  hffffffff

# Permission:

M mode/S mode/U mode

## Exception:

Illegal instruction.

## Affected flag bits:



None

# Instruction format:

31	25	24 20	19 15	14 12	11 7	6 0
	0010000	fs2	fs1	000	fd	1010011

# 14.4.26 FSGNJN.S: a single-precision floating-point negate sign-injection instruction

# Syntax:

fsgnjn.s fd, fs1, fs2

# **Operation:**

 $\mathrm{fd}[30{:}0] \leftarrow \mathrm{fs1}[30{:}0]$ 

 $\mathrm{fd}[31] \gets ! \ \mathrm{fs2}[31]$ 

 $fd[63:32] \leftarrow 32'$  hfffffff

# Permission:

M mode/S mode/U mode

# Exception:

Illegal instruction.

# Affected flag bits:

None

## Instruction format:



# 14.4.27 FSGNJX.S: a single-precision floating-point XOR sign-injection instruction

# Syntax:

fsgnjx.s fd, fs1, fs2

# **Operation:**

 $fd[30:0] \leftarrow fs1[30:0]$ 

 $\mathrm{fd}[31] \leftarrow \mathrm{fs1}[31] \,\widehat{}\, \mathrm{fs2}[31]$ 

 $fd[63:32] \leftarrow 32'$  hfffffff

# Permission:

M mode/S mode/U mode



# Exception:

Illegal instruction.

# Affected flag bits:

None

# Instruction format:



# 14.4.28 FSQRT.S: a single-precision floating-point square-root instruction

# Syntax:

fsqrt.s fd, fs1, rm

# **Operation:**

 $fd \leftarrow sqrt(fs1)$ 

# Permission:

M mode/S mode/U mode

# Exception:

Illegal instruction.

# Affected flag bits:

Floating-point status bits NV and NX

## Notes:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fsqrt.s fd, fs1, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fsqrt.s fd, fs1, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fsqrt.s fd, fs1, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fsqrt.s fd, fs1, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fsqrt.s fd, fs1, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.



• 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fsqrt.s fd, fs1.

# Instruction format:

31	25 24	20	19 15	14 12	11 7	6 0
0101100		00000	fs1	rm	fd	1010011

# 14.4.29 FSUB.S: a single-precision floating-point subtract instruction

# Syntax:

fsub.s fd, fs1, fs2, rm

# **Operation:**

 $\mathrm{fd} \gets \mathrm{fs1} \text{ - } \mathrm{fs2}$ 

# Permission:

M mode/S mode/U mode

## Exception:

Illegal instruction.

# Affected flag bits:

Floating-point status bits NV, OF, and NX

## Notes:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fsub.fd, fs1, fs2, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fsub.s fd, fs1, fs2, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fsub.s fd, fs1, fs2, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fsub.s fd, fs1, fs2, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fsub.s fd, fs1, fs2, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fsub.s fd, fs1, fs2.



Instruction format:

31	25	24 20	19 15	14 12	11 7	6 0
	0000100	fs2	fs1	rm	fd	1010011

# 14.4.30 FSW: a single-precision floating-point store instruction

## Syntax:

fsw fs2, imm12(rs1)

### **Operation:**

 $address \leftarrow rs1 + sign\_extend(imm12)$ 

 $mem[(address+31):address] \leftarrow fs2[31:0]$ 

## Permission:

M mode/S mode/U mode

### Exception:

Unaligned access, access error, page error, or illegal instruction.

### Instruction format:

31	25	24 20	19 15	14 12	11 7	6 0
	imm12[11:5]	fs2	rs1	010	imm12[4:0]	0100111

# 14.5 Appendix A-5 D instructions

The following describes the RISC-V D instructions implemented by C910. The instructions are 32 bits wide and sorted in alphabetic order.

When the fs bit in the mstatus register is 2' b00, running any instruction listed in this appendix will trigger an illegal instruction exception. When the fs bit in the mstatus register is not 2' b00, it is set to 2' b11 after any instruction listed in this appendix is executed.

# 14.5.1 FADD.D: a double-precision floating-point add instruction

# Syntax:

fadd.d fd, fs1, fs2, rm

# **Operation:**

 $\mathrm{fd} \leftarrow \mathrm{fs1} + \mathrm{fs2}$ 

## Permission:



M mode/S mode/U mode

# Exception:

Illegal instruction.

# Affected flag bits:

Floating-point status bits NV, OF, and NX

# Notes:

RM determines the round-off mode:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fadd.d fd, fs1, fs2, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fadd.d fd, fs1, fs2, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fadd.d fd, fs1, fs2, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fadd.d fd, fs1, fs2, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fadd.d fd, fs1, fs2, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fadd.d fd, fs1, fs2.

## Instruction format:



# 14.5.2 FCLASS.D: a double-precision floating-point classify instruction

## Syntax:

fclass.d rd, fs1

**Operation:** if (fs1 = -Inf)

 $rd \leftarrow 64'$  h1

- if ( fs1 = -norm)
  - $rd \leftarrow 64' h2$
- if ( fs1 = -subnorm)



0

1010011

7 6

# Chapter 14. Appendix A Standard Instructions

$$rd \leftarrow 64' h4$$
if (fs1 = -zero)  
fd \leftarrow 64' h8  
if (fs1 = +Zero)  
rd \leftarrow 64' h10  
if (fs1 = +subnorm)  
rd \leftarrow 64' h20  
if (fs1 = +norm)  
rd \leftarrow 64' h40  
if (fs1 = +Inf)  
rd \leftarrow 64' h80  
if (fs1 = sNaN)  
rd \leftarrow 64' h100  
if (fs1 = qNaN)  
rd \leftarrow 64' h200  
**Permission:**  
M mode/S mode/U mode  
**Exception:**  
Illegal instruction.  
**Affected flag bits:**  
None  
**Instruction format:**  

$$\frac{|31 \qquad 25 \ |24 \qquad 20 \ |19 \qquad 15 \ |14 \qquad 12 \ |11 \qquad |11 \ |11 \ |11 \ |11 \ |11 \ |11 \ |11 \ |11 \ |11 \ |11 \ |11 \ |11 \ |$$

# 14.5.3 FCVT.D.L: an instruction that converts a signed long integer into a doubleprecision floating-point number

# Syntax:

fcvt.d.l fd, rs1, rm

## **Operation:**

 $fd \leftarrow signed\_long\_convert\_to\_double(fs1)$ 



# Permission:

M mode/S mode/U mode

# Exception:

Illegal instruction.

# Affected flag bits:

Floating-point status bit NX

# Notes:

RM determines the round-off mode:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fcvt.d.l fd, rs1, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fcvt.d.l fd, rs1, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fcvt.d.l fd, rs1, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fcvt.d.l fd, rs1, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fcvt.d.l fd, rs1, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fcvt.d.l fd, rs1.

## Instruction format:

31	25	24 20	19 15	14 12	11 7	6 0
	1101001	00010	rs1	rm	fd	1010011

# 14.5.4 FCVT.D.LU: an instruction that converts an unsigned long integer into a double-precision floating-point number

# Syntax:

fcvt.d.lu fd, rs1, rm

## **Operation:**

 $fd \leftarrow unsigned\_long\_convert\_to\_double(fs1)$ 

# Permission:



M mode/S mode/U mode

# Exception:

Illegal instruction.

# Affected flag bits:

Floating-point status bit NX

# Notes:

RM determines the round-off mode:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fcvt.d.lu fd, rs1, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fcvt.d.lu fd, rs1, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fcvt.d.lu fd, rs1, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fcvt.d.lu fd, rs1, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fcvt.d.lu fd, rs1, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fcvt.d.lu fd, rs1.

# Instruction format:



# 14.5.5 FCVT.D.S: an instruction that converts a single-precision floating-point number into a double-precision floating-point number

# Syntax:

fcvt.d.s fd, fs1

# **Operation:**

 $fd \leftarrow single\_convert\_to\_double(fs1)$ 

# Permission:

M mode/S mode/U mode



# Exception:

Illegal instruction.

# Affected flag bits:

None

# Instruction format:



# 14.5.6 FCVT.D.W: an instruction that converts a signed integer into a double-precision floating-point number

### Syntax:

fcvt.d.w fd, rs1

# **Operation:**

 $fd \leftarrow signed\_int\_convert\_to\_double(fs1)$ 

# Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Affected flag bits:

None

## Instruction format:

31	25 24	20	19	15	14 12	11 7	6	0
1101001		00000	rs1		000	fd	1010011	

# 14.5.7 FCVT.D.WU: an instruction that converts an unsigned integer into a doubleprecision floating-point number

# Syntax:

fcvt.d.wu fd, rs1

## **Operation:**

 $fd \leftarrow unsigned\_int\_convert\_to\_double(fs1)$ 

## Permission:



M mode/S mode/U mode

# Exception:

Illegal instruction.

# Affected flag bits:

None

# Instruction format:

31	25 24 2	) 19 15	14 12	11 7	6 0
1101001	00001	rs1	000	fd	1010011

# 14.5.8 FCVT.L.D: an instruction that converts a double-precision floating-point number into a signed long integer

## Syntax:

fcvt.l.d rd, fs1, rm

# **Operation:**

 $rd \leftarrow double\_convert\_to\_signed\_long(fs1)$ 

# Permission:

M mode/S mode/U mode

## Exception:

Illegal instruction.

## Affected flag bits:

Floating-point status bits NV and NX

## Notes:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fcvt.l.d rd, fs1, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fcvt.l.d rd, fs1, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fcvt.l.d rd, fs1, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fcvt.l.d rd, fs1, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fcvt.l.d rd, fs1, rmm.



- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fcvt.l.d rd, fs1.

# Instruction format:

31	25	24 20	19 15	14 12	11 7	6 0
	1100001	00010	fs1	rm	rd	1010011

# 14.5.9 FCVT.LU.D: an instruction that converts a double-precision floating-point number into an unsigned long integer

# Syntax:

fcvt.lu.d rd, fs1, rm

# **Operation:**

 $rd \leftarrow double\_convert\_to\_unsigned\_long(fs1)$ 

# Permission:

M mode/S mode/U mode

## Exception:

Illegal instruction.

## Affected flag bits:

Floating-point status bits NV and NX

## Notes:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fcvt.lu.d rd, fs1, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fcvt.lu.d rd, fs1, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fcvt.lu.d rd, fs1, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fcvt.lu.d rd, fs1, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fcvt.lu.d rd, fs1, rmm.
- 3' b101: This code is reserved and not used.



- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fcvt.lu.d rd, fs1.

# Instruction format:

31	25 24	20	19 15	14 12	11 7	6 0
1100001		00011	fs1	rm	rd	1010011

# 14.5.10 FCVT.S.D: an instruction that converts a double-precision floating-point number into a single-precision floating-point number

## Syntax:

fcvt.s.d fd, fs1, rm

### **Operation:**

 $fd \leftarrow double\_convert\_to\_single(fs1)$ 

## Permission:

M mode/S mode/U mode

### Exception:

Illegal instruction.

## Affected flag bits:

Floating-point status bits NV, OF, UF, and NX

## Notes:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fcvt.s.d fd, fs1, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fcvt.s.d fd, fs1, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fcvt.s.d fd, fs1, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fcvt.s.d fd, fs1, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fcvt.s.d fd, fs1, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.



• 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fcvt.s.d fd, fs1.

# Instruction format:

31	25 24 20	19 15	14 12	11 7	6 0
0100000	00001	fs1	rm	fd	1010011

# 14.5.11 FCVT.W.D: an instruction that converts a double-precision floating-point number into a signed integer

## Syntax:

fcvt.w.d rd, fs1, rm

## **Operation:**

 $tmp \leftarrow double\_convert\_to\_signed\_int(fs1)$ 

 $rd \leftarrow sign\_extend(tmp)$ 

## Permission:

M mode/S mode/U mode

### Exception:

Illegal instruction.

## Affected flag bits:

Floating-point status bits NV and NX

## Notes:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fcvt.w.d rd, fs1, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fcvt.w.d rd, fs1, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fcvt.w.d rd, fs1, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fcvt.w.d rd, fs1, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fcvt.w.d rd, fs1, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.



• 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fcvt.w.d rd, fs1.

# Instruction format:

31	25 2	24 20	19 15	14 12	11 7	6 0
1	100001	00000	fs1	rm	rd	1010011

# 14.5.12 FCVT.WU.D: an instruction that converts a double-precision floating-point number into an unsigned integer

## Syntax:

fcvt.wu.d rd, fs1, rm

## **Operation:**

 $tmp \leftarrow double\_convert\_to\_unsigned\_int(fs1)$ 

 $rd \leftarrow sign\_extend(tmp)$ 

# Permission:

M mode/S mode/U mode

### Exception:

Illegal instruction.

## Affected flag bits:

Floating-point status bits NV and NX

## Notes:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fcvt.wu.d rd, fs1, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fcvt.wu.d rd, fs1, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fcvt.wu.d rd, fs1, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fcvt.wu.d rd, fs1, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fcvt.wu.d rd, fs1, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.



• 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fcvt.wu.d rd, fs1.

# Instruction format:

31	25	24 20	19 15	14 12	11 7	6 0
	1100001	00001	fs1	rm	rd	1010011

# 14.5.13 FDIV.D: a double-precision floating-point divide instruction

# Syntax:

fdiv.d fd, fs1, fs2, rm

# **Operation:**

 $fd \leftarrow fs1 / fs2$ 

## Permission:

M mode/S mode/U mode

## Exception:

Illegal instruction.

## Affected flag bits:

Floating-point status bits NV, DZ, OF, UF, and NX

## Notes:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fdiv.d fd, fs1, fs2, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fdiv.d fd fs1, fs2, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fdiv.d fd, fs1, fs2, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fdiv.d fd, fs1, fs2, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fdiv.d fd, fs1, fs2, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fdiv.d fd, fs1, fs2.



Instruction format:



# 14.5.14 FEQ.D: a double-precision floating-point compare equal instruction

# Syntax:

feq.d rd, fs1, fs2  $\,$ 

## **Operation:**

if(fs1 == fs2)

 $\mathrm{rd} \gets 1$ 

else

 $\mathrm{rd} \gets 0$ 

## Permission:

M mode/S mode/U mode

## Exception:

Illegal instruction.

## Affected flag bits:

Floating-point status bit NV

# Instruction format:



# 14.5.15 FLD: a double-precision floating-point load instruction

## Syntax:

fld fd, imm12(rs1)

## **Operation:**

 $address \leftarrow rs1 + sign\_extend(imm12)$ 

 $fd[63:0] \leftarrow mem[(address+7):address]$ 

# Permission:

M mode/S mode/U mode





# Exception:

Unaligned access, access error, page error, or illegal instruction.

# Affected flag bits:

None

# Instruction format:

31 20	19 15	14 12	11 7	6 0
imm12[11:0]	rs1	011	fd	0000111

# 14.5.16 FLE.D: a double-precision floating-point compare less than or equal to instruction

## Syntax:

fle.d rd, fs1, fs2

# **Operation:**

 $if(fs1 \le fs2)$ 

 $\mathrm{rd} \gets 1$ 

else

 $\mathrm{rd} \leftarrow 0$ 

## Permission:

M mode/S mode/U mode

## Exception:

Illegal instruction.

## Affected flag bits:

Floating-point status bit NV

## Instruction format:



# 14.5.17 FLT.D: a double-precision floating-point compare less than instruction

## Syntax:

flt.d rd, fs1, fs2

# **Operation:**




if(fs1 < fs2)

 $\mathrm{rd} \gets 1$ 

else

 $\mathrm{rd} \gets 0$ 

# Permission:

M mode/S mode/U mode

### Exception:

Illegal instruction.

## Affected flag bits:

Floating-point status bit NV

### Instruction format:

31	25 24 20	19 15	14 12	11 7	6 0
1010001	fs2	fs1	001	rd	1010011

# 14.5.18 FMADD.D: a double-precision floating-point multiply-add instruction

### Syntax:

fmadd.<br/>d $\operatorname{fd},\,\operatorname{fs1},\,\operatorname{fs2},\,\operatorname{fs3},\,\operatorname{rm}$ 

### **Operation:**

 $\mathrm{fd} \leftarrow \mathrm{fs1*fs2} + \mathrm{fs3}$ 

### Permission:

M mode/S mode/U mode

### Exception:

Illegal instruction.

### Affected flag bits:

Floating-point status bits NV, OF, UF, and IX

### Notes:

RM determines the round-off mode:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fmadd.d fd, fs1, fs2, fs3, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fmadd.d fd, fs1, fs2, fs3, rtz.



- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fmadd.d fd, fs1, fs2, fs3, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fmadd.d fd, fs1, fs2, fs3, rdn.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fmadd.d fd, fs1, fs2, fs3, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fmadd.d fd, fs1, fs2, fs3.

### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
fs	3	01	fs2	fs1	rm	fd	1000011

# 14.5.19 FMAX.D: a double-precision floating-point MAX instruction

#### Syntax:

fmax.d fd, fs1, fs2

### **Operation:**

 $if(fs1 \ge fs2)$ 

 $\mathrm{fd} \leftarrow \mathrm{fs1}$ 

else

 $\mathrm{fd} \gets \mathrm{fs2}$ 

### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

### Affected flag bits:

Floating-point status bit NV

31	25	24 20	19 15	14 12	11 7	6 0
	0010101	fs2	fs1	001	fd	1010011



# 14.5.20 FMIN.D: a double-precision floating-point MIN instruction

### Syntax:

fmin.d fd, fs1, fs2

### **Operation:**

 $if(fs1 \ge fs2)$ 

 $\mathrm{fd} \gets \mathrm{fs2}$ 

else

 $\mathrm{fd} \gets \mathrm{fs1}$ 

# Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

### Affected flag bits:

Floating-point status bit NV

#### Instruction format:

31	25	24 20	19 15	14 12	11 7	6 0
	0010101	fs2	fs1	000	fd	1010011

# 14.5.21 FMSUB.D: a double-precision floating-point multiply-subtract instruction

## Syntax:

fmsub.d fd, fs1, fs2, fs3, rm

### **Operation:**

 $\mathrm{fd} \leftarrow \mathrm{fs1*fs2}$ - fs3

### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

### Affected flag bits:

Floating-point status bits NV, OF, UF, and IX

### Notes:



RM determines the round-off mode:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fmsub.d fd, fs1, fs2, fs3, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fmsub.d fd, fs1, fs2, fs3, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fmsub.d fd, fs1, fs2, fs3, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fmsub.d fd, fs1, fs2, fs3, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fmsub.d fd, fs1, fs2, fs3, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fmsub.d fd, fs1, fs2, fs3.

### Instruction format:



# 14.5.22 FMUL.D: a double-precision floating-point multiply instruction

### Syntax:

fmul.d fd, fs1, fs2, rm

### **Operation:**

 $\mathrm{fd} \gets \mathrm{fs1} \, * \, \mathrm{fs2}$ 

### Permission:

M mode/S mode/U mode

### Exception:

Illegal instruction.

### Affected flag bits:

Floating-point status bits NV, OF, UF, and NX

### Notes:

RM determines the round-off mode:



- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fmul.d fd, fs1, fs2, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fmul.d fd, fs1, fs2, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fmul.d fd, fs1, fs2, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fmul.d fd, fs1, fs2, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fmul.d fd, fs1, fs2, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fmul. fd, fs1, fs2.

# Instruction format:

31 2	24 20	19 15	14 12	11 7	6 <mark>0</mark>
0001001	fs2	fs1	rm	fd	1010011

# 14.5.23 FMV.D.X: a double-precision floating-point write move instruction

### Syntax:

fmv.d.x fd, rs1

### **Operation:**

 $\mathrm{fd} {\leftarrow} \mathrm{rs1}$ 

### Permission:

M mode/S mode/U mode

### Exception:

Illegal instruction.

### Affected flag bits:

None

### Notes:

This instruction moves data from an integer register to a floating-point register.

31	25	24	20 1	19 15	14 12	11 7	6 (	)
11110	01	00000		rs1	000	fd	1010011	

# 14.5.24 FMV.X.D: a double-precision floating-point read move instruction

# Syntax:

fmv.x.d rd, fs1

### **Operation:**

 $\mathrm{rd} {\leftarrow} \mathrm{fs1}$ 

# Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Affected flag bits:

None

#### Notes:

This instruction moves data from a floating-point register to an integer register.

### Instruction format:

31 25	24 20	19 15	14 12	11 7	6 0
1110001	00000	fs1	000	rd	1010011

# 14.5.25 FNMADD.D: a double-precision floating-point negate-(multiply-add) instruction

### Syntax:

fnmadd.d fd, fs1, fs2, fs3, rm

### **Operation:**

 $fd \leftarrow -(fs1*fs2 + fs3)$ 

### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

### Affected flag bits:



Floating-point status bits NV, OF, UF, and IX

## Notes:

RM determines the round-off mode:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fnmadd.d fd, fs1, fs2, fs3, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fnmadd.d fd, fs1, fs2, fs3, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fnmadd.d fd, fs1, fs2, fs3, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fnmadd.d fd, fs1, fs2, fs3, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fnmadd.d fd, fs1, fs2, fs3, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fnmadd.d fd,fs1, fs2, fs3.

## Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	fs3	01	fs2	fs1	rm	fd	1001111

# 14.5.26 FNMSUB.D: a double-precision floating-point negate-(multiply-subtract) instruction

### Syntax:

fnmsub.d fd, fs1, fs2, fs3, rm

### **Operation:**

 $fd \leftarrow -(fs1*fs2 - fs3)$ 

### Permission:

M mode/S mode/U mode

# Exception:

Illegal instruction.

# Affected flag bits:

Floating-point status bits NV, OF, UF, and IX



# Notes:

RM determines the round-off mode:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fnmsub.d fd, fs1, fs2, fs3, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fnmsub.d fd, fs1, fs2, fs3, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fnmsub.d fd, fs1, fs2, fs3, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fnmsub.d fd, fs1, fs2, fs3, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fnmsub.d fd, fs1, fs2, fs3, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fnmsub.d fd,fs1, fs2, fs3.

# Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
f	s3	01	fs2	fs1	rm	fd	1001011

# 14.5.27 FSD: a double-precision floating-point store instruction

# Syntax:

fsd fs2, imm12(rs1)

# Operation:

 $address \leftarrow rs1 + sign\_extend(imm12)$ 

 $mem[(address+63):address] \leftarrow fs2[63:0]$ 

# Permission:

M mode/S mode/U mode

### Exception:

Unaligned access, access error, page error, or illegal instruction.

31	25	24 20	19 15	14 12	11 7	6 0
	imm12[11:5]	fs2	rs1	011	imm12[4:0]	0100111



# 14.5.28 FSGNJ.D: a double-precision floating-point sign-injection instruction

### Syntax:

fsgnj.d fd, fs1, fs2

### **O**peration:

 $\mathrm{fd}[62:0] \leftarrow \mathrm{fs1}[62:0]$ 

 $fd[63] \leftarrow fs2[63]$ 

### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

## Affected flag bits:

None

### Instruction format:

31	25 24 20	19 15	14 12	11 7	6 0
0010001	fs2	fs1	000	fd	1010011

# 14.5.29 FSGNJN.D: a double-precision floating-point negate sign-injection instruction

### Syntax:

fsgnjn.d fd, fs1, fs2

### **Operation:**

 $\mathrm{fd}[62:0] \leftarrow \mathrm{fs1}[62:0]$ 

 $fd[63] \leftarrow !fs2[63]$ 

### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

### Affected flag bits:

None

31	25	24 20	19 15	14 12	11 7	6 0
0010001		fs2	fs1	001	fd	1010011



# 14.5.30 FSGNJX.D: a double-precision floating-point XOR sign-injection instruction

### Syntax:

fsgnjx.d fd, fs<br/>1, fs2 $\,$ 

# **Operation:**

 $\mathrm{fd}[62:0] \leftarrow \mathrm{fs1}[62:0]$ 

 $\mathrm{fd}[63] \leftarrow \mathrm{fs1}[63] \widehat{\ } \mathrm{fs2}[63]$ 

## Permission:

M mode/S mode/U mode

### Exception:

Illegal instruction.

# Affected flag bits:

None

### Instruction format:

31 2	5 24 20	19 15	14 12	11 7	6 0
0010001	fs2	fs1	010	fd	1010011

# 14.5.31 FSQRT.D: a double-precision floating-point square-root instruction

### Syntax:

fsqrt.d fd, fs1, rm  $\,$ 

# **Operation:**

 $fd \leftarrow sqrt(fs1)$ 

# Permission:

 $M \mod/S \mod/U \mod$ 

### Exception:

Illegal instruction.

### Affected flag bits:

Floating-point status bits NV and NX

### Notes:

RM determines the round-off mode:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fsqrt.d fd, fs1, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fsqrt.d fd, fs1, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fsqrt.d fd, fs1, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fsqrt.d fd, fs1, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fsqrt.d fd, fs1, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fsqrt.d fd, fs1.

### Instruction format:

31	25 24	20 19	15	14 12	11 7	6 0
0101101	000	00	fs1	rm	fd	1010011

# 14.5.32 FSUB.D: a double-precision floating-point subtract instruction

### Syntax:

fsub.d fd, fs1, fs2, rm  $\,$ 

### **Operation:**

 $\mathrm{fd} \leftarrow \mathrm{fs1} \text{ - } \mathrm{fs2}$ 

### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

### Affected flag bits:

Floating-point status bits NV, OF, and NX

Notes:

RM determines the round-off mode:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fsub.fd, fs1, fs2, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fsub.d fd, fs1, fs2, rtz.



- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fsub.d fd, fs1, fs2, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fsub.d fd, fs1, fs2, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fsub.d fd, fs1, fs2, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fsub.dfd, fs1, fs2.

### Instruction format:

31	25 24	20 19	15 14 12	11 7	6 0
0000101	fs2	fs1	rm	fd	1010011

# 14.6 Appendix A-6 C Instructions

This section describes RISC-V C instructions implemented by C910. The instructions are 16 bits wide and sorted in alphabetic order.

# 14.6.1 C.ADD: a signed add instruction

### Syntax:

c.add rd, rs2

#### **Operation:**

 $rd \gets rs1 + rs2$ 

#### **Permission:**

M mode/S mode/U mode

#### Exception:

None

Notes:

rs1 = rd! = 0

rs2 ! = 0



15 13	12	11 7	6 2	1 0
100	1	rs1/rd	rs2	10

# 14.6.2 C.ADDI: a signed add immediate instruction

### Syntax:

c.addi rd, nzimm6

#### **Operation:**

 $rd \leftarrow rs1 + sign\_extend(nzimm6)$ 

#### Permission:

M mode/S mode/U mode

### Exception:

None

### Notes:

rs1 = rd! = 0

nzimm6!=0

## Instruction format:

15 1	3 12	11 7	6 2	1 0
000		rs1/rd	nzimm6[4:0]	01
		nzimm6[5]		

# 14.6.3 C.ADDIW: an add immediate instruction that operates on the lower 32 bits

#### Syntax:

c.addiw rd, imm6

#### **Operation:**

 $tmp[31:0] \leftarrow rs1[31:0] + sign\_extend(imm6)$ 

 $rd \leftarrow sign\_extend(tmp[31:0])$ 

#### Permission:

M mode/S mode/U mode

### Exception:

None



Notes:

rs1 = rd! = 0

Instruction format:

15	13	12	11	7	6	2	1	0
00	D1		rs1/rd		imm6[4:0]		(	)1
			imm6[5]					

# 14.6.4 C.ADDI4SPN: an instruction that adds an immediate scaled by 4 to the stack pointer

### Syntax:

c.addi4spn rd, sp, nzuimm8<<2

### **Operation:**

 $rd \leftarrow sp + zero\_extend(nzuimm8 < < 2)$ 

### Permission:

M mode/S mode/U mode

# Exception:

None

## Notes:

nzuimm8 != 0

Typical rd code registers are:

- 000 x8
- 001 x9
- 010 x10
- 011 x11
- 100 x12
- 101 x13
- 110 x14
- 111 x15

15 13	12 5	4 2	1 0
000	nzuimm8[3:2 7:4 0 1]	rd	00



# 14.6.5 C.ADDI16SP: an instruction that adds an immediate scaled by 16 to the stack pointer

### Syntax:

c.addi16sp sp, nzuimm6<<4

### **Operation:**

 $sp \leftarrow sp + sign\_extend(nzuimm6 < < 4)$ 

### **Permission:**

M mode/S mode/U mode

### Exception:

None

### Instruction format:

1	5	13	12	11		7	6			2	1	0
	011				00010							01
			n	zimm6[5]			nzimr	n6[0 :	2	4:3	3 1]	

# 14.6.6 C.ADDW: a signed add instruction that operates on the lower 32 bits

### Syntax:

c.addw rd, rs2

### **Operation:**

 $tmp[31:0] \leftarrow rs1[31:0] + rs2[31:0]$ 

 $rd \leftarrow sign\_extend(tmp[31:0])$ 

### **Permission:**

 $M \mod/S \mod/U \mod$ 

# Exception:

None

# Notes:

 $\mathrm{rs1}=\mathrm{rd}$ 

Typical rd/rs1 and rs2 code registers are:

- 000: x8
- 001: x9



- 010: x10
- 011: x11
- 100: x12
- 101: x13
- 110: x14
- 111: x15

Instruction format:

15	13	12	11	10	9	7	6	5	4		2	1	0
100		1	11	1	rs1	/rd	(	01		rs2			01

# 14.6.7 C.AND: a bitwise AND instruction

### Syntax:

c. and rd,  $\mathrm{rs}2$ 

## **Operation:**

 $rd \gets rs1 \ \& \ rs2$ 

# Permission:

M mode/S mode/U mode

# Exception:

None

# Notes:

rs1 = rd

Typical rd/rs1 and rs2 code registers are:

- 000: x8
- 001: x9
- 010: x10
- 011: x11
- 100: x12
- 101: x13
- 110: x14
- 111: x15



### Instruction format:

15 1	3 12	11 10	97	65	4 2	1 0
100	0	11	rs1/rd	11	rs2	01

# 14.6.8 C.ANDI: an immediate bitwise AND instruction

# Syntax:

c.andi rd, imm6

### **Operation:**

 $rd \leftarrow rs1 \& sign\_extend(imm6)$ 

### **Permission:**

M mode/S mode/U mode

### Exception:

None

# Notes:

rs1 = rd

Typical rd/rs1 code registers are:

- 000: x8
- 001: x9
- 010: x10
- 011: x11
- 100: x12
- 101: x13
- 110: x14
- 111: x15





# 14.6.9 C.BEQZ: a branch-if-equal-to-zero instruction

### Syntax:

c.beqz rs1, label

### **Operation:**

if (rs1 == 0)

next pc = current pc + imm8 << 1;

else

next pc = current pc + 2;

## Permission:

M mode/S mode/U mode

### Exception:

None

### Notes:

Typical rs1 code registers are:

- 000: x8
- 001: x9
- 010: x10
- 011: x11
- 100: x12
- 101: x13
- 110: x14
- 111: x15

The compiler calculates immediate 8 based on the label.

The jump range of the instruction is  $\pm 256$  B address space.





# 14.6.10 C.BNEZ: a branch-if-not-equal-to-zero instruction

### Syntax:

c.bnez rs1, label

### **Operation:**

```
if (rs1 != 0)
```

next pc = current pc + imm8 << 1;

else

next pc = current pc + 2;

# Permission:

M mode/S mode/U mode

#### Exception:

None

#### Notes:

Typical rs1 code registers are:

- 000: x8
- 001: x9
- 010: x10
- 011: x11
- 100: x12
- 101: x13
- 110: x14
- 111: x15

The compiler calculates immediate 12 based on the label.

The jump range of the instruction is  $\pm 256$  B address space.





# 14.6.11 C.EBREAK: a break instruction

### Syntax:

c.ebreak

### **Operation:**

Generates breakpoint exceptions or enables the core to enter the debug mode.

#### Permission:

M mode/S mode/U mode

### Exception:

Breakpoint exceptions

#### Instruction format:

15 13	12	11 7	6 2	1 0
100	1	00000	00000	10

# 14.6.12 C.FLD: a floating-point load doubleword instruction

#### Syntax:

c.fld fd, uimm5 < <3(rs1)

### **Operation:**

address  $\leftarrow$  rs1+ zero\_extend(uimm5<<3)

 $fd \leftarrow mem[address+7:address]$ 

### Permission:

M mode/S mode/U mode

### Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on load instructions

### Notes:

Typical rs1 code registers are:

- 000: x8
- 001: x9
- 010: x10
- 011: x11
- 100: x12



- 101: x13
- 110: x14
- 111: x15

Typical fd code registers are:

- 000: f8
- 001: f9
- 010: f10
- 011: f11
- 100: f12
- 101: f13
- 110: f14
- 111: f15

Instruction format:

15	13	12	10	9		7	6	5	4		2	1	0
011					rs1					fd			00
			uim	m5[2	2:0]			uim	m5	6[4:3]			

# 14.6.13 C.FLDSP: a floating-point doubleword load stack instruction

# Syntax:

c.fldsp fd, uimm6 < < 3(sp)

# **Operation:**

address  $\leftarrow$  sp+ zero\_extend(uimm6<<3)

 $fd \leftarrow mem[address+7:address]$ 

# Permission:

M mode/S mode/U mode

### Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on load instructions





# 14.6.14 C.FSD: a floating-point store doubleword instruction

## Syntax:

c.fsd fs2, uimm5 < < 3(rs1)

### **Operation:**

address  $\leftarrow$  rs1+ zero\_extend(uimm5<<3)

 $mem[address+7:address] \leftarrow fs2$ 

# Permission:

M mode/S mode/U mode

### Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on store instructions

### Notes:

Typical fs1 code registers are:

- 000: x8
- 001: x9
- 010: x10
- 011: x11
- 100: x12
- 101: x13
- 110: x14
- 111: x15

Typical rs2 code registers are:

- 000: f8
- 001: f9
- 010: f10
- 011: f11
- 100: f12





- 101: f13
- 110: f14
- 111: f15

Instruction format:

15	13	12	10	9	7	6	5	4		2	1	0
10	01			rs1					fs2			00
L			uim	m5[2:0]		u	imr	n5[	4:3]			

# 14.6.15 C.FSDSP: a floating-point store doubleword stack pointer instruction

## Syntax:

c.fsdsp fs2, uimm6 < < 3(sp)

## **Operation:**

address  $\leftarrow$  sp+ zero\_extend(uimm6<<3)

 $mem[address+7:address] \leftarrow fs2$ 

## Permission:

M mode/S mode/U mode

# Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on store instructions

### Instruction format:

15 :	13 12	7 6		2 1	0
101	uimm6	5[2:0 <b> </b> 5:3]	fs2		10

# 14.6.16 C.J: a unconditional jump instruction

### Syntax:

c.j label

### **Operation:**

next pc  $\leftarrow$  current pc + sign\_extend(imm << 1);

### Permission:

M mode/S mode/U mode



# Exception:

None

# Notes:

The compiler calculates immediate 11 based on the label.

The jump range of the instruction is  $\pm 2$  KB address space.

## Instruction format:

15 13	12 2	1	0
101	imm11[10 3 8:7 9 5 6 2:0 4]	Τ	01

# 14.6.17 C.JALR: a jump and link register instruction

### Syntax:

c.jalr rs1

### **Operation:**

next pc  $\leftarrow$  rs1;

 $x1 \leftarrow current pc + 2;$ 

### Permission:

M mode/S mode/U mode

# Exception:

None

### Notes:

rs1 != 0.

When MMU is enabled, the jump range is the entire 512 GB address space.

When MMU is disabled, the jump range is the entire 1 TB address space.

### Instruction format:

15	13	12	11	76	2	1	0
100		1	rs1		00000		10

# 14.6.18 C.JR: a jump register instruction

### Syntax:

c.jr rs1





# **Operation:**

next pc = rs1;

# Permission:

M mode/S mode/U mode

# Exception:

None

## Notes:

rs<br/>1 $!=0_{\,\circ}$ 

When MMU is enabled, the jump range is the entire 512 GB address space.

When MMU is disabled, the jump range is the entire 1 TB address space.

## Instruction format:

15	13	12	11 7	6 2	1 0
10	0	0	rs1	00000	10

# 14.6.19 C.LD: a load doubleword instruction

### Syntax:

c.ld rd, uimm5 < <3(rs1)

# **Operation:**

address  $\leftarrow$  rs1+ zero\_extend(uimm5<<3)

 $rd \leftarrow mem[address + 7:address]$ 

### Permission:

M mode/S mode/U mode

### Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on load instructions

### Notes:

Typical rs1/rd code registers are:

- 000: x8
- 001: x9
- 010: x10
- 011: x11



- 100: x12
- 101: x13
- 110: x14
- 111: x15

# Instruction format:



# 14.6.20 C.LDSP: a load doubleword instruction

## Syntax:

c.ldsp rd, uimm6 << 3(sp)

## **Operation:**

address  $\leftarrow$  sp+ zero\_extend(uimm6<<3)

 $rd \leftarrow mem[address+7:address]$ 

# Permission:

M mode/S mode/U mode

# Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on load instructions

Notes:

rd != 0

# Instruction format:



# 14.6.21 C.LI: a load immediate instruction

# Syntax:

c.li rd, imm6

# **Operation:**



 $rd \leftarrow sign\_extend(imm6)$ 

### Permission:

M mode/S mode/U mode

# Exception:

None

Notes:

 $\mathrm{rd} \mathrel{!=} 0$ 

## Instruction format:

15	13	12	11	76	2	2	1	0
01	L <b>O</b>		rd		imm[4:0]		(	)1
			—imm[5]					

# 14.6.22 C.LUI: a load upper immediate instruction

# Syntax:

c.lui rd, nzimm6

# **Operation:**

rd  $\leftarrow$ sign\_extend(nzimm6<<12)

# Permission:

M mode/S mode/U mode

## Exception:

None

# Notes:

 $\mathrm{rd} \mathrel{!=} 0 \, .$ 

Nzimm6  $!= 0_{\circ}$ 





# 14.6.23 C.LW: a load word instruction

### Syntax:

c.lw rd, uimm5 < < 2(rs1)

### **Operation:**

address  $\leftarrow$  rs1+ zero\_extend(uimm5<<2)

 $tmp[31:0] \leftarrow mem[address+3:address]$ 

 $rd \leftarrow sign\_extend(tmp[31:0])$ 

### Permission:

M mode/S mode/U mode

### Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on load instructions

#### Notes:

Typical rs1/rd code registers are:

- 000: x8
- 001: x9
- 010: x10
- 011: x11
- 100: x12
- 101: x13
- 110: x14
- 111: x15

#### Instruction format:



# 14.6.24 C.LWSP: a load word stack pointer instruction

#### Syntax:

c.lwsp rd, uimm6 < < 2(sp)

#### **Operation:**



address  $\leftarrow$  sp+ zero\_extend(uimm6<<2)

 $tmp[31:0] \leftarrow mem[address+3:address]$ 

 $rd \leftarrow sign\_extend(tmp[31:0])$ 

# Permission:

M mode/S mode/U mode

### Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on load instructions

#### Notes:

 $\mathrm{rd} \mathrel{!=} 0$ 

### Instruction format:

15	13	12	11	7	6 2	1	0
010			rd		umm6[2:0 5:4]		10
			-uimm6[3]				

# 14.6.25 C.MV: an instruction that copies the value in rs to rd

### Syntax:

c.mv rd, rs2

### Operation:

 $rd \leftarrow rs2;$ 

### Permission:

M mode/S mode/U mode

### Exception:

None

### Notes:

rs2 != 0, rd !=0.

15 1	3 12	11 7	6 2	1 0
100	0	rd	rs2	10



# 14.6.26 C.NOP: a no-operation instruction

Syntax:

c.nop

### **Operation:**

No operations

### Permission:

M mode/S mode/U mode

### Exception:

None

# Instruction format:

 15 13	12	11 7	6 2	1 0
000	0	00000	00000	01

# 14.6.27 C.OR: a bitwise OR instruction

### Syntax:

 ${\rm c.or}~{\rm rd},\,{\rm rs2}$ 

### **Operation:**

 $rd \gets rs1 \mid rs2$ 

### Permission:

M mode/S mode/U mode

### Exception:

None

Notes:

rs1 = rd

Typical rd/rs1 code registers are:

- 000: x8
- 001: x9
- 010: x10
- 011: x11
- 100: x12



- 101: x13
- 110: x14
- 111: x15

Instruction format:

15 13	12	11 10	97	65	4 2	1 0
100	0	11	rs1/rd	10	rs2	01

# 14.6.28 C.SD: a store doubleword instruction

# Syntax:

c.sd rs2, uimm5 < <3(rs1)

## **Operation:**

address  $\leftarrow$  rs1+ zero\_extend(uimm5<<3)

 $mem[address+7:address] \leftarrow rs2$ 

## Permission:

M mode/S mode/U mode

### Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on store instructions

# Notes:

Typical rs1/rd code registers are:

- 000: x8
- 001: x9
- 010: x10
- 011: x11
- 100: x12
- 101: x13
- 110: x14
- 111: x15





# 14.6.29 C.SDSP: a store doubleword stack pointer instruction

### Syntax:

c.fsdsp rs2, uimm6 < < 3(sp)

## **Operation:**

address  $\leftarrow$  sp+ zero\_extend(uimm6<<3)

 $mem[address+7:address] \leftarrow rs2$ 

### Permission:

M mode/S mode/U mode

### Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on store instructions

### Instruction format:

15 13	12 7	6 2	1 0
111	uimm6[2:0 5:3]	rs2	10

# 14.6.30 C.SLLI: an immediate logical left shift instruction

# Syntax:

c.slli rd, nzuimm6

### **Operation:**

rd  $\leftarrow \! \mathrm{rs1} << \mathrm{nzuimm6}$ 

### **Permission:**

M mode/S mode/U mode

### Exception:

None

### Notes:

rs1 == rd

rd/rs1 = 0, nzuimm6 = 0



# Instruction format:



# 14.6.31 C.SRAI: a right shift arithmetic immediate instruction

### Syntax:

c.srli rd, nzuimm6

### **Operation:**

 $\rm rd \leftarrow \rm rs1 >>> \rm nzuimm6$ 

### Permission:

M mode/S mode/U mode

# Exception:

None

Notes:

nzuimm6 != 0

rs1 == rd

Typical rs1/rd code registers are:

- 000: x8
- 001: x9
- 010: x10
- 011: x11
- 100: x12
- 101: x13
- 110: x14
- 111: x15



# 14.6.32 C.SRLI: an immediate right shift instruction

### Syntax:

c.srli rd, nzuimm6

### **Operation:**

rd  $\leftarrow \! \mathrm{rs1} >> \mathrm{nzuimm6}$ 

### Permission:

M mode/S mode/U mode

### Exception:

None

Notes:

nzuimm6 != 0

rs1 == rd

Typical rs1/rd code registers are:

- 000: x8
- 001: x9
- 010: x10
- 011: x11
- 100: x12
- 101: x13
- 110: x14
- 111: x15

### Instruction format:

15	13	12	11 10	9	7	6	2	1	0
	100		00	rs1,	rs1/rd nzuimm6[4:0]			01	
			—nzui	mm6[5	5]				

# 14.6.33 C.SW: a store word instruction

# Syntax:

c.sw rs2, uimm5 < < 2(rs1)

### **Operation:**





address  $\leftarrow$  rs1+ zero\_extend(uimm5<<2)

 $mem[address{+}3{:}address] \leftarrow rs2$ 

# Permission:

M mode/S mode/U mode

# Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on store instructions

## Notes:

Typical rs1/rs2 code registers are:

- 000: x8
- 001: x9
- 010: x10
- 011: x11
- 100: x12
- 101: x13
- 110: x14
- 111: x15

Instruction format:

15	13	12	10	9	7	6	5	4	2		1	0
11	10			r	s1				rs2		(	00
uimm5[3:				า5 <mark>[</mark> 3:1	]		–ui	mm5[	0	4]		

# 14.6.34 C.SWSP: a store word stack pointer instruction

# Syntax:

c.swsp rs2, uimm6 << 2(sp)

### **Operation:**

address  $\leftarrow$  sp+ zero\_extend(uimm6<<2)

 $mem[address+3:address] \leftarrow rs2$ 

### Permission:

M mode/S mode/U mode





# Exception:

Unaligned access exceptions, access error exceptions, and page error exceptions on store instructions

### Instruction format:

15 13	12 7	6 2	1 0
110	uimm6[3:0 5:4]	rs2	10

# 14.6.35 C.SUB: a signed subtract instruction

# Syntax:

c.sub rd, rs2

# **Operation:**

 $rd \gets rs1 \text{ - } rs2$ 

### Permission:

 $M \mod/S \mod/U \mod$ 

### Exception:

None

### Notes:

rs1 == rd

Typical rs1/rd code registers are:

- 000: x8
- 001: x9
- 010: x10
- 011: x11
- 100: x12
- 101: x13
- 110: x14
- 111: x15

15	13 1	12	11 10	97	65	4 2	1 0
100		0	11	rs1/rd	00	rs2	01


## 14.6.36 C.SUBW: a signed subtract instruction that operates on the lower 32 bits

#### Syntax:

c.subw rd, rs2

## **Operation:**

 $tmp[31:0] \leftarrow rs1[31:0] - rs2[31:0]$ 

 $rd \leftarrow sign\_extend(tmp)$ 

### Permission:

 $M \mod/S \mod/U \mod$ 

## Exception:

None

## Notes:

rs1 == rd

Typical rs1/rd code registers are:

- 000: x8
- 001: x9
- 010: x10
- 011: x11
- 100: x12
- 101: x13
- 110: x14
- 111: x15

Instruction format:

15 1	13 12	11 10	9 7	65	4 2	1 0
100	1	11	rs1/rd	00	rs2	01

## 14.6.37 C.XOR: a bitwise XOR instruction

## Syntax:

c.xor rd, rs2

#### **Operation:**

 $rd \gets rs1 \ \widehat{} \ rs2$ 





## Permission:

M mode/S mode/U mode

### Exception:

None

## Notes:

rs1 == rd

Typical rs1/rd code registers are:

- 000: x8
- 001: x9
- 010: x10
- 011: x11
- 100: x12
- 101: x13
- 110: x14
- 111: x15

Instruction format:

15 1	3 12	11 10	97	65	4 2	1 0
100	0	11	rs1/rd	01	rs2	01

## 14.7 Appendix A-8 Pseudo instructions

RISC-V implements a series of pseudo instructions. The instructions listed in this section are for reference only and are sorted in alphabetic order.

Pseudo instruction	Base instruction	Meaning
beqz rs, offset	beq rs, x0, offset	Takes the branch if rs is zero.
bnez rs, offset	bne rs, x0, offset	Takes the branch if rs is not zero.
blez rs, offset	bge x0,rs, offset	Takes the branch if rs is less than
		or equal to zero.
bgez rs, offset	bge rs, x0, offset	Takes the branch if rs is greater
		than or equal to zero.
bltz rs, offset	blt rs, x0, offset	Takes the branch if rs is less than
		zero.

Continued on next page



Pseudo instruction	Base instruction	Meaning
bgtz rs, offset	blt x0, xs, offset	Takes the branch if rs is greater
		than zero.
bgt rs, rt, offset	blt rt, rs, offset	Takes the branch if rs is greater
		than rt.
ble rs, rt, offset	bge rt, rs, offset	Takes the branch if rs is less than
		or equal to rt.
bgtu rs, rt, offset	bltu rt, rs, offset	Takes the branch if rs is greater
		than rt, using unsigned compari-
		son.
bleu rs, rt, offset	bgeu rt, rs, offset	Takes the branch if rs is less than
		or equal to rt, using unsigned
		comparison.
call offset	auipc x6, offset[31:12]	Calls far-away subroutine.
	jalr x1, x6, offset[11:0]	
csrc csr, rs	csrrc x0, csr, rs	Clears bits in the control/status
		register (CSR).
csrci csr, imm	csrrci x0, csr, imm	Clears bits in the CSR, immedi-
		ate.
csrs csr, rs	csrrs x0, csr, rs	Sets bits in the CSR.
csrsi csr, imm	csrrsi x0, csr, imm	Sets bits in the CSR, immediate
csrw csr, rs	csrrw x0, csr, rs	Writes the CSR.
csrwi csr, imm	csrrwi x0, csr, imm	Writes the CSR, immediate.
fabs.d rd, rs	fsgnjx.d rd, rs, rs	Calculates the double-precision
		floating point (FP) absolute
		value.
fabs.s rd, rs	fsgnjx.s rd, rs, rs	Calculates the single-precision
		FP absolute value.
fence	fence iorw, iorw	Fences on all memory and I/O.
$fl\{w d\}$ rd, symbol, rt	auipc rt, symbol[31:12]	An FP load global instruction.
	$fl\{w d\} rd, symbol[11:0](rt)$	
fmv.d rd, rs	fsgnj.d rd, rs, rs	A double-precision FP copy in-
		struction.
fmv.s rd, rs	fsgnj.s rd, rs, rs	A single-precision FP copy in-
		struction.
fneg.d rd, rs	fsgnjn.d rd, rs, rs	A double-precision FP negate in-
		struction.
fneg.s rd, rs	fsgnjn.s rd, rs, rs	A single-precision FP negate in-
		struction.

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Pseudo instruction	Base instruction	Meaning
frcsr rd	csrrs x0, fcsr, x0	Reads FP CSR.
frflags rd	csrrs rd, fflags, x0	Reads FP exception flags.
frrm rd	csrrs rd, frm, x0	Reads FP rounding mode.
fscsr rs	csrrw x0, fcsr, rs	Writes FP CSR.
fscsr rd, rs	csrrs rd, fcsr, rs	Swaps FP CSR.
fsflags rs	csrrw x0, fcsr, rs	Writes FP exception flags.
fsflags rd, rs	csrrs rd, fcsr, rs	Swaps FP exception flags.
fsflagsi imm	csrrwi x0, fflags, imm	Writes FP exception flags, imme-
		diate.
fsflagsi rd, imm	csrrwi rd, fflags, imm	Swaps FP exception flags, imme-
		diate.
fsrm rs	csrrw x0, frm, rs	Writes FP rounding mode.
fsrm rd, rs	csrrs rd, frm, rs	Swaps FP rounding mode.
fsrmi imm	csrrwi x0, frm, imm	Writes FP rounding mode, imme-
		diate.
fsrmi rd, imm	csrrwi rd, frm, imm	Swaps FP rounding mode, imme-
		diate.
fs{w d} rd, symbol,rt	auipc rt,symbol[31:12]	An FP store global instruction.
	$fs{w d} rd, symbol[11:0](rt)$	
j offset	jal x0, offset	A jump instruction.
jal offset	jal x1, offset	Jumps to subroutine and link.
jalr rs	jalr x1, rs, 0	Jumps to subroutine and links
		register.
jr rs	jalr x0, rs, 0	A jump register instruction.
la rd, symbol	auipc rd, symbol[31:12]	A load address instruction.
	addi rd, rd, symbol[11:0]	
li rd, immediate	Split into multiple instructions	A load immediate instruction
	based on the size of the immedi-	
	ate	
l{b h w d} rd,symbol, rt	auipc rt,   symbol[31:12]	A load global instruction.
	$l\{b h w d\} rd,symbol[11:0](rt)$	
mv rd, rs	addi rd, rs, 0	A instruction that copies the
		value in rs to rd.
neg rd, rs	sub rd, x0, rs	A register negate instruction.
negw rd, rs	subw rd, x0, rs	Negates the lower 32 bits of reg-
		isters.
nop	addi x0,x0,0	A no operation instruction.
not rd, rs	xori rd, rs, -1	A register NOT instruction.

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Pseudo instruction	Base instruction	Meaning	
rdcycle[h] rd	csrrs rd, cycle[h], x0	A read cycle counter instruction.	
rdinstret[h] rd	csrrs rd, instret[h], x0	Reads instructions-retired	
		counter.	
rdtime[h] rd	csrrs rd, time[h], x0	Reads real-time clock.	
ret	jalr x0, x1,0	Returns from subroutine.	
$s{b h w d} rd$ , symbol, rt	auipc rt,symbol[31:12]	A store global instruction.	
	$s{b h w d} rd,symbol[11:0](rt)$		
seqz rd, rs	sltiu rd, rs, 1	Sets 0 in registers to 1.	
sextw rd, rs	addiw rd, rs, 0	A sign extend word instruction.	
sgtz rd, rs	slt rd, rs, x0, rs	Sets rd to 1 if rs is greater than	
		zero.	
sltz rd, rs	slt rd, rs, rs, x0	Sets rd to 1 if rs is less than zero.	
snez rd, rs	sltu rd, rs, x0, rs	Sets rd to 1 if rs is not equal to	
		zero.	
tail offset	auipc x6,offset[31:12]	Tail call far-away subroutine.	
	jalr x0, x6,offset[11:0]		

Table	14.1 –	continued	from	previous	page
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## Chapter 15

## Appendix B T-Head Extended Instructions

Apart from the GC instruction sets defined in the standard, C910 provides custom instruction sets, including the cache instruction set, synchronization instruction set, arithmetic operation instruction set, bitwise operation instruction set, storage instruction set, and half-precision floating-point instruction set.

Among these instruction sets, the cache instructions, synchronization instructions, arithmetic operation instructions, bitwise operation instructions, and storage instructions can be executed only when the value of mxstatus.theadisaee is 1. Otherwise, an instruction exception will occur. Half-precision floating-point instructions can be executed only when the value of mstatus.fs ! is 2' b00. Otherwise, an illegal instruction exception will occur. The following describes each instruction in these instruction sets.

## 15.1 Appendix B-1 Cache instructions

You can use the cache instruction set to manage caches. Each instruction has 32 bits.

Arithmetic operation instructions in this instruction set are described in alphabetical order.

## 15.1.1 DCACHE.CALL: an instruction that clears all dirty page table entries in the D-Cache

Syntax:

dcache.call

**Operation:** 



Clears all page table entries in the L1 D-Cache and writes all dirty page table entries back into the next-level storage. You can perform this operation only on the current core.

#### **Permission:**

M mode/S mode

#### Exception:

Illegal instruction.

#### Notes:

If the value of mxstatus.theadisaee is 0, executing this instruction causes an exception of illegal instruction.

If the value of mxstatus.theadisaee is 1, executing this instruction in U mode causes an exception of illegal instruction.

#### Instruction format:



# 15.1.2 DCACHE.CIALL: an instruction that clears all dirty page table entries in the D-Cache and invalidates the D-Cache

#### Syntax:

dcache.ciall

#### **Operation:**

Writes all dirty page table entries in the L1 D-Cache back into the next-level storage and invalidates all these page table entries.

#### Permission:

M mode/S mode

#### Exception:

Illegal instruction.

#### Notes:

If the value of mxstatus.theadisaee is 0, executing this instruction causes an exception of illegal instruction.

If the value of mxstatus.theadisaee is 1, executing this instruction in U mode causes an exception of illegal instruction.

31	25	24 20	19 15	14 12	11 7	6 <b>0</b>
	000000	00011	00000	000	00000	0001011

# 15.1.3 DCACHE.CIPA: clears dirty page table entries that match the specified physical addresses from the D-Cache and invalidates the the D-Cache

#### Syntax:

dcache.cipa rs1

#### **Operation:**

Writes page table entries that match the specified physical addresses of the D-Cache or L2 Cache of rs1 back into the next-level storage and invalidates these page table entries. You can perform this operation on all cores and the L2 Cache.

#### Permission:

M mode/S mode

#### Exception:

Illegal instruction.

#### Notes:

If the value of mxstatus.theadisaee is 0, executing this instruction causes an exception of illegal instruction.

If the value of mxstatus.theadisaee is 1, executing this instruction in U mode causes an exception of illegal instruction.

#### Instruction format:



## 15.1.4 DCACHE.CISW: an instruction that clears dirty page table entries in the D-Cache based on the specified way and set and invalidates the D-Cache

#### Syntax:

dcache.cisw rs1

#### **Operation:**

Writes the dirty page table entry that matches the specified way and set from the L1 Cache of rs1 back into the next-level storage and invalidates this page table entry. You can perform this operation only on the current core.



### Permission:

M mode/S mode

#### Exception:

Illegal instruction.

### Notes:

C910 D-Cache is a 2-way set-associative cache. rs1[31] specifies the way and rs1[s:6] specifies the set. When the size of the D-Cache is 32 KB, w denotes 13. When the size of the D-Cache is 64 KB, w denotes 14, and so forth.

- If the value of mxstatus.theadisaee is 0, executing this instruction causes an exception of illegal instruction.
- If the value of mxstatus.theadisaee is 1, executing this instruction in U mode causes an exception of illegal instruction.

Instruction format:

31	25 24	20 19	15 14 1	2 11 7	6 0
0000001	00011	rs1	000	00000	0001011

## 15.1.5 DCACHE.CIVA: an instruction that clears dirty page table entries that match the specified virtual addresses in the D-Cache and invalidates the D-Cache

#### Syntax:

dcache.civa rs1

#### **Operation:**

Writes the page table entry that matches the specified virtual address from the D-Cache or L2 Cache of rs1 back into the next-level storage and invalidates this page table entry. You can perform this operation on the current core and the L2 Cache. The sharing attribute of the virtual address determines whether you can perform this operation on other cores.

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction or error page during instruction loading.

#### Notes:

• If the value of mxstatus.theadisaee is 0, executing this instruction causes an exception of illegal instruction.

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- If the value of mxstatus.theadisaee is 1 and the value of mxstatus.ucme is 1, this instruction can be executed in U mode.
- If the value of mxstatus.theadisaee is 1 and the value of mxstatus.ucme is 0, executing this instruction in U mode causes an exception of illegal instruction.

#### Instruction format:

31	25	24 20	19 15	14 12	11 7	6 0
	0000001	00111	rs1	000	00000	0001011

## 15.1.6 DCACHE.CPA: an instruction that clears dirty page table entries that match the specified physical addresses from the D-Cache

#### Syntax:

dcache.cpa rs1

### **Operation:**

Writes the page table entry that matches the specified physical address from the D-Cache or L2 Cache of rs1 back into the next-level storage. You can perform this operation on all cores and the L2 Cache.

#### Permission:

M mode/S mode

#### Exception:

Illegal instruction.

#### Notes:

If the value of mxstatus.theadisaee is 0, executing this instruction causes an exception of illegal instruction.

If the value of mxstatus.theadisaee is 1, executing this instruction in U mode causes an exception of illegal instruction.

## Instruction format:

3	25	24 20	19 15	14 12	11 7	6 0
	0000001	01001	rs1	000	00000	0001011

# 15.1.7 DCACHE.CPAL1: an instruction that clears dirty page table entries that match the specified physical addresses from the L1 D-Cache

## Syntax:

dcache.cpal1 rs1



**Operation:** Writes the page table entry that matches the specified physical address from the D-Cache of rs1 back into the next-level storage. You can perform this operation on all cores and the L1 Cache.

#### Permission:

M mode/S mode

#### Exception:

Illegal instruction.

#### Notes:

If the value of mxstatus.theadisaee is 0, executing this instruction causes an exception of illegal instruction.

If the value of mxstatus.theadisaee is 1, executing this instruction in U mode causes an exception of illegal instruction.

#### Instruction format:



# 15.1.8 DCACHE.CVA: an instruction that clears dirty page table entries that match the specified virtual addresses in the D-Cache

#### Syntax:

dcache.cva rs1

#### **Operation:**

Writes the page table entry that matches the specified virtual address from the D-Cache or L2 Cache of rs1 back into the next-level storage. You can perform this operation on the current core and the L2 Cache. The sharing attribute of the virtual address determines whether you can perform this operation on other cores.

#### Permission:

M mode/S mode

#### Exception:

Illegal instruction or error page during instruction loading.

#### Notes:

If the value of mxstatus.theadisaee is 0, executing this instruction causes an exception of illegal instruction.

If the value of mxstatus.theadisaee is 1, executing this instruction in U mode causes an exception of illegal instruction.

Instruction format:

31	25 2	24 20	19 15	14 12	11 7	6 0
0000001		00101	rs1	000	00000	0001011

# **15.1.9 DCACHE.CVAL1:** an instruction that clears dirty page table entries that match the specified virtual addresses in the L1 D-Cache

#### Syntax:

dcache.cval1 rs1

#### **Operation:**

Writes the page table entry that matches the specified virtual address from the D-Cache of s1 back into the next-level storage. You can perform this operation on all cores and the L1 Cache.

#### **Permission:**

M mode/S mode/U mode

#### **Exception:**

Illegal instruction or error page during instruction loading.

#### Notes:

If the value of mxstatus.theadisaee is 0, executing this instruction causes an exception of illegal instruction.

If the value of mxstatus.theadisaee is 1 and the value of mxstatus.ucme is 0, executing this instruction in U mode causes an exception of illegal instruction.

#### Instruction format:



# 15.1.10 DCACHE.IPA: an instruction that invalidates page table entries that match the specified physical addresses in the D-Cache

#### Syntax:

dcache.ipa rs1

#### Operation:

Invalidates the page table entry that matches the specified physical address in the D-Cache or L2 Cache of rs1. You can perform this operation on all cores and the L2 Cache.

#### Permission:



M mode/S mode

#### Exception:

Illegal instruction.

#### Notes:

- If the value of mxstatus.theadisaee is 0, executing this instruction causes an exception of illegal instruction.
- If the value of mxstatus.theadisaee is 1, executing this instruction in U mode causes an exception of illegal instruction.

### Instruction format:

31	25	24 20	19 15	14 12	11 7	6 0
	000001	01010	rs1	000	00000	0001011

# 15.1.11 DCACHE.ISW: an instruction that invalidates page table entries in the D-Cache based on the specified way and set and invalidates the D-Cache

### Syntax:

dcache.isw rs1  $\,$ 

#### **Operation:**

Invalidates the page table entry in the D-Cache based on the specified set and way. You can perform this operation only on the current core.

#### Permission:

M mode/S mode

#### Exception:

Illegal instruction.

#### Notes:

C910 D-Cache is a 2-way set-associative cache. rs1[31] specifies the way and rs1[s:6] specifies the set. When the size of the D-Cache is 32 KB, w denotes 13. When the size of the D-Cache is 64 KB, w denotes 14, and so forth.

- If the value of mxstatus.theadisaee is 0, executing this instruction causes an exception of illegal instruction.
- If the value of mxstatus.theadisaee is 1, executing this instruction in U mode causes an exception of illegal instruction.

#### Instruction format:

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31 25	24 20	19 15	14 12	11 7	6 0
0000001	00010	rs1	000	00000	0001011

## 15.1.12 DCACHE.IVA: an instruction that invalidates the D-Cache based on the specified virtual address

#### Syntax:

dcache.iva ${\rm rs1}$ 

#### **Operation:**

Invalidates the page table entry that matches the specified virtual address from the D-Cache or L2 Cache of rs1. You can perform this operation on the current core and the L2 Cache. The sharing attribute of the virtual address determines whether you can perform this operation on other cores.

#### Permission:

M mode/S mode

#### Exception:

Illegal instruction or error page during instruction loading.

#### Notes:

- If the value of mxstatus.theadisaee is 0, executing this instruction causes an exception of illegal instruction.
- If the value of mxstatus.theadisaee is 1, executing this instruction in U mode causes an exception of illegal instruction.

#### Instruction format:



# 15.1.13 DCACHE.IALL: an instruction that invalidates all page table entries in the D-Cache.

#### Syntax:

dcache.iall

#### Operation:

Invalidates all page table entries in the L1 Cache. You can perform this operation only on the current core.

#### Permission:

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M mode/S mode

#### Exception:

Illegal instruction.

#### Notes:

- If the value of mxstatus.theadisaee is 0, executing this instruction causes an exception of illegal instruction.
- If the value of mxstatus.theadisaee is 1, executing this instruction in U mode causes an exception of illegal instruction.

### Instruction format:

31	25	24 20	19	15 14	12	11 7	6	0
0000000		00010	00000		000	00000	0001011	

# 15.1.14 ICACHE.IALL: an instruction that invalidates all page table entries in the I-Cache

### Syntax:

icache.iall

#### **Operation:**

Invalidates all page table entries in the I-Cache. You can perform this operation only on the current core.

#### Permission:

M mode/S mode

#### Exception:

Illegal instruction.

#### Notes:

If the value of mxstatus.theadisaee is 0, executing this instruction causes an exception of illegal instruction.

If the value of mxstatus.theadisaee is 1, executing this instruction in U mode causes an exception of illegal instruction.





# 15.1.15 ICACHE.IALLS: an instruction that invalidates all page table entries in the I-Cache through broadcasting

#### Syntax:

icache.ialls

#### **Operation:**

Invalidates all page table entries in the I-Cache and invalidates all page table entries in the I-Cache of other cores through broadcasting. You can perform this operation on all cores.

#### Permission:

M mode/S mode

#### Exception:

Illegal instruction.

#### Notes:

If the value of mxstatus.theadisaee is 0, executing this instruction causes an exception of illegal instruction.

If the value of mxstatus.theadisaee is 1, executing this instruction in U mode causes an exception of illegal instruction.

#### Instruction format:



# 15.1.16 ICACHE.IPA: an instruction that invalidates page table entries that match the specified physical addresses in the I-Cache

#### Syntax:

icache.ipa rs1

#### **Operation:**

Invalidates the page table entry that matches the specified physical address in the I-Cache of rs1. You can perform this operation on all cores.

#### Permission:

M mode/S mode

#### Exception:

Illegal instruction.

#### Notes:

If the value of mxstatus.theadisaee is 0, executing this instruction causes an exception of illegal instruction.

If the value of mxstatus.theadisaee is 1, executing this instruction in U mode causes an exception of illegal instruction.

#### Instruction format:

31 25	24 20	19 15	14 12	11 7	6 0
0000001	11000	rs1	000	00000	0001011

# 15.1.17 ICACHE.IVA: an instruction that invalidates page table entries that match the specified virtual addresses in the I-Cache

#### Syntax:

icache.iva rs1

#### **Operation:**

Invalidates the page table entry that matches the specified virtual address in the I-Cache of rs1. You can perform this operation only on the current core. The sharing attribute of the virtual address determines whether you can perform this operation on other cores.

#### **Permission:**

M mode/S mode/U mode

#### Exception:

Illegal instruction or error page during instruction loading.

#### Notes:

If the value of mxstatus.theadisaee is 0, executing this instruction causes an exception of illegal instruction.

If the value of mxstatus.theadisaee is 1 and the value of mxstatus.ucme is 1, this instruction can be executed in U mode.

If the value of mxstatus.theadisaee is 1 and the value of mxstatus.ucme is 0, executing this instruction in U mode causes an exception of illegal instruction.

31	25 24	20	19 :	15	.4 12	11	7	6	0
0000001		10000	rs1		000	00000	)	0001011	



## 15.1.18 L2CACHE.CALL: an instruction that clears all dirty page table entries in the L2 Cache

## Syntax:

l2cache.call

#### **Operation:**

Writes all dirty page table entries from the L2 Cache back into the next-level storage.

#### **Permission:**

M mode/S mode

#### Exception:

Illegal instruction.

#### Notes:

- If the value of mxstatus.theadisaee is 0, executing this instruction causes an exception of illegal instruction.
- If the value of mxstatus.theadisaee is 1, executing this instruction in U mode causes an exception of illegal instruction.

#### Instruction format:



# 15.1.19 L2CACHE.CIALL: an instruction that clears all dirty page table entries in the L2 Cache and invalidates the L2 Cache

#### Syntax:

l2cache.ciall

#### **Operation:**

Writes all dirty page table entries from the L2 Cache back into the next-level storage and invalidates all page table entries in the L2 Cache.

#### Permission:

M mode/S mode

#### Exception:

Illegal instruction.

#### Notes:



- If the value of mxstatus.theadisaee is 0, executing this instruction causes an exception of illegal instruction.
- If the value of mxstatus.theadisaee is 1, executing this instruction in U mode causes an exception of illegal instruction.

#### Instruction format:

31	25	24 20	19 15	14 12	11 7	6 0
	000000	10111	00000	000	00000	0001011

## 15.1.20 L2CACHE.IALL: an instruction that invalidates the L2 Cache

#### Syntax:

l2cache.iall

#### **Operation:**

Invalidates all page table entries in the L2 Cache.

#### Permission:

M mode/S mode

#### Exception:

Illegal instruction.

#### Notes:

- If the value of mxstatus.cskisayee is 0, executing this instruction causes an exception of illegal instruction.
- If the value of mxstatus.cskisayee is 1, executing this instruction in U mode causes an exception of illegal instruction.

#### Instruction format:

31 25	24 20	19 15	14 12	11 7	6 0
0000000	10110	00000	000	00000	0001011

## 15.1.21 DCACHE.CSW: an instruction that clears dirty page table entries in the D-Cache based on the specified set and way

#### Syntax:

dcache.csw rs1

## **Operation:**



Writes the dirty page table entry from the D-Cache back into the next-level storage device based on the specified set and way.

#### Permission:

M mode/S mode

#### Exception:

Illegal instruction.

#### Notes:

C910 D-Cache is a 2-way set-associative cache. rs1[31] specifies the way and rs1[s:6] specifies the set. When the size of the D-Cache is 32 KB, w denotes 13. When the size of the D-Cache is 64 KB, w denotes 14, and so forth.

If the value of mxstatus.theadisaee is 0, executing this instruction causes an exception of illegal instruction.

If the value of mxstatus.theadisaee is 1, executing this instruction in U mode causes an exception of illegal instruction.

#### Instruction format:

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0	0	0	0	0	0	1	0	0	0	0	1		rs	51	
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
rs1	0	0	0	0	0	0	0	0	0	0	0	1	0	1	1

Fig. 15.1: DCACHE.CSW

## 15.2 Appendix B-2 Multi-core synchronization instructions

This synchronization instruction set extends multi-core synchronization instructions. Each instruction has 32 bits. Synchronization instructions in this instruction set are described in alphabetical order.

## 15.2.1 SFENCE.VMAS: a broadcast instruction that synchronizes the virtual memory address

#### Syntax:

sfence.vmas rs1,rs2



#### **Operation:**

Invalidates and synchronizes page table entries in the virtual memory and broadcasts them to other cores in the cluster.

#### Permission:

M mode/S mode

#### Exception:

Illegal instruction.

#### Notes:

rs1 is the virtual address, and rs2 is the address space identifier (ASID).

- If the value of rs1 is x0 and the value of rs2 is x0, invalidate all page table entries in the TLB and broadcast them to other cores in the cluster.
- When rs1! and rs2 are both x0, all TLB entries that hit the virtual address specified by rs1 are invalidated and broadcast to other cores in the cluster.
- When rs1 and rs2! are both x0, all TLB entries that hit the process ID specified by rs2 are invalidated and broadcast to other cores in the cluster.
- When rs1! and rs2! are both x0, all TLB entries that hit the virtual address specified by rs1 and the process ID specified by rs2 are invalidated and broadcast to other cores in the cluster.

If the value of mxstatus.theadisaee is 0, executing this instruction causes an exception of illegal instruction.

If the value of mxstatus.theadisaee is 1, executing this instruction in U mode causes an exception of illegal instruction.

#### Instruction format:



## 15.2.2 SYNC: an instruction that performs the synchronization operation

#### Syntax:

sync

#### **Operation:**

Ensures that all preceding instructions retire earlier than this instruction and all subsequent instructions retire later than this instruction.

#### Permission:

M mode/S mode/U mode





#### Exception:

Illegal instruction.

#### Instruction format:

31 25	24 20	19 15	14 12	11 7	6 0
0000000	11000	00000	000	00000	0001011

## 15.2.3 SYNC.I: an instruction that synchronizes the clearing operation.

#### Syntax:

sync.i

#### **Operation:**

Ensures that all preceding instructions retire earlier than this instruction and all subsequent instructions retire later than this instruction, and clears the pipeline when this instruction retires.

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Instruction format:



## 15.2.4 SYNC.IS: a broadcast instruction that synchronizes the clearing operation

#### Syntax:

sync.is

#### **Operation:**

Ensures that all preceding instructions retire earlier than this instruction and all subsequent instructions retire later than this instruction. Clears the pipeline when this instruction retires and broadcasts the request to other cores.

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.



## 15.2.5 SYNC.S: a broadcast instruction that performs a synchronization operation

#### Syntax:

sync.s

#### **Operation:**

Ensures that all preceding instructions retire earlier than this instruction and all subsequent instructions retire later than this instruction, and broadcasts the request to other cores.

#### **Permission:**

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Instruction format:

31	25 24	4 20	19 15	5 14 12	11 7	6 0
0000000		11001	00000	000	00000	0001011

## 15.3 Appendix B-3 Arithmetic operation instructions

The arithmetic operation instruction set extends arithmetic operation instructions. Each instruction has 32 bits.

Arithmetic operation instructions in this instruction set are described in alphabetical order.

## 15.3.1 ADDSL: an add register instruction that shifts registers

#### Syntax:

addsl rd rs1, rs2, imm2

#### **Operation:**

 $rd \gets rs1 + rs2 {<} simm2$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.



#### Instruction format:

31	1 27	26 25	24 20	19 15	14 12	11 7	6 0
	00000	imm2	rs2	rs1	001	rd	0001011

## 15.3.2 MULA: a multiply-add instruction

## Syntax:

mula rd, rs1, rs2

#### **Operation:**

 $rd \leftarrow rd + (rs1 * rs2)[63:0]$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	00100	00	rs2	rs1	001	rd	0001011

## 15.3.3 MULAH: a multiply-add instruction that operates on the lower 16 bits

### Syntax:

mulah rd, rs1, rs2

## **Operation:**

 $tmp[31:0] \leftarrow rd[31:0] + (rs1[15:0] * rs[15:0])$ 

 $rd \leftarrow sign\_extend(tmp[31:0])$ 

#### **Permission:**

M mode/S mode/U mode

#### Exception:

Illegal instruction.

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	00101	00	rs2	rs1	001	rd	0001011



## 15.3.4 MULAW: a multiply-add instruction that operates on the lower 32 bits

#### Syntax:

mulaw rd, rs1, rs2

#### **Operation:**

 $tmp[31:0] \leftarrow rd[31:0] + (rs1[31:0] * rs[31:0])[31:0]$ 

 $rd \leftarrow sign\_extend(tmp[31:0])$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	00100	10	rs2	rs1	001	rd	0001011

## 15.3.5 MULS: a multiply-subtract instruction

#### Syntax:

muls rd, rs1, rs2

#### **Operation:**

 $rd \leftarrow rd$ - (rs1 \* rs2)[63:0]

### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Instruction format:

31	27	26 25	24	20 19		15	14 1	2 11	7	6	0
00100		01	rs2		rs1		001		rd	0001011	

## 15.3.6 MULSH: a multiply-subtract instruction that operates on the lower 16 bits

### Syntax:

mulsh rd, rs1, rs2



## **Operation:**

 $tmp[31:0] \leftarrow rd[31:0] - (rs1[15:0] * rs[15:0])$ 

 $rd \leftarrow sign\_extend(tmp[31:0])$ 

## Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	00101	01	rs2	rs1	001	rd	0001011

## 15.3.7 MULSW: a multiply-subtract instruction that operates on the lower 32 bits

#### Syntax:

mulaw rd, rs1, rs2

### **Operation:**

 $tmp[31:0] \leftarrow rd[31:0] - (rs1[31:0] * rs[31:0])$ 

 $rd \leftarrow sign\_extend(tmp[31:0])$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	00100	11	rs2	rs1	001	rd	0001011

## 15.3.8 MVEQZ: an instruction that sends a message when the register is 0

Syntax:

mveqz rd, rs1, rs2

**Operation:** if (rs2 == 0)

 $\mathrm{rd} \leftarrow \mathrm{rs1}$ 

else



 $\mathrm{rd} \leftarrow \mathrm{rd}$ 

## Permission:

 $M \mod/S \mod/U \mod$ 

#### Exception:

Illegal instruction.

#### Instruction format:

31	27	26 25	24 20	19	15	14	12	11	7 6		0
0	1000	00	rs2	rs1		00	)1	rd		0001011	

## 15.3.9 MVNEZ: an instruction that sends a message when the register is not 0

### Syntax:

mvnez rd, rs1, rs2

#### **Operation:**

if (rs2 != 0)

 $\mathrm{rd} \gets \mathrm{rs1}$ 

else

 $\mathrm{rd} \leftarrow \mathrm{rd}$ 

#### Permission:

M mode/S mode/U mode

### Exception:

Illegal instruction.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	01000	01	rs2	rs1	001	rd	0001011

## 15.3.10 SRRI: an instruction that implements a cyclic right shift operation on a linked list

#### Syntax:

srri rd, rs1, imm6

#### **Operation:**

 $rd \gets rs1 >>> imm6$ 



Shifts the original value of rs1 to the right, disconnects the last value on the list, and re-attaches the value to the start of the linked list.

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Instruction format:

31	26	25 20	19 15	14 12	11 7	6 0
	000100	imm6	rs1	001	rd	0001011

## 15.3.11 SRRIW: an instruction that implements a cyclic right shift operation on a linked list of low 32 bits of registers.

#### Syntax:

srriw rd, rs1, imm5

#### **Operation:**

 $rd \leftarrow sign\_extend(rs1[31:0] >>> imm5)$ 

Shifts the original value of rs1[31:0] to the right, disconnects the last value on the list, and re-attaches the value to the start of the linked list.

#### Permission:

M mode/S mode/U mode

#### **Exception:**

Illegal instruction.

#### Instruction format:

31	25	24	20 19	15	14	12	11	7	6	0
000101	0	imm5		rs1		001	r	d	000	01011

## **15.4 Appendix B-4 Bitwise operation instructions**

The bitwise operation instruction set extends bitwise operation instructions. Each instruction has 32 bits.

Arithmetic operation instructions in this instruction set are described in alphabetical order.



## 15.4.1 EXT: a signed extension instruction that extracts consecutive bits of a register

#### Syntax:

ext rd, rs1, imm1,imm2

#### **Operation:**

 $rd \leftarrow sign\_extend(rs1[imm1:imm2])$ 

#### **Permission:**

M mode/S mode/U mode

#### Exception:

Illegal instruction.

## Notes:

If imm1 is smaller than imm2, the action of this instruction is not predictable.

#### Instruction format:

31 26	25 20	19 15	14 12	11 7	6 0
imm1	imm2	rs1	010	rd	0001011

## 15.4.2 EXTU: a zero extension instruction that extracts consecutive bits of a register

#### Syntax:

extu rd, rs1, imm1, imm2

## **Operation:**

 $rd \leftarrow zero\_extend(rs1[imm1:imm2])$ 

### Permission:

M mode/S mode/U mode

#### **Exception:**

Illegal instruction.

#### Notes:

If imm1 is smaller than imm2, the action of this instruction is not predictable.

31 26	25 20	19 15	14 12	11 7	6 0
imm1	imm2	rs1	011	rd	0001011



## 15.4.3 FF0: an instruction that finds the first bit with the value of 0 in a register

#### Syntax:

ff0 rd, rs1  $\,$ 

#### **Operation:**

Finds the first bit with the value of 0 from the highest bit of rs1 and writes the result back into the rd register. If the highest bit of rs1 is 0, the result 0 is returned. If all the bits in rs1 are 1, the result 64 is returned.

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Instruction format:

31	27	26 25	24 20	19 1	5 14 12	11 7	6 0
	10000	10	00000	rs1	001	rd	0001011

## 15.4.4 FF1: an instruction that finds the bit with the value of 1

#### Syntax:

ff1 rd, rs1

## Operation:

Finds the first bit with the value of 1 from the highest bit of rs1 and writes the index of this bit back into rd. If the highest bit of rs1 is 1, the result 0 is returned. If all the bits in rs1 are 1, the result 64 is returned.

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	10000	11	00000	rs1	001	rd	0001011

## 15.4.5 REV: an instruction that reverses the byte order in a word stored in the register

Syntax:



rev rd, rs1

## **Operation:**

$$rd[63:56] \leftarrow rs1[7:0]$$

- $rd[55:48] \leftarrow rs1[15:8]$
- $rd[47:40] \leftarrow rs1[23:16]$
- $rd[39:32] \leftarrow rs1[31:24]$
- $rd[31:24] \leftarrow rs1[39:32]$
- $rd[23:16] \leftarrow rs1[47:40]$
- $rd[15:8] \leftarrow rs1[55:48]$

 $rd[7:0] \leftarrow rs1[63:56]$ 

### Permission:

M mode/S mode/U mode

### Exception:

Illegal instruction.

### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	10000	01	00000	rs1	001	rd	0001011

## 15.4.6 REVW: an instruction that reverses the byte order in a low 32-bit word

#### Syntax:

revw rd, rs1

## **Operation:**

 $tmp[31:24] \leftarrow rs1[7:0]$ 

tmp  $[23:16] \leftarrow rs1[15:8]$ 

tmp [15:8]  $\leftarrow$ rs1[23:16]

tmp [7:0]  $\leftarrow$ rs1[31:24]

 $rd \leftarrow sign\_extend(tmp[31:0])$ 

## Permission:

M mode/S mode/U mode



## Exception:

Illegal instruction.

## Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	10010	00	00000	rs1	001	rd	0001011

## 15.4.7 TST: an instruction that tests bits with the value of 0

### Syntax:

tst rd, rs1, imm6

## **Operation:**

if(rs1[imm6] == 1)

 $\mathrm{rd}{\leftarrow}1$ 

else

 $\mathrm{rd}{\leftarrow}0$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

## Instruction format:

31	26	25 20	19 15	14 12	11 7	6 0
	100010	imm6	rs1	001	rd	0001011

## 15.4.8 TSTNBZ: an instruction that tests bytes with the value of 0

#### Syntax:

tstnbz rd, rs1

#### **Operation:**

$rd[63:56] \leftarrow (rs1[63:56] == 0) ? 8'$	hff: 8'	h0
$rd[55:48] \leftarrow (rs1[55:48] == 0) ? 8'$	hff: 8'	h0
$rd[47:40] \leftarrow (rs1[47:40] == 0) ? 8'$	hff: 8'	h0
$rd[39:32] \leftarrow (rs1[39:32] == 0) ? 8'$	hff: 8'	h0
$rd[31:24] \leftarrow (rs1[31:24] == 0) ? 8'$	hff: 8'	h0



 $rd[23:16] \leftarrow (rs1[23:16] == 0) ? 8' hff: 8' h0$  $rd[15:8] \leftarrow (rs1[15:8] == 0) ? 8' hff: 8' h0$  $rd[7:0] \leftarrow (rs1[7:0] == 0) ? 8' hff: 8' h0$ 

### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	10000	00	00000	rs1	001	rd	0001011

## 15.5 Appendix B-5 Storage instructions

The storage instruction set extends storage instructions. Each instruction has 32 bits.

Arithmetic operation instructions in this instruction set are described in alphabetical order.

## 15.5.1 FLRD: a load doubleword instruction that shifts floating-point registers

#### Syntax:

flrd rd, rs1, rs2, imm2

#### **Operation:**

 $rd \leftarrow mem[(rs1+rs2<<imm2)+7: (rs1+rs2<<imm2)]$ 

### Permission:

M mode/S mode/U mode

## Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:

If the value of mxstatus.theadisaee is 1' b0 or the value of mstatus.fs is 2' b00, executing this instruction causes an exception of illegal instruction.

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	01100	imm2	rs2	rs1	110	rd	0001011



## 15.5.2 FLRW: a load word instruction that shifts floating-point registers

#### Syntax:

flrw rd, rs1, rs2, imm2

#### **Operation:**

 $rd \leftarrow one\_extend(mem[(rs1+rs2<<imm2)+3: (rs1+rs2<<imm2)])$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:

If the value of mxstatus. theadisaee is 1' b0 or the value of mstatus. fs is 2' b00, executing this instruction causes an exception of illegal instruction.

#### Instruction format:

31	27	26 25	24 20	19 1	5 14 12	11 7	6 0
01000		imm2	rs2	rs1	110	rd	0001011

## 15.5.3 FLURD: a load doubleword instruction that shifts low 32 bits of floating-point registers

#### Syntax:

flurd rd, rs1, rs2, imm2

#### **Operation:**

 $rd \leftarrow mem[(rs1+rs2[31:0] < (imm2) + 7: (rs1+rs2[31:0] < (imm2)]$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:

rs2[31:0] specifies an unsigned value. 0s are added to the high bits [63:32] for address calculation.

If the value of mxstatus.theadisaee is 1' b0 or the value of mstatus.fs is 2' b00, executing this instruction causes an exception of illegal instruction.

31	27	26 25	24 20	19 15	14 12	11 7	6	0
	01110	imm2	rs2	rs1	110	rd	0001011	

## 15.5.4 FLURW: a load word instruction that shifts low 32 bits of floating-point registers

#### Syntax:

flurw rd, rs1, rs2, imm2

#### **Operation:**

 $rd \leftarrow one\_extend(mem[(rs1+rs2[31:0]<<imm2)+3: (rs1+rs2[31:0]<<imm2)])$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:

rs2[31:0] specifies an unsigned value. 0s are added to the high bits [63:32] for address calculation.

If the value of mxstatus.theadisaee is 1' b0 or the value of mstatus.fs is 2' b00, executing this instruction causes an exception of illegal instruction.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	01010	imm2	rs2	rs1	110	rd	0001011

## 15.5.5 FSRD: a store doubleword instruction that shifts floating-point registers

#### Syntax:

fsrd rd, rs1, rs2, imm2

#### **Operation:**

 $mem[(rs1+rs2<<imm2)+7: (rs1+rs2<<imm2)] \leftarrow rd[63:0]$ 

### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:

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If the value of mxstatus.theadisaee is 1' b0 or the value of mstatus.fs is 2' b00, executing this instruction causes an exception of illegal instruction.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	01100	imm2	rs2	rs1	111	rd	0001011

## 15.5.6 FSRW: a store word instruction that shifts floating-point registers.

#### Syntax:

fsrw rd, rs1, rs2, imm2

#### **Operation:**

 $mem[(rs1+rs2<<imm2)+3: (rs1+rs2<<imm2)] \leftarrow rd[31:0]$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:

If the value of mxstatus.theadisaee is 1' b0 or the value of mstatus.fs is 2' b00, executing this instruction causes an exception of illegal instruction.

#### Instruction format:

31 27	26 25	24 20	19 1	5 14 1	.2 11	7 6 0
01000	imm2	rs2	rs1	111	rd	0001011

# 15.5.7 FSURD: a store doubleword instruction that shifts low 32 bits of floating-point registers

#### Syntax:

fsurd rd, rs1, rs2, imm2

#### **Operation:**

 $mem[(rs1+rs2[31:0] < <imm2)+7: (rs1+rs2[31:0] < <imm2)] \leftarrow rd[63:0]$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.


#### Notes:

rs2[31:0] specifies an unsigned value. 0s are added to the high bits [63:32] for address calculation.

If the value of mxstatus.theadisaee is 1' b0 or the value of mstatus.fs is 2' b00, executing this instruction causes an exception of illegal instruction.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6	0
	01110	imm2	rs2	rs1	111	rd	0001011	

## 15.5.8 FSURW: a store word instruction that shifts low 32 bits of floating-point registers

#### Syntax:

fsurw rd, rs1, rs2, imm2

#### **Operation:**

 $mem[(rs1+rs2[31:0] < <imm2)+3: (rs1+rs2[31:0] < <imm2)] \leftarrow rd[31:0]$ 

### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:

rs2[31:0] specifies an unsigned value. 0s are added to the high bits [63:32] for address calculation.

If the value of mxstatus.theadisaee is 1' b0 or the value of mstatus.fs is 2' b00, executing this instruction causes an exception of illegal instruction.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	01010	imm2	rs2	rs1	111	rd	0001011

# 15.5.9 LBIA: a base-address auto-increment instruction that extends signed bits and loads bytes

#### Syntax:

lbia rd, (rs1), imm5, imm2

#### **Operation:**



 $rd \leftarrow sign\_extend(mem[rs1])$ 

 $rs1 \leftarrow rs1 + sign\_extend(imm5 << imm2)$ 

### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:

The values of rd and rs1 must not be the same.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	00011	imm2	imm5	rs1	100	rd	0001011

## 15.5.10 LBIB: a load byte instruction that auto-increments the base address and extends signed bits

#### Syntax:

lbib rd, (rs1), imm5, imm2

#### **Operation:**

 $rs1 \leftarrow rs1 + sign\_extend(imm5 << imm2)$ 

 $rd \leftarrow sign\_extend(mem[rs1])$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:

The values of rd and rs1 must not be the same.

#### Instruction format:





## 15.5.11 LBUIA: a base-address auto-increment instruction that extends zero bits and loads bytes

#### Syntax:

lbuia rd, (rs1), imm5, imm2

#### **Operation:**

 $rd \leftarrow zero\_extend(mem[rs1])$ 

 $rs1 \leftarrow rs1 + sign\_extend(imm5 << imm2)$ 

#### **Permission:**

 $M \mod/S \mod/U \mod$ 

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:

The values of rd and rs1 must not be the same.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	10011	imm2	imm5	rs1	100	rd	0001011

# 15.5.12 LBUIB: a load byte instruction that auto-increments the base address and extends zero bits

### Syntax:

lbuib rd, (rs1), imm5, imm2

#### **Operation:**

 $rs1 \leftarrow rs1 + sign\_extend(imm5 << imm2)$ 

 $rd \leftarrow zero\_extend(mem[rs1])$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:

The values of rd and rs1 must not be the same.



Instruction format:

1	31 27	26 25	24 20	19 15	14 12	11 7	6 0
	10001	imm2	imm5	rs1	100	rd	0001011

### 15.5.13 LDD: an instruction that loads double registers

#### Syntax:

ldd rd1,rd2, (rs1),imm2

#### **Operation:**

 $address \leftarrow rs1 + zero\_extend(imm2 << 4)$ 

 $rd1 \leftarrow mem[address+7:address]$ 

 $rd2 \leftarrow mem[address+15:address+8]$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:

The values of rd1, rd2, and rs1 must not be the same.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	11111	imm2	rd2	rs1	100	rd1	0001011

## 15.5.14 LDIA: a base-address auto-increment instruction that loads doublewords and extends signed bits

#### Syntax:

ldia rd, (rs1), imm5, imm2

#### **Operation:**

 $rd \leftarrow sign\_extend(mem[rs1+7:rs1])$ 

 $rs1 \leftarrow rs1 + sign\_extend(imm5 << imm2)$ 

### Permission:

M mode/S mode/U mode



#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:

The values of rd and rs1 must not be the same.

#### Instruction format:

31	27	26 25	24 20	0 19	15	14	12	11	7	6		0
	01111	imm2	imm5	rs1		10	00	rd	l		0001011	

# 15.5.15 LDIB: a load doubleword instruction that auto-increments the base address and extends the signed bits

#### Syntax:

ldib rd, (rs1), imm5, imm2

#### **Operation:**

 $rs1 \leftarrow rs1 + sign\_extend(imm5 << imm2)$ 

 $rd \leftarrow sign\_extend(mem[rs1+7:rs1])$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:

The values of rd and rs1 must not be the same.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	01101	imm2	imm5	rs1	100	rd	0001011

# 15.5.16 LHIA: a base-address auto-increment instruction that loads halfwords and extends signed bits

#### Syntax:

lhia rd, (rs1), imm5, imm2

#### **Operation:**



 $rd \leftarrow sign\_extend(mem[rs1+1:rs1])$ 

 $rs1 \leftarrow rs1 + sign\_extend(imm5 << imm2)$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:

The values of rd and rs1 must not be the same.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	00111	imm2	imm5	rs1	100	rd	0001011

# 15.5.17 LHIB: a load halfword instruction that auto-increments the base address and extends signed bits

#### Syntax:

lhib rd, (rs1), imm5, imm2

#### **Operation:**

 $rs1 \leftarrow rs1 + sign\_extend(imm5 << imm2)$ 

 $rd \leftarrow sign\_extend(mem[rs1+1:rs1])$ 

#### **Permission:**

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:

The values of rd and rs1 must not be the same.

#### Instruction format:





## 15.5.18 LHUIA: a base-address auto-increment instruction that extends zero bits and loads halfwords

#### Syntax:

lhuia rd, (rs1), imm5, imm2

#### **Operation:**

 $rd \leftarrow zero\_extend(mem[rs1+1:rs1])$ 

 $rs1 \leftarrow rs1 + sign\_extend(imm5 << imm2)$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:

The values of rd and rs1 must not be the same.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	10111	imm2	imm5	rs1	100	rd	0001011

# 15.5.19 LHUIB: a load halfword instruction that auto-increments the base address and extends zero bits

#### Syntax:

lhuib rd, (rs1), imm5, imm2

#### **Operation:**

 $rs1 \leftarrow rs1 + sign\_extend(imm5 << imm2)$ 

 $rd \leftarrow zero\_extend(mem[rs1+1:rs1])$ 

#### **Permission:**

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:

The values of rd and rs1 must not be the same.



#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 <mark>0</mark>
	10101	imm2	imm5	rs1	100	rd	0001011

### 15.5.20 LRB: a load byte instruction that shifts registers and extends signed bits

#### Syntax:

lrb rd, rs1, rs2, imm2

#### **Operation:**

 $rd \leftarrow sign\_extend(mem[(rs1+rs2 < imm2)])$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	00000	imm2	rs2	rs1	100	rd	0001011

## 15.5.21 LRBU: a load byte instruction that shifts registers and extends zero bits

#### Syntax:

lrbu rd, rs1, rs2, imm2

### **Operation:**

 $rd \leftarrow zero\_extend(mem[(rs1+rs2<<imm2)])$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	10000	imm2	rs2	rs1	100	rd	0001011



## 15.5.22 LRD: a load doubleword instruction that shifts registers

#### Syntax:

lrd rd, rs1, rs2, imm2

#### **Operation:**

 $rd \leftarrow mem[(rs1+rs2<<imm2)+7: (rs1+rs2<<imm2)]$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Instruction format:

31	27	26 25	24 20	19	15 14	12 1	11 7	6	0
	01100	imm2	rs2	rs1	10	0	rd	0001011	

## 15.5.23 LRH: a load halfword instruction that shifts registers and extends signed bits

#### Syntax:

lrh rd, rs1, rs2, imm2

### **Operation:**

 $rd \leftarrow sign\_extend(mem[(rs1+rs2<<imm2)+1: (rs1+rs2<<imm2)])$ 

### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	00100	imm2	rs2	rs1	100	rd	0001011

## 15.5.24 LRHU: a load halfword instruction that shifts registers and extends zero bits

#### Syntax:

lrhu rd, rs1, rs2, imm2

#### **Operation:**



 $rd \leftarrow zero\_extend(mem[(rs1+rs2<<imm2)+1: (rs1+rs2<<imm2)])$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Instruction format:

31	27	26 25	24 20	19	15	14 12	11 7	6 0
	10100	imm2	rs2	rs1		100	rd	0001011

### 15.5.25 LRW: a load word instruction that shifts registers and extends signed bits

#### Syntax:

lrw rd, rs1, rs2, imm2

#### **Operation:**

 $rd \leftarrow sign\_extend(mem[(rs1+rs2<<imm2)+3: (rs1+rs2<<imm2)])$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	01000	imm2	rs2	rs1	100	rd	0001011

### 15.5.26 LRWU: a load word instruction that shifts registers and extends zero bits

#### Syntax:

lrwu rd, rs1, rs2, imm2

#### **Operation:**

 $rd \leftarrow zero\_extend(mem[(rs1+rs2<<imm2)+3: (rs1+rs2<<imm2)])$ 

### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	11000	imm2	rs2	rs1	100	rd	0001011

# 15.5.27 LURB: a load byte instruction that shifts low 32 bits of registers and extends signed bits

#### Syntax:

lurb rd, rs1, rs2, imm2

#### **Operation:**

 $rd \leftarrow sign\_extend(mem[(rs1+rs2[31:0] < (imm2)]))$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:

rs2[31:0] specifies an unsigned value. 0s are added to the high bits [63:32] for address calculation.

#### Instruction format:

Ì	31	27	26 25	24	20 19	15 1	.4 12	11	7 6		0
	000	.0	imm2	rs2	rs1		100	rd		0001011	

# 15.5.28 LURBU: a load byte instruction that shifts low 32 bits of registers and extends zero bits

#### Syntax:

lurbu rd, rs1, rs2, imm2

#### **Operation:**

 $rd \leftarrow zero\_extend(mem[(rs1+rs2[31:0] < (imm2)])$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:



rs2[31:0] specifies an unsigned value. 0s are added to the high bits [63:32] for address calculation.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	10010	imm2	rs2	rs1	100	rd	0001011

### 15.5.29 LURD: a load doubleword instruction that shifts low 32 bits of registers

#### Syntax:

lurd rd, rs1, rs2, imm2

#### **Operation:**

 $rd \leftarrow mem[(rs1+rs2[31:0] < (imm2) + 7: (rs1+rs2[31:0] < (imm2)]$ 

#### **Permission:**

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:

rs2[31:0] specifies an unsigned value. Os are added to the high bits [63:32] for address calculation.

#### Instruction format:

31	27	26 25	24 20	19	15 14	12	11 7	6	0
	01110	imm2	rs2	rs1		100	rd	0001011	

# 15.5.30 LURH: a load halfword instruction that shifts low 32 bits of registers and extends signed bits

#### Syntax:

lurh rd, rs1, rs2, imm2

#### **Operation:**

 $rd \leftarrow sign\_extend(mem[(rs1+rs2[31:0] < imm2)+1:$ 

(rs1+rs2[31:0] < (imm2)])

#### **Permission:**

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.



### Notes:

rs2[31:0] specifies an unsigned value. 0s are added to the high bits [63:32] for address calculation.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	00110	imm2	rs2	rs1	100	rd	0001011

## 15.5.31 LURHU: a load halfword instruction that shifts low 32 bits of registers and extends zero bits

#### Syntax:

lurhu rd, rs1, rs2, imm2

#### **Operation:**

 $rd \leftarrow zero\_extend(mem[(rs1+rs2[31:0] < imm2)+1:$ 

(rs1+rs2[31:0]<<imm2)])

### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:

rs2[31:0] specifies an unsigned value. 0s are added to the high bits [63:32] for address calculation.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	10110	imm2	rs2	rs1	100	rd	0001011

# 15.5.32 LURW: a load word instruction that shifts low 32 bits of registers and extends signed bits

#### Syntax:

lurw rd, rs1, rs2, imm2

#### **Operation:**

 $rd \leftarrow sign\_extend(mem[(rs1+rs2[31:0] < < imm2) + 3:$ 

(rs1+rs2[31:0]<<imm2)])

#### Permission:



M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:

rs2[31:0] specifies an unsigned value. Os are added to the high bits [63:32] for address calculation.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	01010	imm2	rs2	rs1	100	rd	0001011

# 15.5.33 LURWU: a load word instruction that shifts 32 bits of registers and extends zero bits

#### Syntax:

lwd rd1, rd2, (rs1),imm2

#### **Operation:**

 $address \leftarrow rs1 + zero\_extend(imm2 < <3)$ 

 $rd1 \leftarrow sign\_extend(mem[address+3: address])$ 

 $rd2 \leftarrow sign\_extend(mem[address+7: address+4])$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:

The values of rd1, rd2, and rs1 must not be the same.

#### Instruction format:



## 15.5.34 LWD: a load word instruction that loads double registers and extends signed bits

#### Syntax:

lwd rd, imm7(rs1)



### **Operation:**

 $address \leftarrow rs1 + sign\_extend(imm7)$ 

 $rd \leftarrow sign\_extend(mem[address+31: address])$ 

 $rd+1 \leftarrow sign\_extend(mem[address+63: address+32])$ 

#### **Permission:**

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	11100	imm2	rd2	rs1	100	rd1	0001011

# 15.5.35 LWIA: a base-address auto-increment instruction that extends signed bits and loads words

#### Syntax:

lwia rd, (rs1), imm5, imm2

#### **Operation:**

 $rd \leftarrow sign\_extend(mem[rs1+3:rs1])$ 

 $rs1 \leftarrow rs1 + sign\_extend(imm5 << imm2)$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:

The values of rd and rs1 must not be the same.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 <b>0</b>
	01011	imm2	imm5	rs1	100	rd	0001011



## 15.5.36 LWIB: a load word instruction that auto-increments the base address and extends signed bits

### Syntax:

lwib rd, (rs1), imm5, imm2

#### **Operation:**

 $rs1 \leftarrow rs1 + sign\_extend(imm5 << imm2)$ 

 $rd \leftarrow sign\_extend(mem[rs1+3:rs1])$ 

#### **Permission:**

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:

The values of rd and rs1 must not be the same.

#### Instruction format:

31	27	26 25	24 20	19 1	5 14 12	11 7	6 0
	01001	imm2	imm5	rs1	100	rd	0001011

# 15.5.37 LWUD: a load word instruction that loads double registers and extends zero bits

#### Syntax:

lwud rd1,rd2, (rs1),imm2

#### **Operation:**

 $address \leftarrow rs1 + zero\_extend(imm2 < <3)$ 

 $rd1 \leftarrow zero\_extend(mem[address+3: address])$ 

 $rd2 \leftarrow zero\_extend(mem[address+7: address+4])$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:



The values of rd1, rd2, and rs1 must not be the same.

#### Instruction format:

31	27	26 25	24 20	19 1	5 14 12	11 7	6 0	
1:	110	imm2	rd2	rs1	100	rd 1	0001011	

## 15.5.38 LWUIA: a base-address auto-increment instruction that extends zero bits and loads words

#### Syntax:

lwuia rd, (rs1), imm5, imm2

#### **Operation:**

 $rd \leftarrow zero\_extend(mem[rs1+3:rs1])$ 

 $rs1 \leftarrow rs1 + sign\_extend(imm5 << imm2)$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:

The values of rd and rs1 must not be the same.

#### Instruction format:

31	27	26 25	24 20	0 19	15	14	12	11	7	6		0
	11011	imm2	imm5	rs1		10	0		rd		0001011	

## 15.5.39 LWUIB: a load word instruction that auto-increments the base address and extends zero bits

#### Syntax:

lwuib rd, (rs1), imm5, imm2

#### **Operation:**

 $rs1 \leftarrow rs1 + sign\_extend(imm5 << imm2)$ 

 $rd \leftarrow zero\_extend(mem[rs1+3:rs1])$ 

#### Permission:

M mode/S mode/U mode



#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:

The values of rd and rs1 must not be the same.

#### Instruction format:

3:	L 27	26 25	24 20	19 15	14 12	11 7	6 0
	11001	imm2	imm5	rs1	100	rd	0001011

### 15.5.40 SBIA: a base-address auto-increment instruction that stores bytes

#### Syntax:

sbia rs2, (rs1), imm5, imm2

#### **Operation:**

 $mem[rs1] \leftarrow rs2[7:0]$ 

 $rs1 \leftarrow rs1 + sign\_extend(imm5 << imm2)$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Instruction format:



### 15.5.41 SBIB: a store byte instruction that auto-increments the base address

#### Syntax:

```
sbib rs2, (rs1), imm5, imm2
```

#### **Operation:**

 $rs1 \leftarrow rs1 + sign\_extend(imm5 << imm2)$ 

 $mem[rs1] \leftarrow rs2[7:0]$ 

### Permission:

M mode/S mode/U mode





#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	00001	imm2	imm5	rs1	101	rs2	0001011

## 15.5.42 SDD: an instruction that stores double registers

### Syntax:

sdd rd1,rd2, (rs1),imm2

#### **Operation:**

 $address \leftarrow rs1 + zero\_extend(imm2 << 4)$ 

 $mem[address{+}7:address] \leftarrow rd1$ 

 $mem[address+15:address+8]{\leftarrow}rd2$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Instruction format:

31	27	26 25	24 20	19	15 14	4 12	11 7	6 0	
	11111	imm2	rd2	rs1		101	rd1	0001011	

### 15.5.43 SDIA: a base-address auto-increment instruction that stores doublewords

#### Syntax:

sdia rs2, (rs1), imm5, imm2

#### **Operation:**

 $mem[rs1+7:rs1] \leftarrow rs2[63:0]$ 

 $rs1 \leftarrow rs1 + sign\_extend(imm5 << imm2)$ 

### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.



Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	01111	imm2	imm5	rs1	101	rs2	0001011

### 15.5.44 SDIB: a store doubleword instruction that auto-increments the base address

#### Syntax:

sdib rs2, (rs1), imm5, imm2

#### **Operation:**

 $rs1 \leftarrow rs1 + sign\_extend(imm5 << imm2)$ 

 $mem[rs1+7:rs1] \leftarrow rs2[63:0]$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Instruction format:

31 27	26 25	24 20	19 15	14 12	11 7	6 0
01101	imm2	imm5	rs1	101	rs2	0001011

### 15.5.45 SHIA: a base-address auto-increment instruction that stores halfwords

#### Syntax:

shia rs2, (rs1), imm5, imm2

#### **Operation:**

 $mem[rs1+1:rs1] \leftarrow rs2[15:0]$ 

 $rs1 \leftarrow rs1 + sign\_extend(imm5 << imm2)$ 

### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	00111	imm2	imm5	rs1	101	rs2	0001011



## 15.5.46 SHIB: a store halfword instruction that auto-increments the base address

#### Syntax:

shib rs2, (rs1), imm5, imm2

#### **Operation:**

 $rs1 \leftarrow rs1 + sign\_extend(imm5 << imm2)$ 

 $mem[rs1+1:rs1] \leftarrow rs2[15:0]$ 

### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	00101	imm2	imm5	rs1	101	rs2	0001011

## 15.5.47 SRB: a store byte instruction that shifts registers

#### Syntax:

srb rd, rs1, rs2, imm2

#### **Operation:**

 $mem[(rs1+rs2<<imm2)] \leftarrow rd[7:0]$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Instruction format:

31	27	26 25	24 20	19	15	14	12	11	7	6	0
	00000	imm2	imm5	rs1		10	)1	rd		0001011	

## 15.5.48 SRD: a store doubleword instruction that shifts registers

#### Syntax:

srd rd, rs1, rs2, imm2



#### **Operation:**

 $mem[(rs1+rs2<<imm2)+7: (rs1+rs2<<imm2)] \leftarrow rd[63:0]$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	01100	imm2	rs2	rs1	101	rd	0001011

### 15.5.49 SRH: a store halfword instruction that shifts registers

### Syntax:

srh rd, rs1, rs2, imm2

#### **Operation:**

 $mem[(rs1+rs2<<imm2)+1: (rs1+rs2<<imm2)] \leftarrow rd[15:0]$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	00100	imm2	rs2	rs1	101	rd	0001011

## 15.5.50 SRW: a store word instruction that shifts registers

#### Syntax:

srw rd, rs1, rs2, imm2

#### **Operation:**

 $mem[(rs1+rs2<<imm2)+3: (rs1+rs2<<imm2)] \leftarrow rd[31:0]$ 

### Permission:

M mode/S mode/U mode





#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	01000	imm2	rs2	rs1	101	rd	0001011

## 15.5.51 SURB: a store byte instruction that shifts low 32 bits of registers

#### Syntax:

surb rd, rs1, rs2, imm2

### **Operation:**

 $mem[(rs1+rs2[31:0] < imm2)] \leftarrow rd[7:0]$ 

### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:

rs2[31:0] specifies an unsigned value. 0s are added to the high bits [63:32] for address calculation.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	00010	imm2	rs2	rs1	101	rd	0001011

### 15.5.52 SURD: a store doubleword instruction that shifts low 32 bits of registers

#### Syntax:

surd rd, rs1, rs2, imm2

#### **Operation:**

 $mem[(rs1+rs2[31:0] < <imm2)+7: (rs1+rs2[31:0] < <imm2)] \leftarrow rd[63:0]$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:



rs2[31:0] specifies an unsigned value. 0s are added to the high bits [63:32] for address calculation.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	01110	imm2	rs2	rs1	101	rd	0001011

### 15.5.53 SURH: a store halfword instruction that shifts low 32 bits of registers

#### Syntax:

surh rd, rs1, rs2, imm2

#### **Operation:**

 $mem[(rs1+rs2|31:0] < (mm2)+1: (rs1+rs2|31:0] < (mm2)] \leftarrow rd[15:0]$ 

#### **Permission:**

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:

rs2[31:0] specifies an unsigned value. Os are added to the high bits [63:32] for address calculation.

#### Instruction format:

31	27	26 25	24 20	19	15 14	12 1	l1 7	6	0
	00110	imm2	rs2	rs1	10	1	rd	0001011	

## 15.5.54 SURW: a store word instruction that shifts low 32 bits of registers

#### Syntax:

surw rd, rs1, rs2, imm2

#### **Operation:**

 $mem[(rs1+rs2[31:0] < (rs1+rs2[31:0] < (rs1+rs2[31:0] < (rs1)] \leftarrow rd[31:0]$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Notes:

rs2[31:0] specifies an unsigned value. 0s are added to the high bits [63:32] for address calculation.



#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	01010	imm2	rs2	rs1	101	rd	0001011

### 15.5.55 SWIA: a base-address auto-increment instruction that stores words

#### Syntax:

swia rs2, (rs1), imm5, imm2

#### **Operation:**

 $mem[rs1+3:rs1] \leftarrow rs2[31:0]$ 

 $rs1 \leftarrow rs1 + sign\_extend(imm5 << imm2)$ 

### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	01011	imm2	imm5	rs1	101	rs2	0001011

### 15.5.56 SWIB: a store word instruction that auto-increments the base address

#### Syntax:

swib rs2, (rs1), imm5, imm2

#### **Operation:**

 $rs1 \leftarrow rs1 + sign\_extend(imm5 << imm2)$ 

 $mem[rs1+3:rs1] \leftarrow rs2[31:0]$ 

#### Permission:

 $M \mod/S \mod/U \mod$ 

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	01001	imm2	imm5	rs1	101	rs2	0001011



## 15.5.57 SWD: an instruction that stores the low 32 bits of double registers

#### Syntax:

swd rd1,rd2,(rs1),imm2

#### **Operation:**

 $address \leftarrow rs1 + zero\_extend(imm2 << 3)$ 

 $mem[address+3:address] \leftarrow rd1[31:0]$ 

 $mem[address+7:address+4] \leftarrow rd2[31:0]$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	11100	imm2	rd2	rs1	101	rd1	0001011

## 15.6 Appendix B-6 Half-precision floating-point instructions

You can use instructions in this instruction set to process floating-point half-precision data. Each instruction has 32 bits. Instructions in this instruction set are described in alphabetical order.

## 15.6.1 FADD.H: a half-precision floating-point add instruction

Syntax:

fadd.h fd, fs1, fs2, rm

### **Operation:**

 $\mathrm{fd} \leftarrow \mathrm{fs1} + \mathrm{fs2}$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Affected flag bits:

Floating-point status bits NV, OF, and NX



#### Notes:

RM determines the round-off mode:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fadd.h fd, fs1, fs2, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fadd.h fd, fs1, fs2, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fadd.h fd, fs1, fs2, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fadd.h fd, fs1, fs2, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fadd.h fd, fs1,fs2, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fadd.h fd, fs1, fs2.

#### Instruction format:

31	25 24	20	19	15	14 12	11 7	6 0
0000010		fs2	fs1		rm	fd	1010011

## 15.6.2 FCLASS.H: a half-precision floating-point classification instruction

#### Syntax:

fclass.h rd, fs1

#### **Operation:**

- if (fs1 = -inf)
  - $rd \leftarrow 64'$  h1
- if ( fs1 = -norm)

$$rd \leftarrow 64' h2$$

- if (fs1 = -subnorm)
  - $rd \leftarrow 64' h4$
- if (fs1 = -zero)
  - $rd \leftarrow 64' h8$
- if (  ${\rm fs1}=+{\rm zero})$





$$rd \leftarrow 64' h10$$
  
if (fs1 = +subnorm)  
$$rd \leftarrow 64' h20$$
  
if (fs1 = +norm)  
$$rd \leftarrow 64' h40$$
  
if (fs1 = +inf)  
$$rd \leftarrow 64' h80$$
  
if (fs1 = sNaN)  
$$rd \leftarrow 64' h100$$
  
if (fs1 = qNaN)  
$$rd \leftarrow 64' h200$$
  
**Permission:**  
M mode/S mode/U mode  
**Exception:**

Illegal instruction.

### Affected flag bits:

None

Instruction format:

31 2	24 20	19 15	14 12	11 7	6 0
1110010	00000	fs1	001	rd	1010011

# 15.6.3 FCVT.D.H: an instruction that converts half-precision floating-point data to double-precision floating-point data

#### Syntax:

fcvt.d.h fd, fs1

### **Operation:**

 $fd \leftarrow half\_convert\_to\_double(fs1)$ 

#### Permission:

M mode/S mode/U mode



### Exception:

Illegal instruction.

#### Affected flag bits:

None

#### Instruction format:

31	25	24 20	19 15	14 12	11 7	6 0
	0100001	00010	fs1	000	fd	1010011

# 15.6.4 FCVT.H.D: an instruction that converts double-precision floating-point data to half-precision floating-point data

#### Syntax:

fcvt.h.d fd, fs1, rm

#### **Operation:**

 $fd \leftarrow double\_convert\_to\_half(fs1)$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Affected flag bits:

Floating-point status bits NV, OF, UF, and NX

#### Notes:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fcvt.h.d fd, fs1, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fcvt.h.d fd, fs1, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fcvt.h.d fd, fs1, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fcvt.h.d fd, fs1, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fcvt.h.d fd, fs1, rmm.
- 3' b101: This code is reserved and not used.



- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fcvt.h.d fd, fs1.

#### Instruction format:

31 25	24 20	19 15	14 12	11 7	6 0
0100010	00001	fs1	rm	fd	1010011

## 15.6.5 FCVT.H.L: an instruction that converts a signed long integer into a halfprecision floating-point number

#### Syntax:

fcvt.h.l fd, rs1, rm

#### **Operation:**

 $fd \leftarrow signed\_long\_convert\_to\_half(rs1)$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Affected flag bits:

Floating-point status bits NX and OF

#### Notes:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fcvt.h.l fd, rs1, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fcvt.h.l fd, rs1, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fcvt.h.l fd, rs1, fdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fcvt.h.l fd, rs1, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fcvt.h.l fd, rs1, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.



• 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fcvt.h.l fd, rs1.

#### Instruction format:

31	25 24 20	19 15	14 12	11 7	6 0
1101010	00010	rs1	rm	fd	1010011

## 15.6.6 FCVT.H.LU: an instruction that converts an unsigned long integer into a halfprecision floating-point number

#### Syntax:

fcvt.h.lu fd, rs1, rm

#### **Operation:**

 $fd \leftarrow unsigned\_long\_convert\_to\_half\_fp(rs1)$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Affected flag bits:

Floating-point status bits NX and OF

#### Notes:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fcvt.h.lu fd, rs1, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fcvt.h.lu fd, rs1, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fcvt.h.lu fd, rs1, fdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fcvt.h.lu fd, rs1, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fcvt.h.lu fd, rs1, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.



• 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fcvt.h.lu fd, rs1.

#### Instruction format:

31	25 24 2	0 19 15	14 12	11 7	6 0
1101010	00011	rs1	rm	fd	1010011

# 15.6.7 FCVT.H.S: an instruction that converts single precision floating-point data to half-precision floating-point data

#### Syntax:

fcvt.h.s fd, fs1, rm

#### **Operation:**

 $fd \leftarrow single\_convert\_to\_half(fs1)$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Affected flag bits:

Floating-point status bits NV, OF, UF, and NX

#### Notes:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fcvt.h.s fd, fs1, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fcvt.h.s fd, fs1, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fcvt.h.s fd, fs1, fdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fcvt.h.s fd, fs1, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fcvt.h.s fd, fs1, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.



• 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fcvt.h.s fd, fs1.

#### Instruction format:

31	25 24	20 19	15 14	12	11 7	6 0
0100010	0000	00 fs1		rm	fd	1010011

# **15.6.8 FCVT.H.W:** an instruction that converts a signed integer into a half-precision floating-point number

#### Syntax:

fcvt.h.w fd, rs1, rm

#### **Operation:**

 $fd \leftarrow signed\_int\_convert\_to\_half(rs1)$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Affected flag bits:

Floating-point status bits NX and OF

#### Notes:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fcvt.h.w fd, rs1, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fcvt.h.w fd, rs1, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fcvt.h.w fd, rs1, fdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fcvt.h.w fd, rs1, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fcvt.h.w fd, rs1, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.



• 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fcvt.h.w fd, rs1.

#### Instruction format:

31 2	5 24 20	19 15	14 12	11 7	6 0
1101010	00000	rs1	rm	fd	1010011

## 15.6.9 FCVT.H.WU: an instruction that converts an unsigned integer into a halfprecision floating-point number

#### Syntax:

fcvt.h.wu fd, rs1, rm

#### **Operation:**

 $fd \leftarrow unsigned\_int\_convert\_to\_half\_fp(rs1)$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Affected flag bits:

Floating-point status bits NX and OF

#### Notes:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fcvt.h.wu fd, rs1, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fcvt.h.wu fd, rs1, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fcvt.h.wu fd, rs1, fdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fcvt.h.wu fd, rs1, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fcvt.h.wu fd, rs1, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.



• 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fcvt.h.wu fd, rs1.

#### Instruction format:

31 2	5 24 20	19 15	14 12	11 7	6 <b>0</b>
1101010	00001	rs1	rm	fd	1010011

# 15.6.10 FCVT.L.H: an instruction that converts a half-precision floating-point number to a signed long integer

#### Syntax:

fcvt.l.h rd, fs1, rm

#### **Operation:**

 $rd \leftarrow half\_convert\_to\_signed\_long(fs1)$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Affected flag bits:

Floating-point status bits NV and NX

#### Notes:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fcvt.l.h rd, fs1, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fcvt.l.h rd, fs1, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fcvt.l.h rd, fs1, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fcvt.l.h rd, fs1, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fcvt.l.h rd, fs1, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.



• 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fcvt.l.h rd, fs1.

#### Instruction format:

31	25	24 20	19 15	14 12	11 7	6 0
	1100010	00010	fs1	rm	rd	1010011

## 15.6.11 FCVT.LU.H: an instruction that converts a half-precision floating-point number to an unsigned long integer

#### Syntax:

fcvt.lu.h rd, fs1, rm

#### **Operation:**

 $rd \leftarrow half\_convert\_to\_unsigned\_long(fs1)$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Affected flag bits:

Floating-point status bits NV and NX

#### Notes:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fcvt.lu.h rd, fs1, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fcvt.lu.h rd, fs1, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fcvt.lu.h rd, fs1, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fcvt.lu.h rd, fs1, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fcvt.lu.h rd, fs1, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.


• 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fcvt.lu.h rd, fs1.

#### Instruction format:

31 25	24 20	19 15	14 12	11 7	6 0
1100010	00011	fs1	rm	rd	1010011

## 15.6.12 FCVT.S.H: an instruction that converts half-precision floating-point data to single precision floating-point data

#### Syntax:

fcvt.s.h fd, fs1

#### **Operation:**

 $fd \leftarrow half\_convert\_to\_single(fs1)$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Affected flag bits:

None

#### Instruction format:

31	25 24	20	19 1	.5 14 12	11 7	6 0
0100000	(	00010	fs1	000	fd	1010011

## 15.6.13 FCVT.W.H: an instruction that converts a half-precision floating-point number to a signed integer

#### Syntax:

fcvt.w.h rd, fs1, rm

#### **Operation:**

 $tmp \leftarrow half\_convert\_to\_signed\_int(fs1)$ 

 $rd{\leftarrow}sign\_extend(tmp)$ 

#### Permission:

M mode/S mode/U mode



#### Exception:

Illegal instruction.

#### Affected flag bits:

Floating-point status bits NV and NX

#### Notes:

RM determines the round-off mode:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fcvt.w.h rd, fs1, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fcvt.w.h rd, fs1, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fcvt.w.h rd, fs1, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fcvt.w.h rd, fs1, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fcvt.w.h rd, fs1, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fcvt.w.h rd, fs1.

#### Instruction format:

31	25 24 20	19 15	14 12	11 7	6 0
1100010	00000	fs1	rm	rd	1010011

## 15.6.14 FCVT.WU.H: an instruction that converts a half-precision floating-point number to an unsigned integer

#### Syntax:

fcvt.wu.h rd, fs1, rm

#### **Operation:**

 $tmp \leftarrow half\_convert\_to\_unsigned\_int(fs1)$ 

 $rd{\leftarrow}sign\_extend(tmp)$ 

#### Permission:

M mode/S mode/U mode



#### Exception:

Illegal instruction.

#### Affected flag bits:

Floating-point status bits NV and NX

#### Notes:

RM determines the round-off mode:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fcvt.wu.h rd, fs1, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fcvt.wu.h rd, fs1, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fcvt.wu.h rd, fs1, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fcvt.wu.h rd, fs1, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fcvt.wu.h rd, fs1, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fcvt.wu.h rd, fs1.

#### Instruction format:



## 15.6.15 FDIV.H: a half-precision floating-point division instruction

#### Syntax:

fdiv.h fd, fs1, fs2, rm

#### **Operation:**

 $\mathrm{fd} \leftarrow \mathrm{fs1} \ / \ \mathrm{fs2}$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.



#### Affected flag bits:

Floating-point status bits NV, DZ, OF, UF, and NX

#### Notes:

RM determines the round-off mode:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fdiv.h fs1, fs2, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fdiv.h fd fs1, fs2, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fdiv.h fd, fs1, fs2, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fdiv.h fd, fs1, fs2, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fdiv.h fd, fs1, fs2, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fdiv.h fd, fs1, fs2.

#### Instruction format:

31 25	24 20	19 15	14 12	11 7	6 0
0001110	fs2	fs1	rm	fd	1010011

## 15.6.16 FEQ.H: an equal instruction that compares two half-precision numbers

#### Syntax:

feq.h rd, fs1, fs2

#### **Operation:**

if(fs1 == fs2)

 $\mathrm{rd} \gets 1$ 

else

 $\mathrm{rd} \gets 0$ 

#### Permission:

M mode/S mode/U mode



#### Exception:

Illegal instruction.

#### Affected flag bits:

Floating-point status bit NV

#### Instruction format:



## 15.6.17 FLE.H: a less than or equal to instruction that compares two half-precision floating-point numbers

#### Syntax:

fle.h rd, fs1, fs2

#### **Operation:**

 $if(fs1 \le fs2)$ 

 $\mathrm{rd} \gets 1$ 

else

 $\mathrm{rd} \gets 0$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Affected flag bits:

Floating-point status bit NV

#### Instruction format:

31	25 24	20	19 15	14 12	11 7	6 0
1010010		fs2	fs1	000	rd	1010011

## 15.6.18 FLH: an instruction that loads half-precision floating-point data

#### Syntax:

flh fd, imm12(rs1)

#### **Operation:**



 $address \leftarrow rs1 + sign\_extend(imm12)$ 

 $fd[15:0] \leftarrow mem[(address+1):address]$ 

 $fd[63:16] \leftarrow 48'$  hffffffffff

#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Affected flag bits:

None

#### Instruction format:

31 2	0 19	15	14 12	11 7	6 0
imm12[11:0]	rs1		001	rd	0000111

## 15.6.19 FLT.H: a less than instruction that compares two half-precision floating-point numbers

#### Syntax:

flt.h rd, fs1, fs2

#### Operation:

if(fs1 < fs2)

 $\mathrm{rd} \gets 1$ 

else

 $\mathrm{rd} \gets 0$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Affected flag bits:

Floating-point status bit NV

#### Instruction format:

31	25 24	4 20	19 15	14 12	11 7	6 <mark>0</mark>
1	010010	fs2	fs1	001	rd	1010011



## 15.6.20 FMADD.H: a half-precision floating-point multiply-add instruction

#### Syntax:

fmadd.h fd, fs1, fs2, fs3, rm

#### **Operation:**

 $\mathrm{fd} \gets \mathrm{fs1}^*\mathrm{fs2} + \mathrm{fs3}$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Affected flag bits:

Floating-point status bits NV, OF, UF, and IX

#### Notes:

RM determines the round-off mode:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fmadd.h fd, fs1, fs2, fs3, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fmadd.h fd, fs1, fs2, fs3, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fmadd.h fd, fs1, fs2, fs3, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fmadd.h fd, fs1, fs2, fs3, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fmadd.h fd, fs1, fs2, fs3, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fmadd.h fd, fs1, fs2, fs3.

#### Instruction format:





## 15.6.21 FMAX.H: a half-precision floating-point maximum instruction

#### Syntax:

fmax.h fd, fs1, fs2

#### **Operation:**

 $if(fs1 \ge fs2)$ 

 $\mathrm{fd} \gets \mathrm{fs1}$ 

else

 $\mathrm{fd} \gets \mathrm{fs2}$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Affected flag bits:

Floating-point status bit NV

#### Instruction format:

31 25	24 20	19 15	14 12	11 7	6 0
0010110	fs2	fs1	001	fd	1010011

## 15.6.22 FMIN.H: a half-precision floating-point minimum instruction

Syntax:

fmin.h fd, fs1, fs2

#### **Operation:**

 $if(fs1 \ge fs2)$ 

 $\mathrm{fd} \gets \mathrm{fs2}$ 

else

 $\mathrm{fd} \gets \mathrm{fs1}$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.



#### Affected flag bits:

Floating-point status bit NV

#### Instruction format:

31	25 24	1 20	19 15	14 12	11 7	6 0
0010	110	fs2	fs1	000	fd	1010011

## 15.6.23 FMSUB.H: a half-precision floating-point multiply-subtract instruction

#### Syntax:

fmsub.h fd, fs1, fs2, fs3, rm

#### **Operation:**

 $\mathrm{fd} \leftarrow \mathrm{fs1*fs2}$ - fs3

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Affected flag bits:

Floating-point status bits NV, OF, UF, and IX

#### Notes:

RM determines the round-off mode:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fmsub.h fd, fs1, fs2, fs3, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fmsub.h fd, fs1, fs2, fs3, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fmsub.h fd, fs1, fs2, fs3, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fmsub.h fd, fs1, fs2, fs3, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fmsub.h fd, fs1, fs2, fs3, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fmsub.h fd, fs1, fs2, fs3.



#### Instruction format:

31	27	26 25	24 20	19 15	14 12	11 7	6 0
	fs3	10	fs2	fs1	rm	fd	1000111

## 15.6.24 FMUL.H: a half-precision floating-point multiply instruction

#### Syntax:

fmul.h fd, fs1, fs2, rm

#### **Operation:**

 $\mathrm{fd} \gets \mathrm{fs1} \, * \, \mathrm{fs2}$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Affected flag bits:

Floating-point status bits NV, OF, UF, and NX

#### Notes:

RM determines the round-off mode:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fmul.h fd, fs1, fs2, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fmul.h fd, fs1, fs2, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fmul.h fd, fs1, fs2, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fmul.h fd, fs1, fs2, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fmul.h fd, fs1,fs2 , rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fmul.h fs1,fs2.

#### Instruction format:



31	25	24 20	19 15	14 12	11 7	6 0
	0001010	fs2	fs1	rm	fd	1010011

## 15.6.25 FMV.H.X: a half-precision floating-point write transmit instruction

#### Syntax:

fmv.h.x fd, rs1

#### **Operation:**

 $fd[15:0] \leftarrow rs1[15:0]$ 

 $fd[63:16] \leftarrow 48'$  hffffffffff

#### **Permission:**

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Affected flag bits:

None

#### Instruction format:

31	25 24	20 19	15 14 12	11 7	6 0
1111010	00000	rs1	000	fd	1010011

## 15.6.26 FMV.X.H: a transmission instruction that reads half-precision floating-point registers

#### Syntax:

fmv.x.h rd, fs1

#### **Operation:**

 $tmp[15:0] \leftarrow fs1[15:0]$ 

 $rd \leftarrow sign\_extend(tmp[15:0])$ 

#### **Permission:**

M mode/S mode/U mode

#### Exception:

Illegal instruction.



Affected flag bits:

None

#### Instruction format:

31	25 24 20	19 15	14 12	11 7	6 0
1110010	00000	fs1	000	rd	1010011

## 15.6.27 FNMADD.H: a half-precision floating-point negate-(multiply-add) instruction

#### Syntax:

fnmadd.h fd, fs1, fs2, fs3, rm

#### **Operation:**

 $fd \leftarrow -(fs1*fs2 + fs3)$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Affected flag bits:

Floating-point status bits NV, OF, UF, and IX

#### Notes:

RM determines the round-off mode:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fnmadd.h fd,fs1, fs2, fs3, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fnmadd.h fd,fs1, fs2, fs3, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fnmadd.h fd,fs1, fs2, fs3, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fnmadd.h fd,fs1, fs2, fs3, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fnmadd.h fd,fs1, fs2, fs3, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fnmadd.h fd,fs1, fs2, fs3.

#### Instruction format:

31 27	26 25 24	20 19	15 14 12	11 7	6 0
fs3	10 fs2	fs1	rm	fd	1001111

## 15.6.28 FNMSUB.H: a half-precision floating-point negate-(multiply-subtract) instruction

#### Syntax:

fnmsub.h fd, fs1, fs2, fs3, rm

#### **Operation:**

 $fd \leftarrow -(fs1*fs2 - fs3)$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Affected flag bits:

Floating-point status bits NV, OF, UF, and IX

#### Notes:

RM determines the round-off mode:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fnmsub.h fd,fs1, fs2, fs3, rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fnmsub.h fd,fs1, fs2, fs3, rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fnmsub.h fd,fs1, fs2, fs3, rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fnmsub.h fd,fs1, fs2, fs3, rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fnmsub.h fd,fs1, fs2, fs3, rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fnmsub.h fd,fs1, fs2, fs3.

#### Instruction format:



31	27	26 25	24 20	19 15	14	12	11 7	6	0
fs3		10	fs2	fs1	r	m	fd	1001011	

## 15.6.29 FSGNJ.H: a half-precision floating-point sign-injection instruction

#### Syntax:

fsgnj.h fd, fs1, fs2

#### **Operation:**

 $\mathrm{fd}[14:0] \leftarrow \mathrm{fs1}[14:0]$ 

 $\mathrm{fd}[15] \leftarrow \mathrm{fs2}[15]$ 

 $fd[63:16] \leftarrow 48'$  hffffffffff

#### **Permission:**

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Affected flag bits:

None

#### Instruction format:



### 15.6.30 FSGNJN.H: a half-precision floating-point sign-injection negate instruction

#### Syntax:

fsgnjn.h fd, fs1, fs2

#### **Operation:**

 $\mathrm{fd}[14:0] \leftarrow \mathrm{fs1}[14:0]$ 

 $\operatorname{fd}[15] \leftarrow ! \operatorname{fs2}[15]$ 

 $fd[63:16] \leftarrow 48'$  hffffffffff

#### Permission:

M mode/S mode/U mode



#### Exception:

Illegal instruction.

#### Affected flag bits:

None

#### Instruction format:



## 15.6.31 FSGNJX.H: a half-precision floating-point sign-injection XOR instruction

#### Syntax:

fsgnjx.h fd, fs1, fs2

#### **Operation:**

 $fd[14:0] \leftarrow fs1[14:0]$ 

 $\mathrm{fd}[15] \leftarrow \mathrm{fs1}[15] \widehat{} \mathrm{fs2}[15]$ 

 $fd[63:16] \leftarrow 48$ ' hffffffffff

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Affected flag bits:

None

#### Instruction format:

31	25	24 20	19 15	14 12	11 7	6 0
0010010		fs2	fs1	010	fd	1010011

## 15.6.32 FSH: an instruction that stores half-precision floating point numbers

#### Syntax:

fsh fs2, imm12(fs1)

#### **Operation:**

 $address \leftarrow fs1 + sign\_extend(imm12)$ 

```
mem[(address+1):address] \leftarrow fs2[15:0]
```





#### Permission:

M mode/S mode/U mode

#### Exception:

Unaligned access, access error, page error, or illegal instruction.

#### Instruction format:

31	25	24 20	19 15	14 12	11 7	6 0
	imm12[11:5]	fs2	fs1	001	imm12[4:0]	0100111

# 15.6.33 FSQRT.H: an instruction that calculates the square root of the half-precision floating-point number

#### Syntax:

fsqrt.h fd, fs1, rm

#### **Operation:**

 $fd \leftarrow sqrt(fs1)$ 

#### Permission:

M mode/S mode/U mode

#### Exception:

Illegal instruction.

#### Affected flag bits:

Floating-point status bits NV and NX

#### Notes:

RM determines the round-off mode:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fsqrt.h fd, fs1,rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fsqrt.h fd, fs1,rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fsqrt.h fd, fs1,rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fsqrt.h fd, fs1,rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fsqrt.h fd, fs1,rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.



• 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fsqrt.h fd, fs1.

#### Instruction format:

31	25 24	20 19	15 14	4 12	11 7	6 0
010	.110 0	00000 fs	1	rm	fd	1010011

## 15.6.34 FSUB.H: a half-precision floating-point subtract instruction

#### Syntax:

fsub.h fd, fs1, fs2, rm

#### **Operation:**

 $\mathrm{fd} \gets \mathrm{fs1} \text{ - } \mathrm{fs2}$ 

#### Permission:

 $M \mod/S \mod/U \mod$ 

#### Exception:

Illegal instruction.

#### Affected flag bits:

Floating-point status bits NV, OF, and NX

#### Notes:

RM determines the round-off mode:

- 3' b000: Rounds off to the nearest even number. The corresponding assembler instruction is fsub.h fd, fs1,fs2,rne.
- 3' b001: Rounds off to zero. The corresponding assembler instruction is fsub.h fd, fs1,fs2,rtz.
- 3' b010: Rounds off to negative infinity. The corresponding assembler instruction is fsub.h fd, fs1,fs2,rdn.
- 3' b011: Rounds off to positive infinity. The corresponding assembler instruction is fsub.h fd, fs1,fs2,rup.
- 3' b100: Rounds off to the nearest large value. The corresponding assembler instruction is fsub.h fd, fs1,fs2,rmm.
- 3' b101: This code is reserved and not used.
- 3' b110: This code is reserved and not used.
- 3' b111: Dynamically rounds off based on the rm bit of the fcsr register. The corresponding assembler instruction is fsub.h fd, fs1,fs2.



## Instruction format:

31	25 24 20	19 15	14 12	11 7	6 0
0000110	fs2	fs1	rm	fd	1010011

## Chapter 16

## Appendix C Control Registers

This section describes the M-mode control registers, S-mode control registers, and U-mode control registers.

## 16.1 Appendix C-1 M-mode control registers

M-mode control registers are classified by function into M-mode information registers, M-mode exception configuration registers, M-mode exception handling registers, M-mode memory protection registers, M-mode counter registers, and M-mode counter configuration registers.

#### 16.1.1 M-mode information register group

#### 16.1.1.1 Machine vendor ID register (mvendorid)

The mvendorid register stores the vendor IDs of T-Head Semiconductor Co., Ltd. It is not defined and the values are all zero.

This register is 64 bits wide and is read-only in M-mode. Accesses in non-M-mode and writes in M-mode will cause an illegal instruction exception.

#### 16.1.1.2 Machine architecture ID register (marchid)

The marchid register stores the architecture IDs of CPU cores. It stores internal IDs of T-Head Semiconductor Co., Ltd. and its reset value is subject to the product.

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This register is 64 bits wide and is read-only in M-mode. Accesses in non-M-mode and writes in M-mode will cause an illegal instruction exception.

#### 16.1.1.3 Machine implementation ID register (mimpid)

The mimpid register stores hardware implementation IDs of CPU cores. This register is not implemented by C910, and its read access value is 0.

This register is 64 bits wide and is read-only in M-mode. Accesses in non-M-mode and writes in M-mode will cause an illegal instruction exception.

#### **16.1.1.4** Machine hart ID register (mhartid)

The mhartid register stores hart IDs of CPU cores.

This register is 64 bits wide and is read-only in M-mode. Accesses in non-M-mode and writes in M-mode will cause an illegal instruction exception.

#### 16.1.2 M-mode exception configuration register group

#### 16.1.2.1 Machine status register (mstatus)

The mstatus register stores status and control information of the CPU in M-mode, including the global interrupt enable bit, exception preserve interrupt enable bit, and exception preserve privilege mode bit.

This register is 64 bits wide and is readable and writable in M-mode. Accesses in non-M-mode will cause an illegal instruction exception.



Machine status register (mstatus)

#### SIE: supervisor interrupt enable bit



- When SIE is 0, S-mode interrupts are invalid.
- When SIE is 1,S-mode interrupts are valid.

This bit is reset to 0 when the CPU is downgraded to the S-mode response interrupt, and is set to the value of SPIE when the CPU exits the interrupt service program.

#### MIE: machine interrupt enable bit

- When MIE is 0, M-mode interrupts are invalid.
- When MIE is 1, M-mode interrupts are valid.

This bit is reset to 0 when the response is interrupted in M-mode on the CPU, and is set to the value of MPIE when the CPU exits the interrupt service program.

#### SPIE: supervisor preserve interrupt enable bit

This bit stores the value of the SIE bit before the response is interrupted in S-mode on the CPU.

This bit will be reset to 0, and set to 1 when the CPU exits the interrupt service program.

#### MPIE: machine preserve interrupt enable bit

This bit stores the value of the MIE bit before the response is interrupted in M-mode on the CPU.

This bit will be reset to 0, and set to 1 when the CPU exits the interrupt exception service program.

#### SPP: supervisor preserve privilege bit

This bit stores the privilege status before the CPU accesses the exception service program in S-mode.

- When SPP is 2' b00, the CPU is in U-mode before accessing the exception service program.
- When SPP is 2' b01, the CPU is in S-mode before accessing the exception service program.

This bit will be reset to 2' b01.

#### MPP: machine preserve privilege bit

This bit stores the privilege status before the CPU accesses the exception service program in M-mode.

- When MPP is 2' b00, the CPU is in U-mode before entering the exception service program.
- When MPP is 2' b01, the CPU is in S-mode before accessing the exception service program.
- When MPP is 2' b11, the CPU is in M-mode before entering the exception service program.

This bit will be reset to 2' b11.

#### FS: floating-point status bit

This bit determines whether to store floating-point registers during context switching.

- When FS is 2' b00, the floating-point unit is in the Off state and exceptions will occur for accesses to related floating-point registers.
- When FS is 2' b01, the floating-point unit is in the Initial state.

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- When FS is 2' b10, the floating-point unit is in the Clean state.
- When FS is 2' b11, the floating-point unit is in the Dirty state, which means the floating-point and control registers have been modified.

#### XS: extension status bit

C910 has no extension units, and therefore this bit is fixed to 0.

#### MPRV: modify privilege mode

- When MPRV is 1, load and store requests are executed based on the privilege mode in MPP.
- When MPRV is 0, load and store requests are executed based on the current privilege mode of the CPU.

#### SUM: allow S-mode accesses to U-mode virtual memory spaces

- When SUM is 1, load, storage, and value-taking requests can be initiated in S-mode to access U-mode virtual memory spaces.
- When SUM is 0, load, storage, and value-taking requests cannot be initiated in S-mode to access virtual memory spaces marked as U-mode.

#### MXR: allow accesses of load requests to memory spaces marked as executable

- When MXR is 1, accesses of load requests are allowed to virtual memory spaces marked as executable or readable.
- When MXR is 0, accesses of load requests are allowed only to virtual memory spaces marked as readable.

#### TVM: trap virtual memory

- When TVM is 1, an illegal instruction exception occurs for reads and writes to the satp control register and for the execution of the sfence instruction in S-mode.
- When TVM is 0, reads and writes to the satp control register and the execution of the sfence instruction are allowed in S-mode.

#### TW: timeout wait

- When TW is 1, an illegal instruction exception occurs if the WFI instruction is executed in S-mode.
- When TW is 0, the WFI instruction can be executed in S-mode.

#### TSR: trap sret

• When TSR is 1, an illegal instruction exception occurs if the sret instruction is executed in S-mode.

When TSR is 0, the sret instruction can be executed in S-mode.

#### VS: vector status bit

This bit determines whether to store vector registers during context switching.



- When VS is 2' b00, the vector unit is in the Off state and exceptions will occur for accesses to related vector registers.
- When VS is 2' b01, the vector unit is in the Initial state.
- When VS is 2' b10, the vector unit is in the Clean state.
- When VS is 2' b11, the vector unit is in the Dirty state, which means the vector registers and vector control registers have been modified.

The VS bit is valid only when the vector execution unit is configured, and is always 0 if the vector execution unit is not configured.

#### UXL: register width

This bit is read-only and always 2, which means the register is 64 bits wide in U-mode.

#### SXL: register width

This bit is read-only and always 2, which means the register is 64 bits wide in S-mode.

#### SD: dirty state sum bit of the floating-point, vector, and extension units

- When SD is 1, the floating-point unit, vector unit, or extension unit is in the Dirty state.
- When SD is 0, none of the floating-point, vector, and extension units is in the Dirty state.

#### 16.1.2.2 M-mode instruction set architecture register (misa)

The misa register stores the features of the instruction set architecture supported by the CPU.

This register is 64 bits wide and is readable and writable in M-mode. Accesses in non-M-mode will cause an illegal instruction exception.

C910 supports the RV64GC instruction set architecture, and the reset value of the MISA register is 0x80000000094112d. For more information about the assignment rules, see the official document of RISC-V riscv-privileged.

C910 does not support the dynamic configuration of the MISA register. Writes to this register do not take effect.

#### 16.1.2.3 M-mode exception downgrade control register (medeleg)

The medeleg register can downgrade exceptions that occur in S-mode and U-mode to S-mode responses. The lower 16 bits of the medeleg register are in one-to-one correspondence to exception vector tables. Exceptions to be downgraded to S-mode responses can be selected.

This register is 64 bits wide and is readable and writable in M-mode. Accesses in non-M-mode will cause an illegal instruction exception.

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#### 16.1.2.4 M-mode interrupt downgrade control register (mideleg)

The mideleg register can downgrade S-mode interrupts to S-mode responses.



M-mode interrupt downgrade control register (mideleg)

This register is 64 bits wide and is readable and writable in M-mode. Accesses in non-M-mode will cause an illegal instruction exception.

#### 16.1.2.5 M-mode interrupt-enable register (mie)

The mie register enables and masks different types of interrupts. This register is 64 bits wide and is readable and writable in M-mode. Accesses in non-M-mode will cause an illegal instruction exception.



M-mode interrupt-enable register (mie)

#### SSIE: S-mode software interrupt enable bit

- When SSIE is 0, S-mode software external interrupts are invalid.
- When SSIE is 1, S-mode software external interrupts are valid.

#### MSIE: M-mode software interrupt enable bit

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- When MSIE is 0, M-mode software interrupts are invalid.
- When MSIE is 1, M-mode software interrupts are valid.

#### STIE: S-mode timer interrupt enable bit

- When STIE is 0, S-mode timer interrupts are invalid.
- When STIE is 1, S-mode timer interrupts are valid.

#### MTIE: M-mode timer interrupt enable bit

- When MTIE is 0, M-mode timer interrupts are invalid.
- When MTIE is 1, M-mode timer interrupts are valid.

#### SEIE: S-mode external interrupt enable bit

- When SEIE is 0, S-mode external interrupts are invalid.
- When SEIE is 1, S-mode external interrupts are valid.

#### MEIE: M-mode external interrupt enable bit

- When MEIE is 0, M-mode external interrupts are invalid.
- When MEIE is 1, M-mode external interrupts are valid.

#### MOIE: M-mode overflow interrupt enable bit

- When MOIE is 0, M-mode counter overflow interrupts are invalid.
- When MOIE is 1, M-mode counter overflow interrupts are valid.

#### 16.1.2.6 M-mode trap vector base address register (mtvec)

The mtvec register stores the entry address of the exception service program.

This register is 64 bits wide and is readable and writable in M-mode. Accesses in non-M-mode will cause an illegal instruction exception.



M-mode trap vector base address register (mtvec)

#### BASE: vector base address bit

The BASE bit indicates the upper 62 bits of the entry address of the exception service program. Combining this base address with 2' b00 obtains the entry address of the exception service program.



This bit will be reset to 0.

#### MODE: vector entry mode bit

- When MODE[1:0] is 2' b00, the base address is used as the entry address for both exceptions and interrupts.
- When MODE[1:0] is 2' b01, the base address is used as the entry address for exceptions, and BASE + 4\*cause is used as the entry address for interrupts.

#### 16.1.2.7 M-mode counter access enable register (mcounteren)

The mounteren register determines whether U-mode counters can be accessed in S-mode.

For more information, see ref: performance\_test.

### 16.1.3 M-mode exception handling register group

#### 16.1.3.1 M-mode scratch register (mscratch)

The mscratch register is used by the CPU to back up temporary data in the exception service program. It is usually used to store the entry pointer to the local context space in M-mode.

This register is 64 bits wide and is readable and writable in M-mode. Accesses in non-M-mode will cause an illegal instruction exception.

#### 16.1.3.2 M-mode exception program counter register (mepc)

The mepc register stores the program counter value (PC value) when the CPU exits from the exception service program. C910 supports 16 bits wide instructions. The MEPC value is aligned with 16 bits and the lowest bit is 0.

This register is 64 bits wide and is readable and writable in M-mode. Accesses in non-M-mode will cause an illegal instruction exception.

#### **16.1.3.3** M-mode cause register (mcause)

The meause register stores the vector numbers of events that trigger exceptions. The vector numbers are used to handle corresponding events in the exception service program.

This register is 64 bits wide and is readable and writable in M-mode. Accesses in non-M-mode will cause an illegal instruction exception.



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M-mode cause register (mcause)

#### Interrupt: interrupt bit

- When the Interrupt bit is 0, the corresponding exception is not triggered by an interrupt. The exception code is parsed as an exception.
- When the Interrupt bit is 1, the corresponding exception is triggered by an interrupt. The exception code is parsed as an interrupt.

#### Exception Code: exception vector number

When the CPU encounters an exception, the Exception Code bit will be updated to the value of the exception source.

#### 16.1.3.4 M-mode interrupt-pending register (mip)

The mip register stores information about pending interrupts. When the CPU cannot immediately respond to an interrupt, the corresponding bit in the mip register will be set.

Writing the msip and ssip registers in the CLINT interrupt controller can trigger corresponding interrupts. After the interrupts become valid, the msip bit and ssip bit can be queried based on the corresponding bits in the mip register.

This register is 64 bits wide and is readable and writable in M-mode. Accesses in non-M-mode will cause an illegal instruction exception.



M-mode interrupt-pending register (mip)

SSIP: supervisor software interrupt pending bit



- When SSIP is 0, there is no pending S-mode software interrupt on the CPU.
- When SSIP is 1, there are pending S-mode software interrupts on the CPU.

The SSIP bit is readable and writable in M-mode. After it is delegated to S-mode, it is readable and writable in S-mode. Otherwise, it is read-only in S-mode.

#### MSIP: M-mode software interrupt pending bit

- When MSIP is 0, there is no pending M-mode software interrupt on the CPU.
- When MSIP is 1, there are pending M-mode software interrupts on the CPU. This bit is read-only.

#### STIP: S-mode timer interrupt pending bit

- When STIP is 0, there is no pending S-mode timer interrupt on the CPU.
- When STIP is 1, there are pending S-mode timer interrupts on the CPU.

#### MTIP: M-mode timer interrupt pending bit

- When MTIP is 0, there is no pending M-mode timer interrupt on the CPU.
- When MTIP is 1, there are pending M-mode timer interrupts on the CPU.

#### SEIP: S-mode external interrupt pending bit

- When SEIP is 0, there is no pending S-mode external interrupt on the CPU.
- When SEIP is 1, there are pending S-mode external interrupts on the CPU.

#### MEIP: machine external interrupt pending bit

- When MEIP is 0, there is no pending M-mode external interrupt on the CPU.
- When MEIP is 1, there are pending M-mode external interrupts on the CPU.

#### MOIP: M-mode overflow interrupt pending bit

- When MOIP is 0, there is no pending M-mode counter overflow interrupt on the CPU.
- When MOIP is 1, there are pending M-mode counter overflow interrupts on the CPU.

#### 16.1.4 M-mode memory protection registers

M-mode memory protection registers are related to the settings of the memory protection unit.

#### 16.1.4.1 Physical memory protection configuration register (pmpcfg)

The pmpcfg register configures access permissions and address matching mode for the physical memory.

This register is 64 bits wide and is readable and writable in M-mode. Accesses in non-M-mode will cause an illegal instruction exception.



For more information, see ref: *physical\_mem\_pmpcfg*.

#### **16.1.4.2** Physical memory address register (pmpaddr)

The pmpaddr register configures the address range of each entry of the physical memory.

This register is 64 bits wide and is readable and writable in M-mode. Accesses in non-M-mode will cause an illegal instruction exception.

For more information, see ref: *physical\_mem\_pmpaddr*.

#### **16.1.5** M-mode counter registers

M-mode counter registers belong to the PMU and collect software and hardware information during a program operation for software development personnel to optimize programs.

#### 16.1.5.1 M-mode cycle counter (mcycle)

The mcycle counter stores the cycles executed by the CPU. When the CPU is in the execution state (non-low power state), the mcycle register increases the count upon each execution cycle.

The mcycle counter is 64 bits wide and will be reset to 0.

For more information, see ref: performance\_test\_cont.

#### 16.1.5.2 M-mode instructions-retired counter (minstret)

The minstret counter stores the number of retired instructions of the CPU. The minstret register increases the count when each instruction retires.

The minstret counter is 64 bits wide and will be reset to 0.

For more information, see ref: performance\_test\_cont.

#### **16.1.5.3** M-mode event counter (mhpmcountern)

The mhpmcountern counter counts events.

The mhpmcountern counter is 64 bits wide and will be reset to 0.

For more information, see ref: performance\_test\_cont.

#### **16.1.6** M-mode counter configuration registers

The M-mode counter configuration register (mhpmeventn) selects events for M-mode event counters.



#### 16.1.6.1 M-mode event selector (mhpmeventn)

The events mhpmevent3-31 selected by the mhpmeventn register for M-mode event counters mhpmcounter3-31 are in one-to-one correspondence. In C910, event counters can count only specified events. Therefore, only specified values can be written to mhpmevent3-31.

The mhpmeventn counter is 64 bits wide and will be reset to 0.

For more information, see ref: performance\_test\_mhpmevent.

## 16.1.7 M-mode CPU control and status extension registers

C910 extends some registers for the CPU and status, including the M-mode extension status register (mxstatus) and M-mode hardware control register (mhcr), M-mode hardware operation register (mcor), M-mode L2 Cache control register (mccr2), M-mode implicit operation register (mhint), M-mode reset vector base address register (mrvbr), S-mode counter write enable register (mcounterwen), M-mode event interrupt enable register (mcounterinten), and M-mode event overflow mark register (mcounterof).

#### 16.1.7.1 M-mode extension status register (mxstatus)

The mxstatus register stores the current privilege mode of the CPU and the enable bit of the extension functions of C910.

This register is 64 bits wide and is readable and writable in M-mode. Accesses in non-M-mode will cause an illegal instruction exception.



M-mode extension status register (mxstatus)

#### PMDU: U-mode performance monitoring count enable bit

When PMDU is 0, performance counters are allowed to count in U-mode.



When PMDU is 1, performance counters are not allowed to count in U-mode.

#### PMDS: S-mode performance monitoring count enable bit

When PMDS is 0, performance counters are allowed to count in S-mode.

When PMDS is 1, performance counters are not allowed to count in S-mode.

#### PMDM: M-mode performance monitoring count enable bit

When PMDM is 0, performance counters are allowed to count in M-mode.

When PMDM is 1, performance counters are not allowed to count in M-mode.

#### PMP4K: PMP minimum granularity control bit

The minimum PMP granularity supported by C910 is 4 KB, which is not affected by this bit.

#### MM: misaligned access enable bit

When MM is 0, misaligned accesses are not supported and cause misaligned exceptions.

When MM is 1, misaligned accesses are supported and processed by hardware. (The default value of this bit is 1 in C910.)

#### UCME: execute extended cache instructions in U-mode

When UCME is 0, extended cache instructions cannot be executed in U-mode. Otherwise, instruction exceptions may occur.

When UCME is 1, extended cache instructions can be executed in U-mode.

#### CLINTEE: Clint timer/software interrupt supervisor extension enable bit

When CLINTEE is 0, supervisor software interrupts and timer interrupts initiated by Clint are not responded to.

When CLINTEE is 1, supervisor software interrupts and timer interrupts initiated by Clint can be responded to.

#### MHRD: disable hardware writeback

When MHRD is 0, hardware writeback is performed if the TLB is missing.

When MHRD is 1, hardware writeback is not performed after the TLB is missing.

#### INSDE: disable Icache snoop D-Cache

When INSDE is 0, D-Cache is snooped after I-Cache is missing.

When INSDE is 1, D-Cache is not snooped after I-Cache is missing.

#### MAEE: extend MMU address attribute

When MAEE is 0, the MMU address attribute is not extended.

When MAEE is 1, the address attribute is extended in the PTE of the MMU. Users can configure the address attribute of pages.



#### THEADISAEE: enables extended instruction sets

When THEADISAEE is 0, using C910 extended instruction sets causes instruction exceptions.

When THEADISAEE is 1, C910 extended instruction sets can be used.

#### PM: privilege mode

When PM is 2' b00, the CPU is running in U-mode.

When PM is 2' b01, the CPU is running in S-mode.

When PM is 2' b11, the CPU is running in M-mode. (The PM bit will be reset to M-mode.)

#### 16.1.7.2 M-mode hardware configuration register (mhcr)

The mhcr register configures the performance and functions of the CPU.

This register is 64 bits wide and is readable and writable in M-mode. Accesses in non-M-mode will cause an illegal instruction exception.



M-mode hardware configuration register (mhcr)

#### IE: I-Cache enable bit

When IE is 0, I-Cache is disabled.

When IE is 1, I-Cache is enabled.

#### DE: D-Cache enable bit

When DE is 0, D-Cache is disabled.

When DE is 1, D-Cache is enabled.

#### WA: cache write allocate set bit

When WA is 0, the data cache is in write non-allocate mode.

When WA is 1, the data cache is in write allocate mode.

WB: cache writeback set bit



When WB is 0, the data cache is in write-through mode.

When WB is 1, the data cache is in writeback mode.

C910 supports only the writeback mode. Therefore, the WB bit is fixed to 1.

#### RS: address return stack set bit

When RS is 0, the return stack is disabled.

When RS is 1, the return stack is enabled.

#### BPE: branch prediction enable bit

When BPE is 0, branch prediction is disabled.

When BPE is 1, branch prediction is enabled.

#### BTB: branch target prediction enable bit

When BTB is 0, branch target prediction is disabled.

When BTB is 1, branch target prediction is enabled.

#### IBPE: indirect branch prediction enable bit

When IBPE is 0, indirect branch prediction is disabled.

When IBPE is 1, indirect branch prediction is enabled.

#### WBR: write burst transmission enable bit

When WBR is 0, write burst transmission is not supported.

When WBR is 1, write burst transmission is supported.

The WBR bit is fixed to 1 by default in C910, and cannot be modified.

#### L0BTB: level-1 branch target prediction enable bit

When L0BTB is 0, level-1 branch target prediction is disabled.

When L0BTB is 1, level-1 branch target prediction is enabled.

#### SCK: ratio of system clock to CPU clock

This bit indicates the ratio of the system clock to the CPU clock. The calculation format is SCK+1. There are corresponding pins on the CPU. The SCK bit is configured during a reset and cannot be modified later.

#### 16.1.7.3 M-mode hardware operation register (mcor)

The mcor register performs related operations on caches and branch predictors.

This register is 64 bits wide and is readable and writable in M-mode. Accesses in non-M-mode will cause an illegal instruction exception.



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M-mode hardware operation register (mcor)

#### CACHE\_SEL: cache select bit

When CACHE\_SEL is 2' b01, the instruction cache is selected.

When CACHE\_SEL is 2' b10, the data cache is selected.

When CACHE\_SEL is 2' b11, the instruction and data caches are selected.

#### INV: cache invalidate bit

When INV is 0, caches are not invalidated.

When INV is 1, caches are invalidated.

#### CLR: dirty entry clear bit

When CLR is 0, dirty entries in caches are not written out of the chip.

When CLR is 1, dirty entries in caches are written out of the chip.

#### BHT\_INV: BHT invalidate bit

When BHT\_INV is 0, data in branch history tables (BHTs) is not invalidated.

When BHT\_INV is 1, data in BHTs is invalidated.

#### BTB\_INV: BTB invalidate bit

When BTB\_INV is 0, data in branch target buffers (BTBs) is not invalidated.

When BTB\_INV is 1, data in BTBs is invalidated.

#### IBP\_INV: IBP invalidate bit

When IBP\_INV is 0, indirect branch prediction (IBP) data is not invalidated.

When IBP\_INV is 1, IBP data is invalidated.

All the preceding invalidate and dirty entry clear bits are set to 1 when corresponding operations are in progress and reset to 0 when the operations are completed.



#### 16.1.7.4 M-mode L2 Cache control register (mccr2)

The mccr2 register configures the access delays of memories in the shared L2 Cache, including L2 Cache enable/disable, instruction prefetch, and TLB prefetch enable.

This register is 64 bits wide and is readable and writable in M-mode. Accesses in non-M-mode will cause a



M-mode L2 Cache control register (mccr2)

#### RFE: read allocation enable bit

When RFE is 0, if accessed data is missing in the L2 Cache, the data is not written back to the L2 Cache.

When RFE is 1, if accessed data is missing in the L2 Cache, the data is written back to the L2 Cache.

#### L2EN: L2 Cache enable bit

When L2EN is 0, the L2 Cache is disabled.

When L2EN is 1, the L2 Cache is enabled. (This bit is fixed to 1 in C910.)

#### DLTNCY: data RAM access cycle configure bit for the L2 Cache

When DLTNCY is 0, the data RAM access cycle is 1.

When DLTNCY is 1, the data RAM access cycle is 2.

When DLTNCY is 2, the data RAM access cycle is 3.

When DLTNCY is 3, the data RAM access cycle is 4.

When DLTNCY is 4, the data RAM access cycle is 5.

When DLTNCY is 5, the data RAM access cycle is 6.

When DLTNCY is 6, the data RAM access cycle is 7.

When DLTNCY is 7, the data RAM access cycle is 8.

#### DSETUP: data RAM setup configure bit for the L2 Cache



When DSETUP is 0, the data RAM does not require an additional setup cycle.

When DSETUP is 1, the data RAM requires an additional setup cycle.

#### TLTNCY: tag RAM access cycle configure bit for the L2 Cache

When TLTNCY is 0, the tag RAM access cycle is 1.

When TLTNCY is 1, the tag RAM access cycle is 2.

When TLTNCY is 2, the tag RAM access cycle is 3.

When TLTNCY is 3, the tag RAM access cycle is 4.

When TLTNCY is 4, the tag RAM access cycle is 5.

#### TSETUP: tag RAM setup configure bit for the L2 Cache

When TSETUP is 0, the tag RAM does not require an additional setup cycle.

When TSETUP is 1, the tag RAM requires an additional setup cycle.

#### IPRF: instruction prefetch capability of the L2 Cache

This bit indicates the number of prefetched cache lines when desired data of a value-taking request is missing in the L2 Cache.

When IPRF is 0, instruction prefetch is disabled for the L2 Cache.

When IPRF is 1, one cache line is prefetched.

When IPRF is 2, two cache lines are prefetched.

When IPRF is 3, three cache lines are prefetched.

#### TPRF: TLB prefetch enable bit for the L2 Cache

When TPRF is 0, TLB prefetch is disabled for the L2 Cache.

When TPRF is 1, TLB prefetch is enabled for the L2 Cache.

#### 16.1.7.5 M-mode implicit operation register (mhint)

The mhint register controls the enable/disable of multiple functions of caches.

This register is 64 bits wide and is readable and writable in M-mode. Accesses in non-M-mode will cause an illegal instruction exception.

M-mode implicit operation register (mhint)

#### DPLD: D-Cache prefetch enable bit

When DPLD is 0, D-Cache prefetch is disabled.

When DPLD is 1, D-Cache prefetch is enabled.




### AMR: write allocate policy automatic adjustment enable bit for the L1 Cache

When AMR is 0, the write allocate policy is subject to the page attribute WA of the access address.

When AMR is 1, if multiple cache lines are stored continuously, desired data of subsequent storage operations of continuous addresses is no longer written to the L1 Cache.

### IPLD: I-Cache prefetch enable bit

When IPLD is 0, I-Cache prefetch is disabled.

When IPLD is 1, I-Cache prefetch is enabled.

### LPE: loop acceleration enable bit

When LPE is 0, loop acceleration is disabled.

When LPE is 1, loop acceleration is enabled.

### IWPE: I-Cache way prediction enable bit

When IWPE is 0, way prediction is disabled for I-Cache.

When IWPE is 1, way prediction is enabled for I-Cache.

### SRE: single retirement enable bit

When SRE is 0, single retirement mode is disabled.

When SRE is 1, single retirement mode is enabled.

### D\_DIS: number of prefetched cache lines in D-Cache

When D\_DIS is 0, two cache lines are prefetched.

When D\_DIS is 1, four cache lines are prefetched.

When D\_DIS is 2, eight cache lines are prefetched.

When D\_DIS is 3, 16 cache lines are prefetched.



The default value is 0.

### L2PLD: the L2 Cache prefetch enable bit

When L2PLD is 0, L2 Cache prefetch is disabled.

When L2PLD is 1, L2 Cache prefetch is enabled.

### L2\_DIS: number of prefetched cache lines in the L2 Cache

When L2\_DIS is 0, eight cache lines are prefetched.

When L2\_DIS is 1, 16 cache lines are prefetched.

When L2\_DIS is 2, 32 cache lines are prefetched.

When L2\_DIS is 3, 64 cache lines are prefetched.

The L2 Cache prefetch is based on the L1 Cache prefetch.

### NO\_SPEC: spec fail prediction enable bit

When NO\_SPEC is 0, spec fail prediction is disabled.

When NO\_SPEC is 1, spec fail prediction is enabled.

### L2STPLD: store prefetch enable bit for the L2 Cache

When L2STPLD is 0, store prefetch is disabled for the L2 Cache.

When L2STPLD is 1, store prefetch is enabled for the L2 Cache.

### TLB\_BROAD\_DIS: the TLB fence operation broadcast disable bit

When TLB\_BROAD\_DIS is 0, sfence.vma instruction operations are broadcast to other cores.

When TLB\_BROAD\_DIS is 1, sfence.vma instruction operations are not broadcast.

This bit is invalid when there is only one core.

### FENCERW\_BROAD\_DIS: fence operation broadcast disable bit

When FENCERW\_BROAD\_DIS is 0, fence instruction operations are broadcast to other cores.

When FENCERW\_BROAD\_DIS is 1, fence instruction operations are not broadcast.

This bit is invalid when there is only one core.

### FENCEI\_BROAD\_DIS: fence.i operation broadcast disable bit

When FENCEI\_BROAD\_DIS is 0, fence.i instruction operations are broadcast to other cores.

When FENCEI\_BROAD\_DIS is 1, fence.i instruction operations are not broadcast.

This bit is invalid when there is only one core.



#### 16.1.7.6 M-mode reset vector base address register (mrvbr)

The mrvbr register stores base addresses of reset exception vectors. Each C910 core has an independent mrvbr register.

This register is 64 bits wide and is read-only in M-mode. Accesses in non-M-mode will cause an illegal instruction exception.

	63 40	39 0
	Reserved	Reset vector base
Reset	0	(Input pin)

M-mode reset vector base address register (mrvbr)

#### Reset vector base: reset base address

It controls the reset base address of a core.

#### 16.1.7.7 S-mode counter write enable register (mcounterwen)

The mounterwen register determines whether S-mode event counters can be written in S-mode.

This register is 64 bits wide and is readable and writable in M-mode. Accesses in non-M-mode will cause an illegal instruction exception.



S-mode counter write enable register (mcounterwen)

When mcounterwen.bit[n] is 1, writes to the corresponding shpmcounter are allowed in S-mode.

When mcounterwen.bit[n] is 0, writes to the corresponding shpmcounter are not allowed in S-mode, and cause instruction exceptions.

#### 16.1.7.8 M-mode event interrupt enable register (mcounterinten)

The mounterinten register enables the triggering of interrupts when event counters overflow.



This register is 64 bits wide and is readable and writable in M-mode. Accesses in non-M-mode will cause an illegal instruction exception.



M-mode event interrupt enable register (mcounterinten)

When mcounterinten.bit[n] is 1, an interrupt is triggered when the corresponding mhpmcounter overflows.

When mcounterinten.bit[n] is 0, an interrupt is not triggered when the corresponding mhpmcounter overflows.

### 16.1.7.9 M-mode event overflow mark register (mcounteren)

The mounteren register marks whether event counters overflow.

This register is 64 bits wide and is readable and writable in M-mode. Accesses in non-M-mode will cause an illegal instruction exception.



M-mode event overflow mark register (mcounteren)

When mcounterof.bit[n] is 1, the corresponding mhpmcounter overflows.

When mcounterof.bit[n] is 0, the corresponding mhpmcounter does not overflow.



## 16.1.8 M-mode cache access extension registers

M-mode cache access extension registers directly read content in the L1 Cache and the L2 Cache for cache debugging.

### 16.1.8.1 M-mode cache instruction register (mcins)

The meins register initiates read requests to the L1 or L2 Cache.

This register is 64 bits wide and is readable and writable in M-mode. Accesses in non-M-mode will cause an illegal instruction exception.



M-mode cache instruction register (mcins)

#### R: cache read access

- When R is 0, cache read requests are not initiated.
- When R is 1, cache read requests are initiated.

### 16.1.8.2 M-mode cache access index register (mcindex)

The mcindex register configures the location of a cache accessed by read requests.

This register is 64 bits wide and is readable and writable in M-mode. Accesses in non-M-mode will cause an illegal instruction exception.



M-mode cache access index register (mcindex)

### RID: RAM flag bit

This bit specifies the accessed RAM.

• When RID is 0, I-Cache tag RAM is accessed.





- When RID is 1, I-Cache data RAM is accessed.
- When RID is 2, D-Cache tag RAM is accessed.
- When RID is 3, D-Cache data RAM is accessed.
- When RID is 4, L2 Cache tag RAM is accessed.
- When RID is 5, L2 Cache data RAM is accessed.
- When RID is 12, D-Cache LD tag RAM is accessed.

### WAY: cache way information

This bit specifies the RAM access way.

#### **INDEX:** cache index

This bit specifies the RAM access index.

### 16.1.8.3 M-mode cache data register (mcdata0/1)

The mcdata0/1 register records data read from the L1 or L2 Cache.

This register is 64 bits wide and is readable and writable in M-mode. Accesses in non-M-mode will cause an illegal instruction exception.



M-mode cache access data register (mcdata)



types	
RAM type	CDATA content
ICACHE TAG	CDATA0[39:12]: TAG
	CDATA0[0]: VALID
ICACHE DATA	CDATA0–CDATA1: 128bit DATA
DCACHE TAG	CDATA0[39:12]: TAG
	CDATA0[2]: DIRTY
	CDATA0[1]: SHARED
	CDATA0[0]: VALID
DCACHE DATA	CDATA0–CDATA1: 128bit DATA
L2CACHE TAG	CDATA0[39:12]: TAG
	CDATA[1]: DIRTY
	CDATA0[0]: VALID
L2CACHE	CDATA0–CDATA1: 128bit DATA
DATA	

 Table 16.1:
 Correspondence between cache data content and RAM

## 16.1.9 M-mode CPU model registers

### 16.1.9.1 M-mode CPU model register (mcpuid)

The mcpuid registers store CPU models. For more information, see the C-SKY Product ID Definition Regulations (v4.0). The reset value is subject to the product.

### 16.1.9.2 On-chip bus base address register (mapbaddr)

The mapbaddr register stores the base addresses of on-chip registers (CLINT and PLIC) of the CPU. The value of this register is subject to hardware integration.

## 16.1.10 Multi-core extension registers

### 16.1.10.1 Snoop listening enable register (msmpr)

The msmpr register controls whether cores can process listening requests. The listening request processing capability is configured for each core separately. The consistency bus of the L2 subsystem controls the sending of listening requests based on the listening status of each core. This register is readable and writable in M-mode.

The msmpr register is 64 bits wide. Only bit 0 is defined and the other bits are reserved.

### Bit 0: SMPEN: core listening enable bit

- When SMPEN is 1' b0, the corresponding core cannot process listening requests, and the L2 subsystem masks the listening requests bound for the core. (This is the reset value.)
- When SMPEN is 1' b1, the corresponding core can process listening requests, and the L2 subsystem sends the listening requests bound for the core.

Before a CPU core is powered off, its SMPEN bit must be set to 0 to disable listening. After a core is powered on, its SMPEN bit must be set to 1 before D-Cache and MMU are enabled. The SMPEN bit must be set to 1 when a core runs properly (including WFI mode). Otherwise, unexpected results may be caused.

# 16.2 Appendix C-2 S-mode control registers

S-mode control registers are classified by function into S-mode exception configuration registers, S-mode exception handling registers, and S-mode address translation registers.

## 16.2.1 S-mode exception configuration registers

When exceptions and interrupts are downgraded to S-mode responses, exceptions must be configured through the S-mode exception configuration registers, like in M-mode.

## 16.2.1.1 S-mode status register (sstatus)

The status register stores status and control information of the CPU in S-mode, including the global interrupt enable bit, exception preserve interrupt enable bit, and exception preserve privilege mode bit. The status register is a partial mapping of the mstatus register.

This register is 64 bits wide and is readable and writable in S-mode. Accesses in U-mode will cause an illegal instruction exception.



S-mode status register (sstatus)

For more information, see ref:*appendix\_c12\_mstatus*.



### 16.2.1.2 S-mode interrupt-enable register (sie)

The sie register controls the enable and mask of different types of interrupts, and is a partial mapping of the mie register. This register is 64 bits wide and readable in S-mode. The write permission in S-mode is determined by the mideleg register of the corresponding bit. Accesses in U-mode will cause an illegal instruction exception.



S-mode interrupt-enable register (sie)

For more information, see ref: appendix\_c12\_mie.

### 16.2.1.3 S-mode trap vector base address register (stvec)

The style register stores the entry address of the exception service program.

This register is 64 bits wide and is readable and writable in S-mode. Accesses in U-mode will cause an illegal instruction exception.



S-mode trap vector base address register (stvec)

For more information, see ref:*appendix\_c12\_mtvec*.

### 16.2.1.4 S-mode counter access enable register (scounteren)

The scounteren register determines whether U-mode counters can be accessed in U-mode.

For more information, see ref: performance\_test\_scounteren.



## 16.2.2 S-mode exception handling registers

### 16.2.2.1 S-mode scratch register (sscratch)

The sscratch register is used by the CPU to back up temporary data in the exception service program. It is usually used to store the entry pointer to the local context space in S-mode.

This register is 64 bits wide and is readable and writable in S-mode. Accesses in U-mode will cause an illegal instruction exception.

### 16.2.2.2 S-mode exception program counter register (sepc)

The sepc register stores the program counter value (PC value) when the CPU exits from the exception service program. C910 supports 16 bits wide instructions. The values of sepc are aligned with 16 bits and the lowest bit is 0.

This register is 64 bits wide and is readable and writable in S-mode. Accesses in U-mode will cause an illegal instruction exception.

### 16.2.2.3 S-mode cause register (scause)

The scause register stores the vector numbers of events that trigger exceptions. The vector numbers are used to handle corresponding events in the exception service program.

This register is 64 bits wide and is readable and writable in S-mode. Accesses in U-mode will cause an illegal instruction exception.

### 16.2.2.4 S-mode interrupt-pending register (sip)

The sip register stores information about pending interrupts. When the CPU cannot immediately respond to an interrupt, the corresponding bit in the sip register will be set.

This register is 64 bits wide and readable in S-mode. The write permission is determined by the mideleg register of the corresponding bit. Accesses in U-mode will cause an illegal instruction exception.





S-mode interrupt-pending register (sip)

### 16.2.3 S-mode address translation registers

Virtual memory spaces need to be accessed in S-mode. The S-mode address translation register (satp) controls MMU mode switching, hardware writeback base address, and process ID.

#### 16.2.3.1 S-mode address translation register (satp)

The S-mode address translation register (satp) controls MMU mode switching, hardware writeback base address, and process ID.

This register is 64 bits wide and is readable and writable in S-mode. Accesses in U-mode will cause an illegal instruction exception.

For more information, see ref: virtual\_mem\_manage\_satp.

### 16.2.4 S-mode CPU control and status extension registers

#### 16.2.4.1 S-mode extension status register (sxstatus)

The sxstatus register is the mapping of the mxstatus register. For more information, see  $ref:appendix\_c17\_mxstatus$ .

This register is 64 bits wide and is readable in S-mode. Only the MM bit is writable. Accesses in U-mode will cause an illegal instruction exception.

#### 16.2.4.2 S-mode hardware control register (shcr)

The shcr register is the mapping of the mhcr register. For more information, see ref:appendix\_c17\_mhcr.

This register is 64 bits wide and is readable in S-mode. Accesses in U-mode will cause an illegal instruction exception.

#### 16.2.4.3 S-mode event overflow interrupt enable register (scounterinten)

The scounterinten register is the mapping of the mcounterinten register. For more information, see  $ref:appendix\_c17\_mcounterinten$ .

This register is 64 bits wide and is readable in S-mode. Accesses in U-mode will cause an illegal instruction exception.

When mcounterwen.bit[n] is 1, scounterinten.bit[n] determines whether to generate an interrupt when the corresponding shpmcounter overflows.



#### 16.2.4.4 S-mode event overflow mark register (scounterof)

The scounter register is the mapping of the mcounter of register. For more information, see  $ref:appendix\_c17\_mcounterof$ .

This register is 64 bits wide and is readable in S-mode. Accesses in U-mode will cause an illegal instruction exception.

When mcounterwen.bit[n] is 1, scounterof.bit[n] indicates whether the corresponding shpmcounter overflows.

#### 16.2.4.5 S-mode cycle counter (scycle)

The scycle counter stores the cycles executed by the CPU. When the CPU is in the execution state (non-low power state), the scycle register increases the count upon each execution cycle.

The mcycle counter is 64 bits wide and will be reset to 0.

For more information, see ref: performance\_test\_cont.

#### 16.2.4.6 S-mode instructions-retired counter (sinstret)

The sinstret counter stores the number of retired instructions of the CPU. The sinstret register increases the count when each instruction retires.

The sinstret counter is 64 bits wide and will be reset to 0.

For more information, see ref: performance\_test\_cont.

#### 16.2.4.7 S-mode event counter (shpmcountern)

The shpmcountern counter is the mapping of the mhpmcountern counter.

For more information, see ref: performance\_test\_cont.

### 16.2.5 S-mode MMU extension register

C910 extends MMU related registers to implement software writeback. Software can directly write and read the TLB.

#### 16.2.5.1 S-mode MMU control register (smcir)

This register is 64 bits wide and is readable in S-mode. Accesses in U-mode will cause an illegal instruction exception.

For more information, see ref: virtual\_mem\_manage\_smcir.



#### 16.2.5.2 S-mode MMU control register (smir)

This register is 64 bits wide and is readable in S-mode. Accesses in U-mode will cause an illegal instruction exception.

For more information, see ref: virtual\_mem\_manage\_smir.

#### 16.2.5.3 S-mode MMU control register (smeh)

This register is 64 bits wide and is readable in S-mode. Accesses in U-mode will cause an illegal instruction exception.

For more information, see ref:virtual\_mem\_manage\_smeh.

#### 16.2.5.4 S-mode MMU control register (smel)

This register is 64 bits wide and is readable in S-mode. Accesses in U-mode will cause an illegal instruction exception.

For more information, see ref: virtual\_mem\_manage\_smel.

## **16.3 Appendix C-3 U-mode control registers**

U-mode control registers are classified by function into floating-point registers, counter registers, and vector control registers.

### 16.3.1 U-mode floating-point control registers

#### 16.3.1.1 Floating-point accrued exceptions register (fflags)

The fflags register is the mapping of accrued exceptions of the fcsr register. For more information, see  $ref:appendix\_c31\_fcsr$ .

#### 16.3.1.2 Floating-point dynamic rounding mode register (frm)

The frm register is the mapping of the rounding mode of the fcsr register. For more information, see  $ref:appendix\_c31\_fcsr$ .

#### 16.3.1.3 Floating-point control and status register (fcsr)

The fcsr register records floating-point accrued exceptions and the rounding mode.

This register is 64 bits wide and readable and writable in any mode.





Floating-point control and status register (fcsr)

#### NX: imprecise exception

• When NX is 0, no imprecise exception occurs.

When NX is 1, imprecise exceptions occur.

### UF: underflow exception

- When UF is 0, no underflow exception occurs.
- When UF is 1, underflow exceptions occur.

#### **OF:** overflow exception

- When OF is 0, no overflow exception occurs.
- When OF is 1, overflow exceptions occur.

#### DZ: division by zero exception

- When DZ is 0, no division by zero exception occurs.
- When DZ is 1, division by zero exceptions occur.

### NV: illegal instruction operand exception

- When NV is 0, no exception of illegal instruction operands occurs.
- When NV is 1, exceptions of illegal instruction operands occur.

### RM: rounding mode

- When RM is 0, the RNE rounding mode takes effect, and values are rounded off to the nearest even number.
- When RM is 1, the RTZ rounding mode takes effect, and values are rounded off to zero.
- When RM is 2, the RDN rounding mode takes effect, and values are rounded off to negative infinity.
- When RM is 3, the RUP rounding mode takes effect, and values are rounded off to positive infinity.
- When RM is 4, the RMM rounding mode takes effect, and values are rounded off to the nearest number.



### VXSAT: vector overflow flag bit

This register is the mapping of the corresponding bit.

### VXRM: vector rounding mode bit

This register is the mapping of the corresponding bit.

## 16.3.2 U-mode counter/timer registers

### 16.3.2.1 User cycle register (cycle)

The cycle register stores the cycles executed by the CPU. When the CPU is in the execution state (non-low power state), the cycle register increases the count upon each execution cycle.

The mcycle counter is 64 bits wide and will be reset to 0.

For more information, see ref: performance\_test\_cont.

### **16.3.2.2** U-mode timer register (time)

The time register is the read-only mapping of the mtime register.

For more information, see ref: performance\_test\_cont.

### 16.3.2.3 User instructions-retired counter (instret)

The instructions of the CPU. The instructions of the CPU. The instructions es the count when each instruction retires.

The sinstret counter is 64 bits wide and will be reset to 0.

For more information, see ref: performance\_test\_cont.

### 16.3.2.4 User event counter (hpmcountern)

The hpmcountern counter is the mapping of the mhpmcountern counter.

For more information, see ref: performance\_test\_cont.

## 16.3.3 U-mode floating-point extension control registers

### 16.3.3.1 U-mode floating-point extension control register (fxcr)

The fxcr register controls the floating-point extension function and floating-point exception accrue bit.





Floating-point extension control register (fxcr)

### NX: imprecise exception

It is the mapping of the corresponding bit of the fcsr register.

### **UF:** underflow exception

It is the mapping of the corresponding bit of the fcsr register.

### **OF:** overflow exception

It is the mapping of the corresponding bit of the fcsr register.

### DZ: division by zero exception

It is the mapping of the corresponding bit of the fcsr register.

### NV: illegal instruction operand exception

It is the mapping of the corresponding bit of the fcsr register.

### FE: floating-point exception accrue bit

This bit is set to 1 when any floating-point exception occurs.

### DQNaN: output QNaN mode bit

When DQNaN is 0, the output QNaN value is the default value.

When DQNaN is 1, the output QNaN value is consistent with the IEEE754 standard.

### RM: rounding mode

It is the mapping of the corresponding bit of the fcsr register.